

Contractor Report Number: CR180817

**ONBOARD PROCESSING
SATELLITE NETWORK ARCHITECTURE
AND
CONTROL STUDY
FINAL REPORT**

NASA CONTRACT NAS3-24886

JUNE 1987

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ABSTRACT
FINAL REPORT

ONBOARD PROCESSING SATELLITE NETWORK
ARCHITECTURE AND CONTROL STUDY
CONTRACT NAS3-24886

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For satellites to remain a vital part of future national and international communications, new system concepts that use their inherent advantages to the fullest must be created. This study is devoted to exploring new network architectures that take maximum advantage of satellites equipped with onboard processing.

New satellite generations must accommodate various services for which satellites constitute the preferred vehicle of delivery. Such services tend to be those that are widely dispersed and present thin to medium loads to the system. Typical services considered are thin and medium route telephony, maritime, land and aeronautical radio, VSAT data, low bit rate video teleconferencing and high bit rate broadcast of high definition video. The study considers delivery of services by TDMA and FDMA multiplexing techniques and combinations of the two for individual and mixed service types. Onboard processing is an essential part of the system architecture as it applies to the switching to rearrange the uplink signals into the downlink signals and serving hopping pencil beams. The possibilities offered by onboard circuit switched and packet switched architectures are examined and the results strongly support a preference for the latter. The memory used in the switch is designed to minimize its size by using advantageously the storage of signals in the space immediately in front of the antenna. A detailed design architecture encompassing the onboard packet switch and its control, the related demand assigned TDMA burst structures, and destination packet protocols for routing traffic are presented. Important features such as distributed network control, acquisition and synchronization, demand assignment, and advantageous use of voice and data activity to achieve channel multiplication are considered. Fundamental onboard hardware requirements comprising speed, memory size, chip count, and power are estimated. The study concludes with identification of key enabling technologies and identifies a plan to develop a POC model.

**ONBOARD PROCESSING NETWORK
ARCHITECTURE AND CONTROL STUDY
FINAL REPORT**

TABLE OF CONTENTS

1.	Introduction	1.1
1.1	Networks and Services	1.1
1.1.1	Spot Beam Considerations	1.1
1.1.2	Demand Assigned, Multiple Access Networks	1.2
1.1.3	Intersatellite Links	1.3
1.1.4	Summary Of Objectives	1.3
1.2	Summary of Contract Tasks	1.3
1.2.1	Task 1 - Network Architecture	1.3
1.2.2	Task 2 - Network Control	1.5
1.2.3	Task 3 - Technology Challenges	1.6
2.	Network Architectures	2.1
2.1	Services Carried	2.1
2.1.1	Identification Of Services	2.1
2.1.2	Categories Of Services	2.2
2.2	Future Communications Satellite Payloads	2.4
2.2.1	International Services And Extrapolations	2.5
2.2.2	Domestic Services And Extrapolations	2.6

2.3	Network Options	2.7
2.3.1	Simple Global Beam Networks	2.7
2.3.2	Regional Beam Networks	2.8
2.3.3	Spot Beam Networks	2.9
2.3.3.1	Spot Beam Advantages	2.9
2.3.3.2	Spot Beam Connectivity	2.9
2.3.3.3	Hopping Spot Beams	2.10
2.3.4	Onboard Switching And Storage	2.10
2.3.4.1	Operating Without Onboard Storage	2.10
2.3.4.2	Operating With Onboard Storage	2.11
2.3.4.3	Comparing Operation Without And With Onboard Storage	2.11
2.3.4.4	Examples Of Operating Without And With Onboard Storage	2.12
2.3.5	Intersatellite Links	2.15
2.4	Transmission Configurations	2.16
2.4.1	FDMA	2.16
2.4.2	TDMA	2.16
2.4.3	MF/TDMA	2.17
2.4.4	CDMA	2.18
2.4.5	Transmission Configurations	2.19
2.4.5.1	FDMA-FDMA Operation	2.19

NAS3-24886 FINAL REPORT

2.4.5.2	FDMA-TDM/TDMA Operation	2.22
2.4.5.3	TDMA-TDMA Operation	2.23
2.4.5.4	TDMA-TDM/TDMA Operation	2.24
2.4.5.5	MF/TDMA-TDM/TDMA Operation	2.24
2.4.5.6	MF/TDMA-MF/TDMA Operation	2.25
2.5	Computer And Data Communications	2.26
2.5.1	Packet Communications On ACTS	2.26
2.5.1.1	Circuit Switched Operation	2.26
2.5.1.2	Stationary Preassigned Channel Operation	2.27
2.5.1.3	Future Onboard Packet Node	2.28
2.5.2	Configurations For Computer And Data Communications	2.29
2.5.2.1	Circuit Switched Operation	2.29
2.5.2.2	Random Access With Preassigned Circuits	2.31
2.5.2.3	Onboard Packet Node Data Transmission	2.32
2.5.2.4	Comparison Of The Data Communications Techniques	2.33
2.6	Advanced Satellite Telecommunications Options	2.38
2.6.1	Advanced Network Control	2.38
2.6.1.1	Call Processing On Board The Satellite	2.38
2.6.1.2	Destination Directed Onboard Switching	2.39
2.6.2	Memory In Space	2.40

2.6.3	Integrating In Other Services	2.41
2.6.3.1	Capability To Accommodate Different Services	2.41
2.6.3.2	Synchronization Among Different Services	2.41
2.6.3.3	Source Coding Considerations	2.42
3.	Destination Directed Packet Onboard Processing Architecture	3.1
3.1	System Design	3.1
3.1.1	Demand Assignment of Capacity	3.1
3.1.1.1	Destination Addresses Packet Message	3.2
3.1.2	Method of Operation	3.3
3.1.2.1	Call Set-Up Procedure	3.3
3.1.2.2	Call In Progress Procedure	3.4
3.1.2.3	Call Termination	3.5
3.1.2.4	Mapping Functions	3.5
3.1.2.5	Detailed Call Set-Up Procedure	3.6
3.1.2.6	Detailed Call In Progress Procedure	3.6
3.1.2.7	Detailed Call Termination Procedure	3.9
3.1.3	Packet Frame Efficiency	3.9
3.1.4	Digital Speech Interpolation	3.10
3.1.5	Acquisition and Synchronization Control	3.10
3.1.5.1	Reference Bursts	3.11
3.1.5.2	Uplink Request Bursts	3.12

3.1.5.3	Acquisition and Synchronization Procedure	3.12
3.1.6	Overall Frame Efficiency	3.13
3.1.7	Onboard Switch Architectures	3.15
3.1.7.1	Separate Input/Output Memory Architecture	3.15
3.1.7.2	Unified Memory Architecture	3.16
3.2	Baseband Processing Implementation	3.19
3.2.1	Separate Input/Output Memory Architecture	3.19
3.2.1.1	Separate Input/Output Memory Hardware Implementation	3.21
3.2.1.1.1	System Memory Requirements	3.22
3.2.1.1.1.1	Input/Output Memory Requirements	3.23
3.2.1.1.1.2	Control Memory Requirements	3.24
3.2.1.1.1.3	Switch State Memory Requirements	3.25
3.2.1.1.1.4	Packet Header Memory and Control	3.26
3.2.1.1.2	Separate Memory System Block Diagram	3.27
3.2.1.1.2.1	Input Subsystem Block Diagram	3.28
3.2.1.1.2.2	Output Subsystem Block Diagram	3.29
3.2.1.2	Conclusions - Separate Memory Architecture	3.31
3.2.2	Unified Memory Architecture	3.32
3.2.2.1	Unified Memory Hardware Implementation	3.35
3.2.2.1.1	System Memory Requirements	3.35

3.2.2.1.1.1	Unified Data Memory Requirements	3.36
3.2.2.1.1.2	Unified Header Memory Requirements	3.36
3.2.2.1.2	Unified Memory System Block Diagram	3.37
3.2.2.1.3	Unified Memory Control Subsystem Block Diagram	3.39
3.2.2.2	Conclusions - Unified Memory Architecture	3.39
3.2.3	Alternative Unified Memory Architecture	3.40
3.2.3.1	Alternative Unified Memory Hardware Implementation	3.41
3.2.3.1.1	System Memory Requirements	3.43
3.2.3.1.2	Alternative Unified Memory Hardware Block Diagram	3.44
3.2.3.1.2.1	Alternative Unified Memory Serial Input Mux Block Diagram	3.45
3.2.3.1.2.2	Alternative Unified Memory Serial Output Mux Block Diagram	3.45
3.2.3.2	Conclusions - Alternative Unified Memory	3.48
4.	Integration Of Other Services	4.1
4.1	Mobile Satellite Service	4.1
4.1.1	Integrated Fixed Satellite and Land Mobile Satellite Services	4.1
4.1.2	System Characteristics	4.2
4.2	Call Set-Up Procedures	4.3
4.2.1	Calls Originating at MT to BS or Gateway	4.3

NAS3-24886 FINAL REPORT

4.2.2	Calls Originating at BS or Gateway to MT	4.4
4.2.3	Calls Originating at a MT Destined to a MT	4.4
4.3	Impact on the OnBoard Packet Processor	4.5
4.3.1	Integration Of FSS and MSS	4.5
4.3.2	MSS Implementation	4.5
4.3.3	Difference In Traffic Bit Rates Of MSS/FSS Links	4.6
4.4	Intersatellite Link Operation	4.7
5.	Technology Forecast For Static Ram and Custom Development	5.1
5.1	Technology Forecast For Static Rams	5.2
5.2	Technology Forecast For Custom and Semi-Custom Logic Arrays	5.4
6.0	Technology Development Requirements	6.1
6.1	Key Device Development	6.1
6.1.1	Custom Logic Devices	6.2
6.1.2	Memory Development	6.2
6.2	Destination Directed Packet Onboard Processing Architecture Development	6.2
6.3	Destination Directed Packet Network Control Test Bed	6.3
6.3.1	Critical Features To Be Investigated	6.3
6.3.2	Proposed POC Test Bed Breadboard	6.3
7.	References	7.1

NAS3-24886 FINAL REPORT

Appendices

A.1	Onboard Baseband Switch Call Processing	A1.1
A.2	Number of Possible Switch States for MxN Switch	A2.1

LIST OF FIGURES

Figure 1.1	Multi-Service Switching and Routing Satellite Gateway	1.7
Figure 1.2	Extended World Coverage With Inter- Satellite Link	1.8
Figure 2.1	Intelsat V Beam Connections	2.44
Figure 2.2	Intelsat VI Beam Connections	2.45
Figure 2.3	Intelsat VI Beam Connections Using 6X6 MS	2.46
Figure 2.4	6X6 MSM Switch State Time Plan	2.47
Figure 2.5	Spot Beam Antenna Coverage of Atlantic Ocean Basin Countries	2.48
Figure 2.6	Preassigned Routes for Random Access TDMA	2.49
Figure 2.7	Single Down Beam Dwell	2.50
Figure 2.8	Preassigned Routes in Superframe For Random Access	2.51
Figure 2.9	Circuit Switching Data Transmission	2.52
Figure 2.10	Random Access Data Transmission with Preassigned Channels	2.54
Figure 2.11	On-Board Packet Node Data Transmission	2.55
Figure 3.1	TDMA/DAMA System with Onboard Processor	3.50
Figure 3.2	Uplink Capacity Reallocation	3.51

Figure 3.3	Onboard Satellite Channel Mapping	3.52
Figure 3.4	Terrestrial Port to Time Slot Mapping and Up-Link to Down-Link Satellite Channel Mapping For Destination Directed Message Switching	3.53
Figure 3.5	Destination Directed Packet System Mapping	3.54
Figure 3.6	Packet Header Structure	3.55
Figure 3.7	Traffic Bursts for Packet Routing	3.56
Figure 3.8	Traffic Bursts for Sub-burst Routing	3.57
Figure 3.9	Packet Header Efficiency for Individual Packet Routing	3.58
Figure 3.10	Packet Header Efficiency for Sub-Burst Packet Routing	3.59
Figure 3.11	Frame Format	3.60
Figure 3.12	Superframe Structure	3.61
Figure 3.13	Reference Burst Format	3.62
Figure 3.14	Request Burst (RQB) Structure	3.63
Figure 3.15	Relationship Between Beam Dwell and Sub-Burst	3.64
Figure 3.16	Separate Input/Output Memory Architecture	3.65
Figure 3.17	Unified Pingpong Memory Architecture	3.66
Figure 3.18	Unified Dual Port Memory Architecture	3.67
Figure 3.19	Onboard Dual Port Switch Operation	3.68

Figure 3.20	Signal Flow for Separate Memory Architecture Destination-Directed Switching Between Beams	3.69
Figure 3.21	Control Memory Maps and Pointers for Separate Memory Architecture of Figure 3.20	3.70
Figure 3.22	Separate Memory Architecture Hardware Block Diagram	3.71
Figure 3.23	Detailed Hardware Block Diagram of Input Section	3.72
Figure 3.24	Detailed Hardware Block Diagram of Output Section	3.73
Figure 3.25	Signal Flow for Unified Memory Architecture Destination-Directed Switching Between Beams	3.74
Figure 3.26	Scrambling Problem with 64-bit Bus	3.75
Figure 3.27	Diagram of Pointer Array to Solve Scrambling Problem	3.76
Figure 3.28	Unified Memory Architecture Hardware Block Diagram	3.77
Figure 3.29	Detailed Hardware Block Diagram of Control Section Unified Memory Architecture	3.78
Figure 3.30	Alternative Signal Flow for Unified Memory Architecture	3.79
Figure 3.31	Alternative Unified Memory Hardware Block Diagram	3.80
Figure 3.32	Block Diagram of Serial Input Mux	3.81

NAS3-24886 FINAL REPORT

Figure 3.33	Block Diagram of Serial Output Demux	3.82
Figure 4.1	Network Elements of An Integrated FSS and MSS Satellite System	4.9
Figure 4.2	MSS Frequency Plans	4.10
Figure 4.3	Onboard Packet Processor For Integrated FS & MS Services	4.11
Figure 4.4	MSS Processor	4.12
Figure 5.1	Speed-Power Products of Various Digital IC Technologies {Source: N. Mokhoff, <u>Computer Design</u> , p 77, Oct. 15, 1985}	5.8
Figure 5.2	Forecast of Commercial GAAS Digital Logic IC Gate Complexity vs. Commercial Silicon IC's	5.9
Figure 5.3	GaAs Device Technology	5.10
Figure 6.1	Destination Directed Packet Switching Test Bed Block Diagram	6.6
Figure 6.2	Test Bed Program Plan	6.7

LIST OF TABLES

Table 1.1	Objectives	1.4
Table 2.1	Satellite Services and Attributes	2.3
Table 2.2	Comparison of Beam Hopping Parameters with and without Onboard Memory	2.12
Table 2.3	Example 1 of the Comparison of Beam Hopping Parameters with and without Onboard Memory	2.13
Table 2.4	Example 2 of the Comparison of Beam Hopping Parameters with and without Onboard Memory	2.14
Table 2.5	Example of the Comparison of Beam Hopping Parameters With and Without Onboard Memory	2.15
Table 2.6	Uplink and Downlink Transmission Configurations	2.21
Table 2.7	Comparison of three Onboard Switch Implementations	2.36
Table 3.1	System Operation for Destination Addressed Message Packet System	3.3(A) 3.3(B)
Table 3.2	Call Set-Up Procedure	3.7
Table 3.3	Memory Requirements for Separate Architecture, Total for 10 120 MBPS Beams	3.27
Table 3.4	Subsystem Device Count and Power Dissipation	3.30

Table 3.5	Memory Requirements for Unified Memory Architecture, Total for 10 120 MBPS Beams	3.36
Table 3.6	Subsystem Device Count and Power Dissipation - Unified Memory Architecture	3.38
Table 3.7	Memory Requirements for Alternative Unified Memory Architecture, Total for 10 120 MBPS Beams	3.43
Table 3.8	Subsystem Device Count and Power Dissipation - Alternative Unified Memory Architecture (Based on 1987 Technology)	3.47
Table 5.1	Subsystem Device Count and Power Dissipation - Alternative Unified Memory Architecture (Based on 1990-1992 Technology	5.1 5.2
Table 5.2	SRAM Technology Rankings According To McDonnell Douglas Study	5.3(A)
Table 5.3	Summary of Future Custom Chip Requirements For Alternative Unified Memory Architecture	5.5

ONBOARD PROCESSING SATELLITE NETWORK
ARCHITECTURE AND CONTROL STUDY
FINAL REPORT

1. INTRODUCTION

Satellites, as a consequence of the natural forces of the market place over more than two decades of application, have been applied to a variety of services incorporating a variety of transmission means. Figure 1.1 illustrates the generic services delivered by satellite systems. These include fixed satellite services (FSS), maritime mobile services (MMSS), land mobile services (LMSS), aeronautical mobile satellite services (AMSS) and intersatellite link (ISL). By far the greatest use lies in the FSS area which supports domestic and international multiple trunk, SCPC and DAMA SCPC telephone and data. Also FSS supports the broadcast distribution of television for the major TV networks and for cable TV. The mobile satellite services currently constitute a small fraction of the total and this resides principally in the MMSS; however because of the changing complexion of the satellite communication industry which will accentuate the prime advantages of satellites (which are multiple access and demand assignment of the space segment) and the expansion of AMSS and LMSS the mobile fraction is expected to grow significantly. The ISL has been used in the TDRSS and some military satellites but has not yet been used in a commercial application. This is expected to change as regional gateway switching satellites appear and interconnection of these gateways to exchange traffic between regions occurs. Any new generation of satellites should be capable of accommodating these services. It is important to bear in mind that the competition from terrestrial transmission media, in particular high capacity, low cost lightguides operating at digital transmission rates per individual fiber potentially approaching a Gigabit per second, are forcing satellite systems to adopt technologies that lead to significantly reduced cost. Such cost reduction must consider the balance of cost between the space segment and the earth segment.

1.1 NETWORKS AND SERVICES

1.1.1 SPOT BEAM CONSIDERATIONS

The most economical satellite system results when the space segment is enhanced to provide high e.i.r.p. and gain to noise temperature (G/T) ratios and the earth segment uses this space segment to advantage by using small, low power stations to deliver the service. This leads to a

NAS3-24886 FINAL REPORT

space segment that has large aperture antennas and consequently narrow spot beams. However, the narrow spot beams reduce the coverage area of any one beam requiring either that many such spot beams be used simultaneously or that a few beams hop to various regions and dwell in each long enough to accommodate the traffic. The spot beams can be fixed if the region they cover carries sufficient traffic to fill the beam. This is suitable for regions that encompass areas of high population density. However, in regions where the density is sparse the beam must hop about to accumulate sufficient traffic to fill it. In the study reported here, this type of system receives the principal attention. The system studied also interconnects with a larger beam.

The services carried over satellites have evolved as a consequence of a selection process that uses the inherent properties to greatest advantage. In this regard, the most attractive property of the satellite is its ability to view almost half the earth's surface from a single vantage point 22300 miles above the equator. Any station in sight of the satellite can communicate to any other station in sight of the same satellite no matter where it is located. Satellites also provide large bandwidth any portion of which, when desired, can be divided into narrow channels. These capabilities have resulted in the world wide distribution of broadcast quality TV and the distribution of demand assigned services for individual telephone and data circuits by both FDMA single channel per carrier techniques and by TDMA techniques for both national (domestic) and international services.

1.1.2 DEMAND ASSIGNED, MULTIPLE ACCESS NETWORKS

Demand assigned multiple access use of satellites which permits space segment capacity to be used when needed and returned for use by another when not needed by any user in view of the satellite constitutes the most powerful communications networking concept known. This property is most valuable for thin route users each of whom uses only a small fraction of an Erlang, but it remains useful for traffic intensities of several Erlangs between destinations. For example, a network of 1000 stations, each serving a traffic intensity averaging 0.2 erlangs can be accommodated with only 250 space segment circuits. The power of demand assignment diminishes on routes bearing traffic intensities greater than 20 Erlangs between destinations. Thus, high intensity routes such as those carrying telephone traffic between the major industrial countries of the North Atlantic Region do not enjoy the DAMA advantage. However on such routes, another advantage, namely that of distributed origins and destinations in which the traffic can be initiated near or at its

NAS3-24886 FINAL REPORT

origin and delivered near or at its destination thus minimizing use of or bypassing all together terrestrial links, is realized. This latter satellite advantage will become very significant in the competitive race between cables and satellites in the international and national arenas provided the cost of satellite earth stations can be very significantly reduced by introduction of a proper space segment that also has reasonable cost .

1.1.3 INTERSATELLITE LINKS.

Intersatellite links provide direct connections between satellites. A question frequently asked is "what use can be made of the intersatellite in commercial satellite applications?" One answer is to bridge between two satellites one located over the North/South America continents and the other over Europe/ Middle East/Africa continents to provide a combination of domestic and international traffic. If these satellites are positioned approximately 57° apart (i.e. 13000 miles apart) in the geostationary orbit as illustrated in Figure 1.2 then individually each can serve domestic and North/South international traffic for the continents beneath it and the intersatellite link can provide East/West international connections. The added one way propagation delay time is 72 ms which will extend the round trip propagation time from the present nominal value of 550 ms to 694 ms. This is a small increase that should not greatly change conversational user subjective reaction. Also the impact on data should be unchanged compared to that experienced on the nominal single hop delay path.

1.1.4 SUMMARY OF OBJECTIVES

The satellite system of the future must fulfill the objectives set forth in Table 1.1 to make the most effective use of its inherent advantages and be competitive in the new market place.

1.2 SUMMARY OF CONTRACT TASKS

The work under the contract is divided into three tasks:

1.2.1 TASK 1 - NETWORK ARCHITECTURE

Segment the market for telecommunications services into user classes having similar transmission requirements and hence similar network architectures.

TABLE 1.1 OBJECTIVES

- A) DEVELOP SATELLITE NETWORKING ARCHITECTURES THAT WILL ACCOMMODATE A VARIETY OF DIFFERENT SERVICES. TYPICAL SERVICES INCLUDE: TRUNK TELEPHONE; THIN ROUTE TELEPHONE; LAND, MARITIME AND AERONAUTICAL MOBILE TELEPHONE; DATA PACKET; AND VIDEO TELECONFERENCING AND BROADCAST VIDEO.
- B) INCORPORATE A VARIETY OF MULTIPLE ACCESS METHODS SELECTED TO BE THE MOST SUITABLE FOR DELIVERY OF EACH TYPE OF SERVICE.
- C) CONSIDER THE SYSTEM AS COMPOSED OF SUBNETWORKS, EACH CHARACTERIZED BY ITS USERS. INTERCONNECTION OF THESE WILL BE ACCOMPLISHED BY A BASEBAND PROCESSOR WHICH CONTAINS A MESSAGE CHANNEL ROUTING SWITCH.
- D) INCLUDE SS/TDMA IN A SWITCHED BENT PIPE MODE THAT IS MOST USEFUL FOR HIGH VOLUME TRUNK TELEPHONE OR DIGITAL TV DISTRIBUTION.
- E) ALL SIGNALS USED IN THE SYSTEM ARE CONSIDERED TO BE DIGITAL AND ARE DEMODULATED AND REMODULATED ON BOARD THE SATELLITE.
- F) DEPENDING ON THEIR PROPERTIES SOME USERS, SUCH AS MOBILE, WILL EMPLOY CONTINUOUS TRANSMISSION TECHNIQUES, WHILE OTHERS SUCH AS TRUNK TELEPHONE OR DATA PACKET WILL EMPLOY BURST TRANSMISSIONS.
- G) THE SATELLITE WILL NECESSARILY EMPLOY A COMBINATION OF CONTINUOUS CARRIERS OPERATING IN FIXED BEAMS AND BURST CARRIERS OPERATING IN FIXED AND HOPPING BEAMS. BOTH FDMA AND TDMA TRANSMISSION TECHNIQUES WILL BE USED.
- H) ALL SERVICES WITHIN EACH SUB NETWORK WILL BE DEMAND ASSIGNED. FURTHERMORE THE INTERCONNECTION OF CALLS BETWEEN THE SUBNETWORKS IS TO ALSO BE DEMAND ASSIGNED.
- I) INTERSATELLITE LINKS WILL INTERCONNECT VARIOUS SATELLITES AND EACH SATELLITE MAY CARRY ONE OR MORE OF THE TYPES OF SERVICES.

A) Consider use of the following transmission architectures:

- Satellite switched TDMA
- TDMA up, TDM down
- Scanning (hopping) beam TDMA
- FDMA up, TDM down
- Satellite Switched MF/TDMA
- Switching Hub earth stations with double hop transmission.

B) Select a candidate network architecture that:

- Comprises multiple access subnetworks optimized for each user.
- Interconnects the subnetworks by means of a baseband processor.
- Optimizes the marriage of interconnection and access techniques.

1.2.2 TASK 2 - NETWORK CONTROL

Provide an overall network control architecture that will serve the needs of the baseband and satellite switched RF interconnected subnetworks. This architecture shall consider the provision of the following network control functions:

- Intelligent Onboard Baseband Processor
- Distributed Network Control
- Acquisition and Synchronization
- Demand Assignment
- Fade Compensation
- Traffic and BBP Scheduling Procedures

- Network Timing and Synchronization
- Onboard Clock Control

1.2.3 TASK 3. - TECHNOLOGY CHALLENGES

The results of the studies shall be used to identify elements of network architecture and control that require the greatest degree of technology development to realize an operational system. This will be specified in terms of :

- Requirements of the Enabling Technology.
- Difference From the Current Available Technology.
- Estimate of the Development Requirements Needed to Achieve An Operational System

The results obtained for each of these tasks are presented sections 2, 3, and 4 of this report.

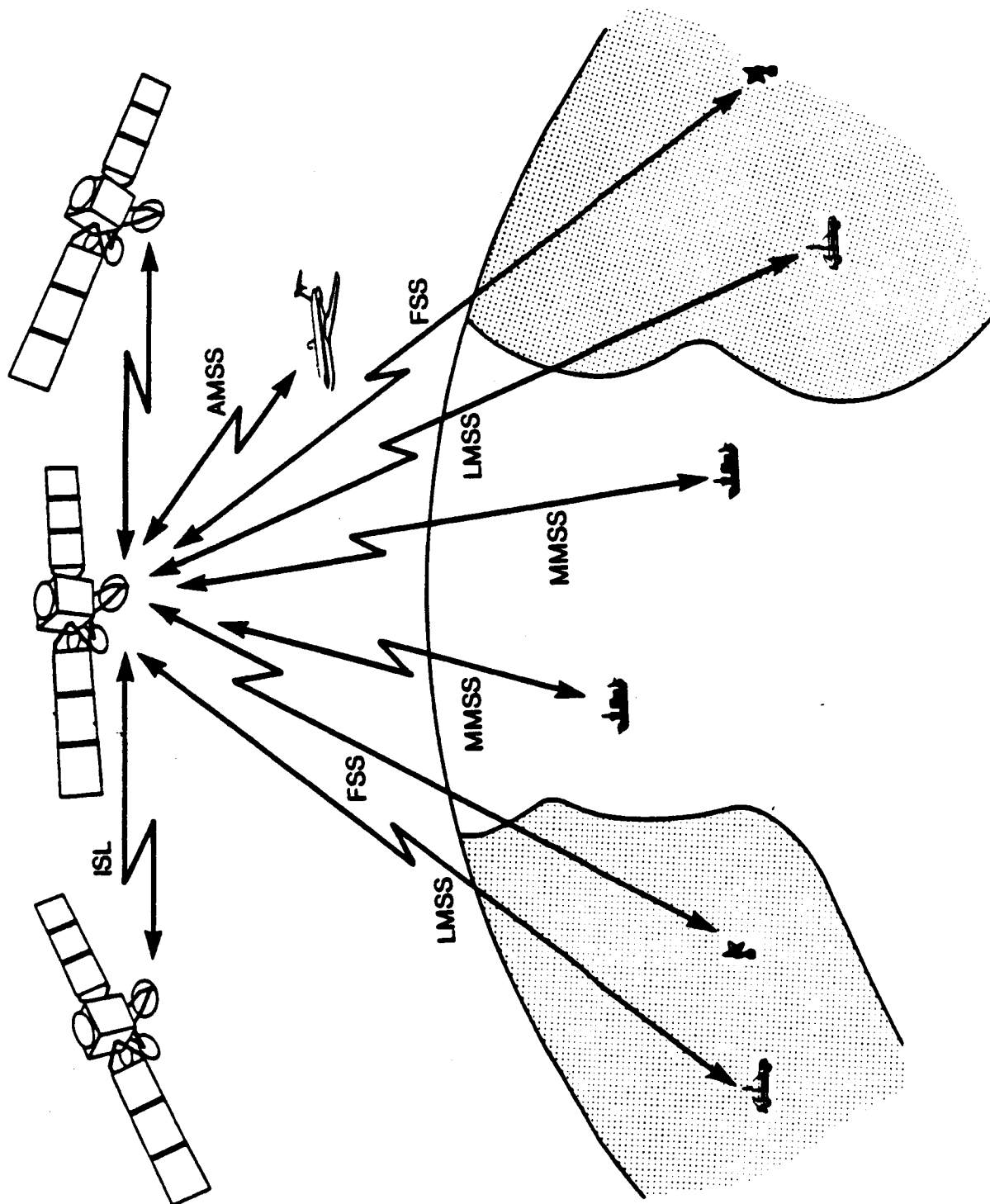


FIGURE 1.1 MULTI-SERVICE SWITCHING AND ROUTING SATELLITE GATEWAY

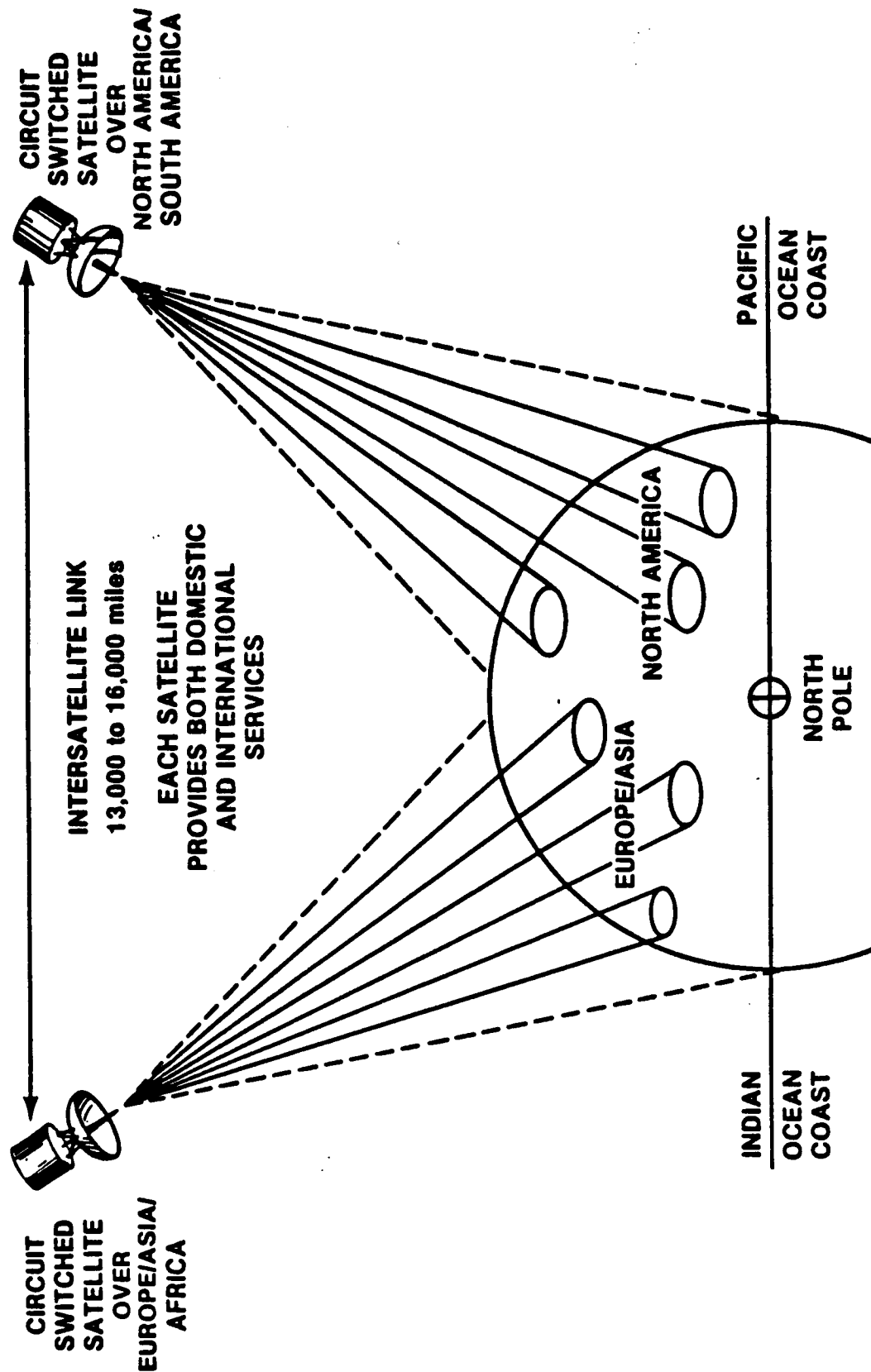


FIGURE 1.2 EXTENDED WORLD COVERAGE WITH INTERSATELLITE LINK

2 NETWORK ARCHITECTURES

2.1 SERVICES CARRIED

2.1.1 IDENTIFICATION OF SERVICES

Various classes of telecommunications services can be expected to be supported by an advanced satellite communications system. These may be integrated into a common network on a single satellite or they may be carried as separate networks over different satellites individually designed to optimize each type of service.

Table 2.1 lists various telecommunications services that are expected to be carried on the satellites of the late 20th and early 21st century. Transmission attributes are identified for each service type in this table. The attributes and their definitions are listed below:

- | | |
|-----------------|--|
| Speed Of Access | - Refers to the speed with which the service must be established following the instant of a request. FAST refers to response in tens of seconds and SLOW in minutes to hours. |
| Traffic Load | - Refers to traffic intensity on the channels provided. LOW refers to fractions of Erlangs, MEDIUM to 1 to 20 Erlangs and HIGH to >20 Erlangs. |
| Channel Rate | - Refers to the bit rate on the channel carrying the service. LOW refers to rates less than 16 kbit/s, MEDIUM to rates between 16 Kbit/s and 20 Mbit/s, HIGH to rates between 20 and 140 Mbit/s and VERY HIGH to rates > 140 Mbit/s. |
| Connectivity | - PP is point-to-point, MP is multipoint-to-point, PM is point-to-multipoint and MM is multipoint-to-multipoint or full mesh. |
| Assignment | - Refers to either PA for preassigned or DA for demand assigned. |
| BER | - Refers to the bit error rate on the transmission that can be tolerated to carry the service. LOW is $<10^{-8}$, MEDIUM is $<10^{-6}$ and HIGH is $<10^{-3}$ |

Error Control - Refers to use of either Forward Error Correction
Method (FEC) or Automatic Repeat Request (ARQ)

2.1.2 CATEGORIES OF SERVICES

The various services can be organized into the following four categories that are based on discipline rather than attributes:

1. MOBILE COMMUNICATIONS

Land
Maritime
Aeronautical
Personal

2. COMPUTER AND DATA COMMUNICATIONS

Packet Data
Bulk File Transfer
Data Collection
Data Broadcast

3. TELECOMMUNICATIONS

Trunk Telephone
ISDN
Business (Customer Premises Station)
Teleconference
Electronic Mail

4. BROADCAST VIDEO

Network Video Distribution
Cable Video Distribution
Educational Video Distribution

The mobile group is characterized by fast access speed, low to medium traffic load per terminal, predominantly low channel transmission rate, mostly multipoint to point and point to multipoint connectivities, medium to high BER and strong dependence on FEC to overcome the vagaries of the transmission links.

TABLE 2.1 SATELLITE SERVICES AND ATTRIBUTES

SERVICE	SPEED OF ACCESS	TRAFFIC LOAD	CHANNEL RATE	CONNECT	ASSIGN	BER	ERROR CONTROL METHOD
LAND MOBILE	FAST	MEDIUM	LOW	MP/PM	DA	HIGH	FEC
MARITIME	FAST	MEDIUM	MEDIUM	MP/PM	DA	MED	FEC
AERONAUTIC.	FAST	LOW	LOW	MP/PM	DA	MED	FEC/ARQ
BUSINESS(CPS)	FAST	HIGH	MED/HIGH	PM/MP/MM	DA/PA	LOW	FEC/ARQ
TELECONF.	SLOW	MEDIUM	MED/HIGH	PM	DA/PA	MED	FEC
PACKET DATA	FAST	HIGH	LOW	PP/MP	DA	MED	FEC/ARQ
BULK DATA	SLOW	MEDIUM	HIGH	PP	PA	LOW	FEC/ARQ
TRUNK TELE.	FAST	HIGH	MEDIUM	MM	DA/PA	LOW	FEC
VIDEO DIST.	SLOW	HIGH	VERY HIGH	PM	PA	LOW	FEC
ELECT. MAIL	SLOW	HIGH	LOW/MED	PP/PM	DA/PA	MED	FEC/ARQ
PERS. COMM.	FAST	HIGH	LOW	MP/PP	DA	HIGH	FEC
DATA BRDCAST	FAST	MEDIUM	LOW/HIGH	PM	PA	MED	FEC
DATA COLLECT	SLOW	LOW	LOW/MED	MP	DA/PA	MED	FEC/ARQ
ISDN	FAST	HIGH	MED/HIGH	MM	DA/PA	LOW	FEC/ARQ

NOTE: ALL TRANSMISSIONS CONSIDERED TO BE DIGITAL.

NAS3-24886 FINAL REPORT

The computer and data group has mixed characteristics. Access speed should be fast for packet and broadcast data but slow for bulk transmission and data collection. Channel transmission rate is high for bulk transmission, medium for broadcast and packet and low for data collection. Connectivity is point to point for bulk data, multipoint to point and point to point for packet data, point to multipoint for broadcast data and multipoint to point for data collection.

The telecommunications group also has mixed characteristics. Access speed is fast for trunk telephone, ISDN and business CPS telephone but slow for video teleconferencing and electronic mail. Traffic load is high for trunk telephone, ISDN, business CPS telephone and electronic mail (assuming concentration of traffic) and medium for teleconferencing. Channel rate is medium to high for all but the electronic mail which ranges from low to medium. Connectivity is full mesh, point to multipoint and point to point. Assignment is preassigned and demand assigned for all members in this group. BER is low for all except electronic mail which may be medium or high when ARQ is used. FEC is used for all of these services to meet the high quality standards that have come to be expected for telecommunications with the possible exception of electronic mail when protected by ARQ.

The broadcast video group comprise services that today are exclusively carried by analog means. However in the future, because of the research being performed in the laboratories on video source coding, it can be expected that digital transmission at rates as low as 20 Mbit/s for broadcast quality video equivalent to today's NTSC/PAL/SECAM quality and 80 Mbit/s for high definition 1050/1125 line broadcast video can be expected. The transmission of these signals over satellite links requires slow access, high traffic loads, high channel rates, point to multipoint preassigned connectivity, low BER and application of FEC.

2.2 FUTURE COMMUNICATION SATELLITE PAYLOADS

Future satellite communications payloads will support all or some subset of the services identified above. A good place to begin is to review some of the types of payloads currently in use or anticipated and project their logical extrapolations. Today's international satellites are designed to support principally the telecommunications and video broadcast groups with the recent addition of the maritime mobile service. It can be expected that the mobile services will include aeronautical in the early 1990s.

2.2.1 International Services and Extrapolations

Telephone services in the INTELSAT V are supported by high capacity FM/FDMA carriers or 120 Mbit/s TDMA carried in bent pipe transponders of 72 MHz occupied bandwidth (spaced on 80 MHz centers) operating with point to multipoint connectivity. The INTELSAT V has four beams at C band, two hemibeams covering the east and west hemispheres of the earth and two zone beams covering the northeast and northwest quadrants such as those containing Europe and North America respectively. The network connectivity configuration is illustrated in Figure 2.1. The beams are interconnected by transponders of 72 MHz bandwidth that can be switched from time to time by means of a static switch to accommodate variations in the traffic load on the various routes. The INTELSAT V also has a global beam at C band equipped with transponders that are used principally for TV transmission. These international satellites also support thin route preassigned and DAMA telephony by use of single channel per carrier (SCPC) in the global and hemibeam transponders.

The INTELSAT VI adds two additional C band zone beams in the southeast and southwest quadrants resulting in six beams. The network connectivity configuration is shown in Figure 2.2. These are interconnected by means of 72 MHz bandwidth transponders that can be switched by a static switch. The INTELSAT VI also has two dynamic microwave switch matrices each interconnecting the six C band beams in a bank of six 72 MHz transponders resulting in an overall capacity of $2 \times 6 \times 120 \text{ Mbit/s} = 1.44 \text{ Gbit/s}$. These operate with the same 120 Mbit/s TDMA terminals that are used for static operation in the INTELSAT V. The TDMA system has been designed for both the static and dynamic switched mode operation without modifications to the earth station TDMA terminal equipments.

Recent research and development work at COMSAT LABS using an advanced modulation technique that merges Octal Phase Shift Keying with FEC and maximum likelihood Viterbi decoding achieves transmission rates of 140 Mbit/s over the 72 MHz bandwidth transponders. These are intended for use in carrying the new international digital exchange rates of 140 Mbit/s for supporting the ISDN. This is probably the highest rate that can be anticipated for satellite use in the foreseeable future and they will appear principally on the international transoceanic paths. The only possible exception is in the case of HDTV which if transmitted in its uncompressed form requires 240 Mbit/s. For the other types of telephone services, lower transmission rates on the uplinks are expected because they allow the use of smaller earth stations.

Both the INTELSAT V and VI are also equipped with fixed spot beams at Ku band pointed at North America and Europe respectively in the Atlantic Ocean Region to serve the international business services (IBS) and intermediate data rate (IDR) services which operate using terminals with antennas of 3.5 to 7.5 m diameter equipped with HPAs of several hundred watts. The IBS services are used by corporations to establish private, open architecture international business communications networks. The IDR services are used by telephone companies and PTTs to carry international PSTN (Public Switched Telephone Network) services. The high EIRP (45 to 48 dBw) and G/T (0 to 3 dB/K) of the Ku band spot beams makes it possible to operate with small low power earth stations. This has created a high demand for use of the INTELSAT Ku band transponders.

2.2.2 Domestic Services and Extrapolations

In the U.S. domestic arena, Ku band satellites with CONUS beams are used extensively for multipoint to point VSAT data services , full mesh DAMA SCPC telephony and point to multipoint preassigned telephony at T1 primary multiplex rates using FDMA and TDMA carriers in transponders having 36 MHz bandwidth (spaced on 40 MHz centers) at C band and 44 MHz bandwidth (spaced on 49 MHz centers) at Ku band. T1 rates (1.544 Mbit/s) are used for telephone and teleconferencing. Small antenna terminal operation at C-band is frequently impeded because of interference with terrestrial and other satellite services making Ku band operation more attractive. Typical U.S.domestic satellites include SATCOM, WESTAR, TELSTAR, GALAXY and COMSTAR at C-band, SBS at Ku-band and SPACENET and TRDS East operating at both C and Ku band.

Much of the medium and high capacity domestic public switched and private business telephone service has been removed from the domestic satellites as a result of the move on the part of a number of the domestic carriers to install long distance terrestrial lightguides. It will be difficult to regain the high capacity traffic that runs between major metropolitan districts; however, the traffic that lies outside these major routes and the bypass traffic between business locations can be retained and made to grow if carried by small, very low cost, customer premises earth stations. For example, VSAT node/hub services and small earth station full mesh SCPC DAMA telephone (such as SKY SWITCH) are expanding.

There is also extensive use of CONUS beams at C band to distribute

NAS3-24886 FINAL REPORT

television for private, religious and commercial broadcast networks in the point to multipoint TVRO and point-to-point and point-to-multipoint broadcast network TV distribution applications. This is also occurring at Ku band. Such TV distribution service occupies the greatest fraction of CONUS satellite usage today.

2.3 NETWORK OPTIONS

2.3.1 SIMPLE GLOBAL BEAM NETWORKS.

Satellite networks had their birth in the full earth coverage beams of the early satellites used in the international services. In such a network all stations in the beam coverage, which includes everything that can see the satellite at an elevation angle of 10° or greater, can easily communicate with each other no matter their location provided the antennas are capable of receiving the signal and developing a good signal to noise ratio. Because these first satellites had very low G/T (-25dB/K) and low e.i.r.p. (11 dBw) the earth stations tended to be large and expensive. None the less, since virtually no other means for establishing long distance communications existed, they proliferated into a world wide international satellite communications network.

Although the global beam configuration is very simple, it fully exploits the multiple access, DAMA attributes that are uniquely the hallmark of satellites. Improvements in performance came by virtue of controlling the beam coverage so that virtually all of the satellite's power was directed to the surface of the earth with little lost to space and by reducing the noise temperature of the receivers. Theoretically, this leads to limiting values of $G \approx 22\text{ dB}$ yielding $G/T \approx -10\text{ dB/K}$ and e.i.r.p. $\approx 28\text{ dBw}$ for a satellite with a 1500 K receiver and 4 watts of power delivered to a global beam antenna in a transponder bandwidth of 36MHz . These values supported links to earth stations with antennas as small as 15m at C band and somewhat smaller if bandwidth was sacrificed; however, the dominant antenna was the gigantic 30m INTELSAT Standard A. Multichannel FDMA, SCPC digital and analog channels and TDMA networks evolved using these transponders and antennas. DAMA made its advent with the digital SCPC which was intended for links to the developing nations. TV distribution also achieved important and highly advertised usage even though it constituted only a small fraction of total usage. Efficient support of smaller terminals was not possible without further increase in both satellite G/T and e.i.r.p. These eventually came about by

the introduction narrower regional beams in later generations of INTELSATS and in domestic satellites of CANADA, the U.S. and EUROPE.

2.3.2 REGIONAL BEAM NETWORKS

Regional beams are those that have a coverage confined to a specific region of the earth smaller than earth coverage. CONUS is a good example of such a regional coverage and numerous privately owned satellite networks are supported over the U.S. carrying all the categories of services identified previously. Typical examples are the COMSTARS that carry analog telephone, TI digital for telephone and teleconferencing and broadcast TV distribution at C Band. The SBS satellites carry the 48 Mbit/s burst rate TDMA which is used for CPS business services for voice data and teleconferencing and is also used for broadcast network TV distribution and TVRO distribution to cable TV heads. Typical antenna diameters used in the SBS network are 5.5m powered by 300 w high power amplifiers. Even though the SBS stations are small compared to INTELSAT standards, they still proved to be too expensive for competitive business services in the U.S. The average installed cost of an SBS earth station is \$750,000.

There are numerous similar satellite systems serving the U.S. and many other regions of the world. New systems are under development, particularly in EUROPE and JAPAN, to introduce direct broadcast TV and high fidelity stereo programs to the home and to serve CPS users. The big advantage enjoyed by the regional satellite systems is the higher satellite antenna gain inherent in the smaller earth coverage. For example, the CONUS beam has an antenna gain of approximately 31 dB which is 9 dB greater than that of the global beam resulting in corresponding reductions in the e.i.r.p. and G/T needed by the earth station. When used to provide either low bit rate SCPC or TDMA services in small-node/large-hub network configurations with bandwidth limited transponder operation, small, low cost earth stations equipped with 1.8m antennas and 2w HPAs can provide random access data services. Accomplishing full mesh connectivity for similar links requires 3.5 m antennas equipped with 25w HPAs.

INTELSAT has introduced regional beams in the INTELSAT V and VI as illustrated previously in Figures 2.1 and 2.2 The hemi beams are essentially half earth coverage resulting in a nominal 3dB increase in beam gain (total ≈ 25 dB) and the zone beams are quarter earth coverage resulting in a nominal 6dB increase in beam gain(total ≈ 28 dB). Also

NAS3-24886 FINAL REPORT

INTELSATs V and VI have Ku band narrow beams that achieve satellite antenna gains of approximately 31 to 34 dB covering EUROPE and NORTH AMERICA. The C band beams have permitted the introduction of the new INTELSAT Std. A earth station antenna, which has a nominal 15m diameter, for wideband telephone services and the Std. F antennas that range in size from 4.5 to 10m for IBS and IDR services. The Ku band beams have permitted the introduction of Std E antennas that range in size from 3.5 to 7.5 m that are also intended for use by the IBS and IDR services.

2.3.3 SPOT BEAM NETWORKS

2.3.3.1 Spot Beam Advantages

The availability of the high eirp and high G/T transponders at K band has stimulated the use of satellite communications in the domestic and international arenas. These have made it possible to operate various satellite services with small, low power earth terminals. The present systems using CONUS type coverage have come to a limit resulting from practical limits on satellite uplink G/T and downlink e.i.r.p. Further improvement requires the use of narrower satellite beams. A spot beam of 200 mile diameter augments the antenna gain by 24 dB compared to a typical CONUS beam. This yields a corresponding increase in the uplink G/T and the downlink e.i.r.p. diminished to a small extent by increased losses due to more complex antenna feed and switching arrangements. Spot beam satellites are a powerful means to reduce the size and power of the earth terminals; however, they reduce the coverage area of the beam and to restore the coverage some form of beam to beam connectivity must be introduced on the satellite.

2.3.3.2 Spot Beam Connectivity

Beam to beam connectivity can be implemented by means of a dynamic microwave switch matrix (MSM) switching in synchronization with TDMA traffic bursts sent at appropriate times in a TDMA frame from earth stations to be routed from their upbeam to a designated downbeam during the epoch of their passage through the satellite. This method is already used in the 120 Mbit/s TDMA system operating on the INTELSAT VI to interconnect its hemi and zone beams as shown in Figure 2.3. An immediately obvious variation is to convert the signals to their digital baseband form by means of a demodulator, perform the upbeam to downbeam routing by a baseband switch and convert the signal once again to the modulated RF signal for the downbeam frequency. Neither of these switch methods, RF matrix or baseband switch matrix, involves storage

onboard the satellite except for short alignment buffers needed in the case of the baseband switch . Rather the storage is done on the ground at the earth stations in the TDMA terminal time compression and expansion buffers used to format the TDMA burst transmission and reception. The principal advantage of conversion to baseband is to achieve signal regeneration and to support the possibility of rate conversion from low and possibly differing uplink rates on multiple FDM carriers to high downlink rates on a single high rate carrier.

2.3.3.3 Hopping Spot Beams

Either of the above methods, dynamic microwave switch matrix (MSM) or baseband switching matrix (BBSM) without further embellishment, can be married to hopping up and down beams. The hopping beam notion derives from the observation that in a multiple beam system (say with beams of 200 mile diameter) there will be several hundred beam coverage areas in a region such as CONUS as shown in Figure 2.4. Even if, due to beam isolation considerations, only one fourth of these beams could be used the amount of transmission capacity they provide would far exceed the capacity that could be processed by a practical spacecraft. It therefore becomes apparent that some means to time division multiplex among the several hundred beams so that for example only ten are active at any given instant is needed. Thus the need for beam hopping is created. Some of the beams which point to regions of intense traffic may not need to hop while others that cover wide expanses of thinly distributed traffic will hop extensively.

2.3.4 ONBOARD SWITCHING AND STORAGE

2.3.4.1 Operating Without Onboard Storage

A multiple hopping beam system can operate in either the MSM or BBSM mode without onboard storage of the traffic. All that needs to be done is to store the bits of each earth station's traffic in a memory and exhaust the contents of the memory as a TDMA burst at the appropriate time to pass through the satellite once each TDMA frame during the connection epoch onboard between the desired upbeam and downbeam. This is nothing more than standard TDMA operation using the method of TDMA synchronization between the earth and space segments as practiced in the INTELSAT SS/TDMA for multiple fixed beam operation or the ACTS system for multiple hopping beam operation. The problem of synchronizing the earth station transmissions to the switching and beam hopping in the

satellite is solved.

2.3.4.2 Operating With Onboard Storage

Since, as explained above, it is possible to accomplish beam hopping operation without onboard storage, then what advantage is offered by adding onboard storage? The principal advantage of onboard storage lies in the fact that a station's traffic can be grouped into a single burst that is transmitted once each TDMA frame. Similarly, a station can receive its traffic in a contiguous group that is time division multiplexed as a burst in the downlink. If a station's traffic is all destined to one downbeam, then there is no real advantage to storing the station's traffic onboard. However if the traffic goes to destinations in different down beams then there is a very significant advantage because without onboard storage the station would have to transmit as many different bursts as there are destination beam dwells. In a hopping beam system with many destination dwell regions to be visited this can constitute a huge burden in terms of the number of uplink and/or downlink beam dwells needed during each TDMA frame. This not only creates a severe and perhaps impossible problem to implement a beam dwell schedule that adapts from frame to frame to accommodate rapidly changing traffic patterns, but it also decreases the system traffic efficiency. This is because the traffic is broken up into many short duration bursts each of which carries a preamble and guardtime overhead. To this must be added the guard times of a large number of beam switchings needed to hop from dwell to dwell.

2.3.4.3 Comparing Operation Without And With Onboard Storage

An estimate of the impact of operating without onboard storage is developed in the following. Assume that a system is operating with one up and one downbeam in an environment with N stations in a system having M beam dwell regions, K beams (each having an up and downbeam) and serving C channels. Thus the average number of channels carried per station is C/N , the number of stations per cell averages N/M and the number of cells served by each beam is M/K . In a full mesh connected network, each of the stations is to communicate to all of the others. Thus there are at most $N(N-1)$ bursts in the system. However, if the number of bursts exceeds the number of channels then full mesh connectivity is not possible in which case there are a maximum of C bursts in the system. Correspondingly, the average number of bursts per station is $N-1$ or C/N . Each of the K beams must on the average hop among

NAS3-24886 FINAL REPORT

M/K dwells which for full mesh connectivity yields a maximum number of $(M/K)^2$ hops per beam except when the number of channels becomes limiting it is C/K hops per beam.

For a system equipped with onboard switching, the parameters involving the bursts in the system, bursts per station and hops per beam are all reduced. Since the onboard switch can disassemble and reassemble the traffic from and to any station, only one burst is needed per station yielding N bursts in the system. For similar reasons the beam needs to visit each dwell region once per frame and hence there are M/K hops per beam.

For convenience, the values of the key parameters described above are tabulated in TABLE 2.2.

TABLE 2.2
COMPARISON OF BEAM HOPPING
PARAMETERS
WITH AND WITHOUT ONBOARD MEMORY

PARAMETER	NO ONBOARD <u>STORAGE</u>	WITH ONBOARD <u>STORAGE</u>
AVE. CHANNELS/STATION	C/N	C/N
NUMBER OF STATIONS/CELL	N/M	N/M
NUMBER OF CELLS/BEAM	M/K	M/K
MAX HOPS/BEAM	LESSOR OF $(M/K)^2$ OR C/K	M/K
MAX BURSTS/SYSTEM	LESSOR OF N(N-1) OR C	N
BURSTS/STATION	LESSOR OF N-1 OR C/N	1

2.3.4.4 Examples Of Operating Without And With Onboard Storage

To illustrate the difference between operation with and without onboard memory, three network examples are now considered.

NAS3-24886 FINAL REPORT

The first is a network of single channel per burst users in which the total number of channels is $C=10,000$, the number of stations served is $N=10,000$, the number of beam dwells is $M=200$ and the number of beams is $K=4$. The results are given in TABLE 2.3. The results reveal that the maximum number of hops/beam is 2,500 without onboard memory and only 50 with the onboard memory.

TABLE 2.3

**EXAMPLE 1 OF THE COMPARISON
OF BEAM HOPPING PARAMETERS
WITH AND WITHOUT ONBOARD MEMORY**

SINGLE CHANNEL PER BURST OPERATION

C = NUMBER OF CHANNELS =10,000
 N = NUMBER OF STATIONS =10,000
 M = NUMBER OF DWELLS =200
 K = NUMBER OF BEAMS =4

PARAMETER	NO ONBOARD <u>STORAGE</u>	WITH ONBOARD <u>STORAGE</u>
AVE. CHANNELS/STATION	1	1
NUMBER OF STATIONS/CELL	50	50
NUMBER OF CELLS/BEAM	50	50
MAX HOPS/BEAM	2,500	50
MAX BURSTS IN SYSTEM	10,000	10,000
MAX BURSTS/STATION	1	1

The second example represents a case having medium traffic intensity per station in which the number of channels is $C=100,000$ the number of stations is $N=500$ while the other parameters are the same as in the first example. The results given in TABLE 2.4 show maximums of 2,500 hops/beam, 100,000 bursts/system and 200 bursts/station without the onboard memory compared to 50, 500 and 1 in corresponding categories with onboard memory.

TABLE 2.4

**EXAMPLE 2 OF THE COMPARISON
OF BEAM HOPPING PARAMETERS
WITH AND WITHOUT ONBOARD MEMORY**

MEDIUM ROUTE INTENSITY

C = NUMBER OF CHANNELS =100,000

N = NUMBER OF STATIONS =500

M = NUMBER OF DWELLS =200

K = NUMBER OF BEAMS =4

PARAMETER	<u>NO ONBOARD STORAGE</u>	<u>WITH ONBOARD STORAGE</u>
AVE. CHANNELS/STATION	200	200
NUMBER OF STATIONS/CELL	2.5	2.5
NUMBER OF CELLS/BYAM	50	50
MAX HOPS/BYAM	2,500	50
MAX BURSTS IN SYSTEM	100,000	500
MAX BURSTS/STATION	200	1

The third example represents a case having thin traffic intensity per station in which the number of channels is C=100,000 the number of stations is N=5,000 while the other parameters are the same as in the first example. The results given in TABLE 2.5 show maximums of 2,500 hops/beam, 100,000 bursts/system and 20 bursts/station without the onboard memory compared to 50, 500 and 1 in corresponding categories with onboard memory.

In all three examples the presence of onboard memory reduces the number of bursts carried in the system and the number of beam hops by orders of magnitude. It is clear that onboard storage has significant value in a beam hopping system.

TABLE 2.5

**EXAMPLE OF THE COMPARISON
OF BEAM HOPPING PARAMETERS
WITH AND WITHOUT ONBOARD MEMORY**

THIN ROUTE INTENSITY

C = NUMBER OF CHANNELS =100,000

N = NUMBER OF STATIONS =5,000

M = NUMBER OF DWELLS =200

K = NUMBER OF BEAMS =4

PARAMETER	<u>NO ONBOARD STORAGE</u>	<u>WITH ONBOARD STORAGE</u>
AVE. CHANNELS/STATION	20	20
NUMBER OF STATIONS/CELL	25	25
NUMBER OF CELLS/BYAM	50	50
MAX HOPS/BYAM	2,500	50
MAX BURSTS IN SYSTEM	100,000	5,000
MAX BURSTS/STATION	20	1

2.3.5 INTERSATELLITE LINKS

In application to commercial communications satellites, a principal use of the intersatellite link may be the interconnection of two or more gateway satellites. This concept has already been described in section 1 of this report. Another use that could evolve would be the interconnection of a cluster of satellites occupying nearly the same location (thus appearing as a single satellite to the earth stations) to interconnect services carried on the different satellites. This might occur if each of

NAS3-24886 FINAL REPORT

the satellites carried a different type of service, such as for example public telephone on one and land, aero mobile on another, etc. The intersatellite link would serve to perform cross connects between services whose transmission modes and implementation architectures are so different that different satellites are the most economical means for implementing them. Implementation of an intersatellite link is discussed further in section 4.

2.4 TRANSMISSION CONFIGURATIONS

In general, two basic transmission methods have dominated satellite communications, Frequency Division Multiplexing abbreviated as FDM and Time Division Multiplexing, abbreviated as TDM. In satellite communications to connote the fact that the uplinks to the satellite can be accessed by any number of earth stations and transmissions transponded from the satellite can be received by any number of stations the abbreviations are modified to FDMA and TDMA which refer to Frequency Division and Time Division Multiple Access respectively. This multiple accessing capability is uniquely the domain of the satellites and must be used to full advantage to compete with the terrestrial transmission options.

2.4.1 FDMA

FDMA customarily designates division of the spectrum of a satellite transponder into a multiplicity of smaller frequency bands each occupied by a carrier. The carriers may have various bandwidths which are individually scaled to accommodate different levels of traffic or they may all be of the same bandwidth as in the case of Single Channel Per Carrier (SCPC) systems used in DAMA networks such as INTELSAT's SPADE, INMARSAT's maritime mobile system, SKY SWITCH and PALAPA. It is likely that the land mobile and aeronautical mobile systems will use this technique.

2.4.2 TDMA

TDMA refers to the division of a high bit rate carrier, occupying the entire bandwidth of a transponder, into time division burst transmissions that emanate from numerous earth stations and are synchronized so that each arrives at the satellite in an epoch assigned uniquely to it. The simplest TDMA system uses a bent pipe transponder in which the uplink transmissions are simply repeated and returned to the earth on the

NAS3-24886 FINAL REPORT

downlink. A multiplicity of transponders can be used in such a system and the up and down beams can be pointed to different regions to provide multiple beam connections such as those previously described for INTELSAT V. Stations can access destinations in different regions by frequency hopping their transmissions to fall in the band of the transponder with its downbeam pointed to the desired destination region.

TDMA is inherently suited for systems that perform onboard dynamic switching. By rule, each station's transmission must arrive and pass through the satellite in a prescribed time epoch. It is a relatively simple matter to coordinate these epochs with the switching of the onboard connections and to have them coincide with the proper switching epoch to be directed to the destination downbeam. As explained previously, this is what happens in the INTELSAT VI when it uses its MSM to operate in the SS-TDMA mode. This also is done for satellites that will perform memoryless onboard switching at baseband such as currently planned on the ITALSAT.

TDMA is also used on the ACTS satellite which incorporates an onboard baseband switch that stores the individual channel signals arriving on the uplinks from multiple uplink hopping beams in input memories and rearranges these into TDM downlink transmissions that contiguously group all of the traffic destined to a dwell region into an epoch that coincides with the time that the downlink hopping beam points to the destination.

2.4.3 MF/TDMA

There is another way to use TDMA that is referred to as MF/TDMA. It simply refers to the transmission of several TDMA carriers in a transponder rather than one. These carriers are used simultaneously by different stations to carrier their burst transmissions. The advantage is a reduction in the amount of transmit power needed by an earth station to access the network. The disadvantage is the reduction of the space segment's capacity because of the transponder output backoff allowance needed to reduce intermodulation distortion to an acceptable level. Typically, between 30 and 50% of the space segment capacity must be given up to achieve the MF/TDMA operation in a bentpipe transponder.

MF/TDMA can also operate in an satellite switched mode (SS-MF/TDMA) in which TDMA traffic bursts operating on multiple low burst rate carriers through the MSM.

MF/TDMA can also be used in baseband switched systems, most likely on the uplinks. For example, the bandwidth normally allocated to the highest bit rate (or symbol rate) TDMA carrier may be assigned to several lower bit rate (or symbol rate) TDMA carriers. This is done in the ACTS where the upbeams can carry either one 110 Msym/s or four 27.5 Msym/s TDMA carriers. In this case, because onboard demodulation and remodulation (regeneration) is used, there is no space segment power backoff penalty.

2.4.4 CDMA

Another transmission method that has been used principally by the military is Code Division Multiplexing which when used on the satellites can be termed as Code Division Multiple Access (CDMA). CDMA uses unique codes to distinguish the transmissions of the individual stations of the network. Each station is assigned a unique orthogonal code that is decoded at its receive side. To call any particular station, a transmitter sends the message coded in the desired receiver's code. Many such transmissions can be sent simultaneously to serve a large number of stations. The system is limited in the number of coded transmissions that can be simultaneously supported by the noise background generated by the cumulative addition of all of the transmissions at the receivers. CDMA systems are thus said to be self noise limiting. CDMA also has an attending property that causes the transmitted signal to be spread over a spectrum that can be orders of magnitude greater than that which would be occupied if the signal were transmitted by ordinary means. This property is due to the fact that each symbol of the message is coded in terms of M symbols of a coding pseudo random bit sequence which causes the spectrum of the coded signal to be multiplied in width by M . The bits of the pseudo random code are frequently referred to as chips. This spreading action dilutes the spectral density of the transmitted signal M^{-1} by and can reduce the signal spectrum level to a level less than the thermal noise background to hide the signal from unwanted listeners. This is called the spread spectrum action. Obviously, this same spread spectrum action can reduce a high power signal's spectral density to a level that is non interfering to other services sharing the same band.

CDMA has not been used to any significant extent in satellite systems mostly because greater transmission capacities can be achieved by FDMA and TDMA using the same facilities. However, there is an application of CDMA that has received considerable attention in the last few years as implemented by the Equatorial Radio Company. In this case the Coded transmission is used principally for its attending property to

NAS3-24886 FINAL REPORT

spread the transmitted signal over a wide spectrum. In this way a high power signal can be transmitted from a small antenna with low spectral density and thereby avoid violating the spectral density limits set forth by the CCIR. This makes it possible to operate small earth stations at C band in environments where clearance could not otherwise be obtained. On the receive side, CDMA also has the advantage of permitting signals coded in the station's code to be picked out of an environment of interfering narrowband signals. This is the result of the correlation receive processing that literally converges the coded receive signal into a narrowband signal of bandwidth determined by the original uncoded signal while spreading the interfering signal's power over a wideband equal to or greater than that of the spectrum spread signal.

In this study, only FDMA, TDMA and MF/TDMA transmission methods are assumed. CDMA has its peculiar advantages which can be factored in on a case by case basis as the need dictates.

2.4.5 TRANSMISSION CONFIGURATIONS

Various arrangements of FDMA, TDMA and MF/TDMA transmission can be used in a satellite system. Transmission schemes are the principal distinguishing hallmarks of the various classes of networks that will use future satellites which have multiple beams some of which are fixed and others hopping. Transmission methods applicable to Uplink and Downlink respectively are listed in the columns of TABLE 2.6. Each row identifies a particular combination of transmission methods for the up and down links respectively.

2.4.5.1 FDMA-FDMA Operation

Arrangement 1 uses FDMA on both the up and down links. It is the principal method used for most satellite systems during their first two decades of existence. The method is the natural evolutionary product of the use of the global and regional beam bent pipe transponding repeater satellite. It is also used as the principal transmission method in the multibeam systems of INTELSATs V and VI. Its attractiveness resides in the freedom it offers in terms of the operating discipline that must be adhered to by the users of the system. This freedom has led to the growth of many different and novel network architectures (such as the node/hub star networks popular at this time for VSAT business communications) and for this reason it will continue to be a principal component of any satellite system in the immediate future. The recent Hughes Galaxy filing for a CONUS system uses a combination of four regional up beams

NAS3-24886 FINAL REPORT

frequency cross connected to 64 fan-shaped downbeams distributed such that 16 fall into each upbeam region to support FDMA carriers carrying 64 kb/s SCPC services and TI digital services.

The principal difficulties with FDMA methods are the transponder distortion limitation and cumbersome interconnectivity. The distortion limitation is caused by the interaction of multiple FDMA carriers that share a single transponder. To reduce the distortion products so that they do not limit the performance of the link, it is necessary to back-off the power output of the transponders TWTA or SSPA by 3 to 5 dB. This wastes the valuable commodity of power for which millions of dollars have been invested. Connectivity is no problem for FDMA as long as all stations of a network are contained within the same beam. Multibeam networks multiply the number of FDMA carriers needed to accomplish full connectivity by the number of beams. This is not the case for TDMA.

TABLE 2.6
UPLINK AND DOWNLINK
TRANSMISSION CONFIGURATIONS

<u>ARRANGEMENT</u>	<u>UPLINK</u>	<u>DOWNLINK</u>
1	FDMA	FDMA
2	FDMA	TDM/TDMA
3	TDMA	TDMA
4	TDMA	TDM/TDMA
5	MF/TDMA	TDM/TDMA
6	MF/TDMA	FM/TDMA

- ON THE UPLINK:

FDMA OPERATION RESULTS IN THE LOWEST TRANSMIT EIRP BECAUSE OF ITS CONTINUOUS TRANSMISSION.

TDMA REQUIRES HIGH EIRP BECAUSE OF ITS LOW DUTY FACTOR BURST TRANSMISSION.

MF/TDMA REDUCES THE EIRP OF PURE TDMA BY INCREASING BURST TRANSMISSION DUTY FACTOR.

TDMA OR MF/TDMA IS MANDATORY FOR HOPPING BEAM SYSTEMS.

- ON THE DOWNLINK:

FROM THE POINT OF VIEW OF THEORETICAL TRANSMISSION PERFORMANCE, THERE IS NO DIFFERENCE BETWEEN TDMA AND FDMA.

TDMA OR MF/TDMA IS MANDATORY FOR HOPPING BEAM OPERATION.

Dynamic time domain switching and beam hopping cannot be used with FDMA to achieve beam to beam connectivity because the transmissions are inherently continuous. To achieve full beam to beam connectivity, it is necessary to slice up the spectrum into bands and to incorporate banks of filters onboard the satellite to frequency cross connect the beams. In a network having K beams, full connectivity requires that each of the K up beams be cross connected to K down beams. This requires K^2 cross connections and as many individual filters. The immensity of the cross connect problem is illustrated by considering the interconnection of a 200 beam system to fully interconnect CONUS which would require 40,000 filters. The cross connect bandwidths would be very small and the implementation of that many filters onboard impractical. Yet another limitation exists in the inflexibility of the traffic distribution. Once the bandwidths are established, they are not easily modified to accommodate changes in the distribution. By formulating special configurations of beam coverages and cross connects it is possible to achieve reasonable multibeam compromises for FDMA distribution. The INTELSAT V is a good example of this.

The recent GALAXY configuration offered by Hughes for FDMA service uses four approximately quarter CONUS uplink beams each connected to sixteen 1/64th CONUS fan beams (four in each of the uplink beam regions) requiring a total of 64 filters to achieve the cross connections. This is a reasonable number. The limitations of this arrangement reside in the fact that to be used efficiently the traffic must conform to a fairly rigid distribution that is literally built into the satellite system design. Also the improvement in the uplink G/T is limited to only 6 dB compared to the full CONUS and the downlink eirp increase attributed to beam gain is limited to 12 dB compared to CONUS.

2.4.5.2 FDMA-TDM/TDMA Operation.

Arrangement 2 employs continuous FDMA transmissions on the uplinks and TDM or TDMA on the downlinks. It is an optimum mode of operation from the point of view of most efficient use of the downlinks jointly with the most efficient use the earth stations if each transmits only one carrier. The earth stations operate in continuous transmission mode which with a single carrier per HPA uses the power potential of the HPA with greatest efficiency. The satellite operates in a single carrier per transponder time division multiplexed mode that allows it to distribute the uplink signals to all destinations without output power backoff or the need to provide many modulator/HPA units for numerous

NAS3-24886 FINAL REPORT

downlink FDMA carriers. However, the earth stations must operate in an asymmetrical manner for this configuration, the uplinks being continuous FDMA and the down links TDMA. The bit rate will be much higher on the downlink. Except for the need to implement a high speed demodulator this higher downlink rate does not change the downlink transmission budgets. This is so because, assuming the same total power delivered by the satellite to the composite of down links, the energy per bit on the downlink is the same whether the transmission is a low bit rate FDMA continuous carrier or a TDMA burst supporting the same bit rate destined to the station. Because TDM/TDMA always operates using single carrier per transponder, it may actually provide a better downlink budget compared to FDMA since output power backoff is avoided.

2.4.5.3 TDMA-TDMA Operation

Arrangement 3 refers to TDMA operation via bent pipe transponders. This is the operating configuration currently used for all TDMA systems. A good example is the 120 Mb/s TDMA system in the INTELSATs V and VI. The 72 MHz bandwidth transponders operate in a single carrier per TWTA mode resulting in very efficient use of the transponder's power resource. Inherently, the uplink and downlinks must be the same since the burst transmissions simply pass through the satellite without processing. By the use of transponder hopping, performed at the earth stations by transmitting their bursts on designated frequencies at designated times, the composition of station bursts carried in the down beams is different from that carried in the up beams. This is accomplished by adjusting the earth station burst time plans that specify the time and frequency of transmission and reception of the TDMA bursts for each station. These burst time plans are generated by INTELSAT traffic management and sent to the earth stations of the entire network over TDMA control (order wire) channels. The time plans of all stations are changed in a synchronized manner by use of a coordinated burst time plan change countdown. This causes the simultaneous switchover from an old to a new time plan in the same TDMA frame for all stations.

In the INTELSAT VI, the number of beams is increased from 4 to 6 and two dynamic microwave switch matrices (MSM), each interconnecting a bank of six 72 MHz bandwidth transponders, are provided to fully interconnect the beams. When TDMA is used jointly with the satellite it is referred to as SS-TDMA. The dynamic MSMs permit full interconnectivity of the 6 beams without the need to perform frequency hopping. The earth stations use the same TDMA terminals as were used in the INTELSAT V. The switching of the MSM is performed in terms of states of the switch

NAS3-24886 FINAL REPORT

that remain static for epochs long enough to pass the traffic scheduled for the state. Such switch states are illustrated in Figure 2.5. Theoretically an upper bound to the number of switch states needed during each TDMA frame to achieve better than 95% efficient traffic fill is given by the expression $K^2 - 2K + 2$ where K is the number of beams. For $K=6$, this number is 26. Approximately twice this number is actually provided to accommodate burst hopping between the switches and other unforeseen contingencies. The satellite switch needs a switch state time plan that is associated with the burst time plans for the earth stations. Both of these time plans are included in the coordinated time plan procedure to synchronize changes in the switch state time plan with those in the traffic time plan. SS-TDMA operation equates to a distributed switching machine in which time domain storage is performed in the earth stations and memoryless space switching is performed on the satellite.

2.4.5.4 TDMA-TDM/TDMA Operation

This mode of operation, designated as arrangement 4, is possible only when there is a baseband processor on board the satellite. The uplink signals are assumed to be carried in the conventional TDMA fashion as described above. However, on the downlink the uplink signals are multiplexed into a contiguous TDM stream. This can be accomplished by means of the onboard baseband processor which converts the TDMA bursts arriving on the uplinks into their digital baseband form and, by means of either onboard buffers or onboard circuit switching with memory, multiplexes these on to the continuous downlink TDM streams. If the downlink beams are stationary then the downlink transmission appears continuous thus simplifying the earth station's demodulator and receive side demultiplexer. The ITALSAT system uses this design. If the downlink uses hopping beams then even though the transmission is continuous, it appears in burst format (like TDMA) in the individual beam dwells. The ACTS system uses this design.

2.4.5.5 MF/TDMA-TDM/TDMA Operation

This mode of operation, designated as arrangement 5, uses the same downlink design as arrangement 4; however, on the uplink it introduces multiple, low bit rate uplink TDMA carriers which are referred to as MF/TDMA. This type of implementation requires an onboard baseband processor that is able to demodulate the low bit rate uplink TDMA signals and recombine them into a composite high bit rate TDM (in the case of fixed beams) or TDMA (in the case of hopping beams) carrier. The advantage of this arrangement is that it makes it possible to use less eirp

NAS3-24886 FINAL REPORT

to operate the uplink permitting the use of earth stations having smaller antennas or lower power HPAs or both. A necessary precaution is that the uplink rate must be high enough to serve the composite traffic of a reasonable number of earth stations. Also, the transmit side burst rate will be higher than the receive side burst rate making it difficult to test the earth station in a local loop back connection. ACTS also operates in this mode.

2.4.5.6 MF/TDMA-MF/TDMA Operation

Arrangement 6 applies to operating multiple low burst rate TDMA carriers in the band of a transponder rather than a single and much higher burst rate TDMA carrier. It applies only in the case of bent pipe operation where individual transponders, used to interconnect the up and downbeams, operating in either a static or dynamic switched mode, carry several low burst rate TDMA carriers shared among the earth stations rather than one high burst rate TDMA carrier. An example of this operation would be the use of the HBR MSM transponders of ACTS to carry a multiplicity of low bit rate TDMA carriers in SS-MF/TDMA with or without beam hopping. Such operation sacrifices capacity but permits access by much smaller earth stations than would otherwise be possible.

2.5 COMPUTER AND DATA COMMUNICATIONS

To establish a departure baseline for Computer and Data Communications, an analysis was made of the possibilities for handling packet data using the onboard configuration presently planned for the ACTS. There are several ways that packet data communications can be supported with the present ACTS multibeam communications processing package to provide node-hub, and full mesh packet connectivities. These are discussed in the following. Because the ACTS MCP has no onboard processing capability for interpreting the packet header information, it cannot be used as a packet node and can act only as a path through which the packets pass without modification. This path may be circuit switched or stationary and with these capabilities the ACTS MCP can support packet communications between nodes in a mesh configuration or between nodes and hubs in a star configuration.

2.5.1 PACKET COMMUNICATIONS ON ACTS

The ACTS system can support experimental studies of packet communications on board satellites by means of its onboard BBP as controlled by the ACTS MCS. This can be accomplished in a circuit switched manner or over a stationary preassigned channels used in a random access TDMA (slotted Aloha) fashion. A packet node onboard is a future possibility and has important operational advantages due to direct multidestinational distribution which is possible only with a satellite, and reduced propagation delay in performing the acknowledgement function. The present ACTS is not equipped with an onboard packet node capability; however, when used in the circuit switched packet mode it can provide valuable experience in studying the protocols needed for such operation.

2.5.1.1 Circuit Switched Operation

In the circuit switched mode a 64 kbit/s channel is set up in each direction between the origin and the destination over the ACTS Multibeam Communications Payload (MCP). Control of the stored messages is performed from the ground by the MCP using a high rate data link to the satellite. This permits network control of onboard packet communications experiments from the ground via the order wire links between sending node and the MCP and the receiving node and the MCP. The various steps needed to accomplish packet communications using this arrangement are

as follows:

- 1) Receive and store packet at the earth station node,
- 2) Request satellite forward and return channels to destination from MCS via orderwire,
- 3) Using a synchronous burst time plan change procedure establish the channels and transmit the packet,
- 4) Destination station receives the packet and performs an error check. If correct, it responds with an acknowledgement. If in error, no acknowledgement is sent,
- 5) If no acknowledgment is received at the originating station within an established timeout, the packet is retransmitted until an acknowledgement is received.
- 6) When an acknowledgement is received at the originating station, it sends a channel disconnect message to the MCS via the orderwire.

2.5.1.2 Stationary Preassigned Channel Operation

In a preassigned stationary configuration, permanent channels are established via the ACTS MCS which connect upbeam dwells to downbeam dwells and these are accessed by the earth stations on a random access TDMA basis using the slotted Aloha packet communications mode. This arrangement is illustrated in Figure 2.6 for the connection of an uplink channel in each of 4 beam dwell regions to 4 downlink channels in one downlink channel which is in this case in beam dwell region 1. In this figure the channels are designated by pairs of numbers, the first designating the dwell region and the second the channel number in that dwell occurring in increasing numerical order. The same connectivity pattern can be repeated for any number of down beams (not shown in the diagram). For total connectivity, if the hopping beam system has N dwell regions that are visited in each 1ms TDMA frame and it is desired to interconnect all N in a random access TDMA manner, N uplink channels would be assigned to each dwell, one destined to each of N downlink dwells, and N downlink channels would be assigned in each downlink dwell. Thus a total of N^2 channels would be used to support the system. Such a configuration can carry approximately 20% of the maximum capacity in the form of random packets synchronized to slot boundaries (the slotted Aloha

mode). Hence the throughput capacity of the system would be $0.2N \times 64$ kbit/s. Assuming that $N = 20$ and that each transaction requires a 1 kbit packet in the forward direction and a 100 bit transaction in the reverse direction, the configuration would support 40000 transactions per day. If a node/hub arrangement in which uplinks from several dwell regions are routed to only one downlink in a destination dwell region containing the hub, a return link must be provided to all originating nodes from the dwell region containing the hub and this can be accomplished by broadcasting the uplink from the hub's dwell.

Stationary preassigned operation can also be configured to provide the uplink channels in a serial fashion in a superframe. This permits operation of random access TDMA with a lesser commitment of total capacity than does the configuration described in the previous paragraph. A single downlink channel in a destination dwell region is time division multiplexed among the uplink beam dwells in a superframe as shown in Figure 2.7. This pattern can be repeated for a downlink in each destination dwell to achieve full interconnectivity using the capacity of N channels. Such a configuration is shown in Figure 2.8 for $N=4$.

2.5.1.3 Future Onboard Packet Node

An attractive communications concept involving future satellites with on board baseband processing capability uses the satellite as a packet communications node. In this application the satellite BBP must perform the following steps:

- 1) Receive packets from earth station nodes,
- 2) Store the packets in its memory,
- 3) Read the address information,
- 4) Send acknowledgments to the sending nodes,
- 5) Forward the packets to an earth station node near the destination,
- 6) Wait for acknowledgements, and
- 7) Remove acknowledge packets from its memory.

The ACTS communications system as it is now configured does not have the capability to perform the packet error check and acknowledgement onboard, and hence these functions must be performed at the destination earth station. However these functions can be executed via the MCS function at the NASA ground station operating in a manner that assigns a switched circuit to carry the packet. Of course this type of operation involves more delay, principally double hop link rather than a half single hop, but it can provide a means to develop protocols and gain operating experience in implementing an onboard packet node function.

The most obvious extension of an advanced onboard processing satellite network controller beyond that of the ACTS for accommodating computer and data communications is the provision of node processing capabilities on board the satellite. This option is considered in the next section.

2.5.2 CONFIGURATIONS FOR COMPUTER AND DATA COMMUNICATIONS

Three methods for configuring computer and data communications over a satellite equipped with an onboard processing and beam hopping capability are discussed in the following. The first uses a circuit switched technique, the second random access with preassigned circuits routed on the satellite and the third incorporates a packet node onboard the satellite. First, it is important to demonstrate the advantages of having such a capability compared to the more simple routing through circuit switched paths as is possible on the ACTS. Important factors to be considered are onboard packet acknowledgements and distribution of such packets directly to their destinations. Secondly, assuming that advantages are identified, it is important to assess and select an implementation technology.

2.5.2.1 Circuit Switched Operation

In a circuit switched mode, a full duplex circuit is established between the origin and the destination. This is accomplished by using the signalling order wires that exist between the traffic stations and the Network Control Center (NCC) facility. When a data transmission session is to be initiated, the originating station requests a duplex circuit by informing the NCC of the destination telephone number. The NCC proceeds to fulfill the request by identifying appropriate time slots in the burst time plans of the originating and destination stations and routing through the satellite switch including the hopping beam dwell assignments. The

NCC commands the execution of these instructions, the circuit is established and the data transmission proceeds. When the session is completed, the originating station indicates the termination to the NCC and the circuit is disconnected.

The various time steps and the delay times encountered in the process of establishing, operating and terminating such a circuit are illustrated in the time graph of Figure 2.9. The four columns of this figure refer respectively to the functions performed at 1) the originating earth station, 2) onboard the satellite, 3) the NCC and 4) the destination station. The vertical axis is annotated with the number of the function performed and the elapsed time between the execution of functions due to propagation delay and processing latency. The propagation delay on a single pass between the satellite and the earth is assumed to range from 120 to 140 ms.

At time 1 a switched circuit session for data transmission is initiated by a circuit request message (CRM) to the NCC which identifies both the originating and destination interfaces. At time 2 the CRM passes through the satellite over an established orderwire path and hence to the station that serves the NCC.

At time 3, the CRM is received by the NCC where the channels are selected for routing the call over the system. The NCC organizes a channel assignment message (CAM) which identifies the channels to be used by the originating and destination stations and transmits this to the stations over an appropriate network control channel. It also organizes a satellite switch message that controls the channel routing through the satellite and sends this to the satellite over its network control link. Both of these messages pass through the satellite at about the same time at time 4. The satellite switch message initiates onboard a coordination delay timer that causes the satellite switch to assume the new switch configuration on a time precisely synchronized with the arrival at the satellite of the newly configured channels that have been set up at the originating and destination stations in response to the CAM. The CAM is received at both the originating and destination stations at about the same time at time 5 and using an appropriate delay of no greater than 20 ms at each to compensate for propagation path length differences the duplex circuit is established for transmission at time 6. The time elapsed from the request at time 1 to the circuit availability at time 6 is a maximum of 580 ms and a minimum of 500 ms. At time 6, the data transmission can commence.

It is assumed that the data is transmitted in packet format. These packets are transmitted using a protocol suitable for satellite propagation delay such as the extended X.25. During the session, ARQ acknowledgements (ACKs) are sent by the receiving end for packets that are successfully received. Any packets that are not acknowledged within a time out long enough to account for the satellite propagation delay are repeated and during such repeats the incoming data is not transmitted and if it cannot be stopped it must be buffered. The transmission of the packets cycles through time steps 6 to 10 repeatedly as long as the session continues. When the session is completed the originating station sends a circuit terminate message (CTM) to the NCC which proceeds to disconnect the circuit. It does this by organizing a disconnect message that is sent to the originating and destination stations and causes them to release the circuit making it available for another call at the NCC in time steps 11 to 15.

2.5.2.2 Random Access With Preassigned Circuits

The idea to be exploited here is based on the use of preassigned connections through the satellite switch that are routed to various down beam dwells. Assume that the satellite has been programmed to provide one or more time slots (channels) from each uplink dwell into each downlink dwell and each station is able to synchronize its transmissions precisely to the time boundaries of these channels and to a superframe that permits it to select slots destined to a particular downlink beam dwell. This channel arrangement has been preassigned by the NCC solely for the purpose of random access packet communications and can varied from time to time to accommodate traffic flow pattern changes. When a station wishes to send a data packet, it simply transmits a burst at a time that aligns it with a time slot at the satellite that will route it to the destination's downlink beam dwell. The only requirement is that the start and stop of transmission be aligned with a time slot but it does nothing otherwise to select the channel slot. This is a slotted random transmission technique that has a theoretical maximum throughput of e^{-1} .

Figure 2.10 depicts the time flow graph for this type of random access transmission. At time 1, the data burst packet is transmitted into a superframe slot that is synchronized at the satellite with the occurrence of a baseband switch routing that will retransmit the data packet into the destination downlink beam dwell. Onboard the satellite at time 2, the onboard processor demodulates and decodes any outer channel

FEC, routes the packet bits to the appropriate downlink output memory, adds an outer FEC code if desired and retransmits the packet into the beam dwell containing the destination station. The packet is received at the destination station at time 3. The packet is decoded and error checked and if the check is successful an acknowledgement (ACK) is sent over a return link of the same type using the same random access method.

Alternatively, if the packet transmission protocol is the selective repeat type, messages not received or received with error are identified by a non acknowledge (NACK) message and these are sent back to the originating station over the same type of link. There will be some delay between reception of a packet and transmission of the acknowledgement at the destination to accommodate path length compensation and packet processing. The ACK or NACK message is transmitted from the destination station at time 3 plus the small delay referred to above, passes through the satellite at time 4 where it undergoes the same type of routing and processing it encountered on the forward link, is retransmitted in the beam dwell containing the originating station and arrives there at time 5. The total time elapsed is a maximum of approximately 580 ms. The originating station does not wait until an ACK or NACK is received before it transmits its next packet. Rather it continuously transmits packets and also stores them in a memory until either an ACK is received or in the case of NACK operation a time out expires.

This random access method is far simpler and faster to operate than the circuit switched method since it eliminates the need to perform call processing and the initial time delay thereby encountered. For data packets with short holding time, the random access method is more suitable because it eliminates the initial call processing and switched circuit setup time. For data transmission sessions with long holding time, the circuit switched method is better because the initial delay in setting up the circuit becomes a small fraction of the total session time, thus rendering it insignificant, and the circuit throughput is essentially 100% rather than having theoretical maximum of e^{-1} .

2.5.2.3 Onboard Packet Node Data Transmission

In this configuration, a packet node function is located onboard the satellite. Each uplink beam dwell would provide one or more preassigned channel time slots which traffic stations would access by the slotted random access method. Unlike the preassigned channel method described in the previous section which must have a superframe for providing channel slots destined to various down beam dwells, the channel slots

need not be destination designated. This is because the onboard packet processor disassembles each packet, reads its destination address from its header and thereby sends it to the appropriate output memory that serves the beam dwell containing the called for destination. In addition, the onboard packet processor generates the ACK or NACK messages for transmissions between the originating station and the satellite. On the downlink, the onboard packet node reassembles the data packets and transmits them to their destinations during the appropriate beam dwell. It retains in memory all outstanding packets for which an ACK has not been received or for which the time out for a NACK has not expired. The channels used to transmit the downlink packets can be preassigned in each downlink beam dwell. The receive sides simply listen to these channels and pick out those messages addressed to them. To do this the receivers must decode all receive messages to a level sufficient to obtain the destination addresses. The use of an onboard packet node processor inherently serves the needs of both full mesh and the node/hub star type networks. In the former the packets are transmitted into all downlink dwells, while in the latter they are automatically transmitted into that downbeam dwell containing the hub.

The time steps involved in operating the onboard packet node are shown in Figure 2.11. At time 1 the originating station transmits its data packet to the satellite. At time 2 the packet is received onboard, disassembled and the ACK or NACK is generated and sent to the originating station as appropriate. Also the packet is reassembled and transmitted into the beam dwell containing the destination station. At time 3, the originating station receives the ACK or NACK approximately 280 ms after transmission and the destination station receives the packet. The destination station sends an ACK or NACK as appropriate back to the satellite where it is received onboard at time 4 (approximately 420 ms after the original transmission), completing the handling of the packet. If a packet gets garbled in transmission, transmission repeats will occur and extend the process. As described previously, the transmission of messages at both the satellite and the originating stations goes on continuously and does not wait for the acknowledgement process for any single packet to be completed.

2.5.2.4 Comparison Of The Data Communications Techniques

Three techniques for accomplishing data communications have been described in the foregoing text. In this section these are compared to determine their relative advantages and disadvantages. A summary of the

three in terms of various system parameters is given in Table 2.7. Considering first the circuit switched technique designated as case 1. It has a prominent characteristic which is the 500 and 580 ms delay encountered in connecting and disconnecting the circuit that under certain circumstances can be a disadvantage. This delay results in low throughput efficiency when the data transmission has a short holding time. For example if a single 1 kbyte packet is to be transmitted over a 64kbit/s circuit, the holding time is only 62.5 ms. Obviously, if it takes 580 ms to setup the circuit and an equal time to take it down, then the total time to serve the message is 1222.5 ms yielding a throughput efficiency of only 5%. However, if the session holding time is long compared to the time required to setup and disconnect the circuit, then the efficiency can be much higher. For comparison, the maximum efficiency of a slotted packet system is e^{-1} (37%). The length of session that yields a switched circuit throughput efficiency of this value is 670 ms. or approximately 10 1 kbyte packets. From the point of view of flexibility, the circuit switched method is rated as good because it is able to establish a circuit anywhere in the network. With regard to earth station complexity, it requires the equipment and protocols needed to perform call processing and the communications link back to the NCC. Such equipment and protocols are not necessary in the random access packet modes. With regard to onboard equipment complexity, it requires a demultiplexing/ demodulation /decoding/circuit switching/coding/modulation/multiplexing capability which is of the order of complexity of the ACTS.

Consider next case 2 which incorporates random access data transmission with preassigned channels. A principal disadvantage of this configuration resides in the requirement that for full connectivity in an N beam dwell system, N channel slots (one to each down beam dwell) must be provided in each upbeam dwell yielding a total of N^2 upbeam channel slots. Thus, a large fraction of system capacity is used to implement this configuration. Because the channel used to carry the packets is preassigned, it is always available and no delay is encountered to connect and disconnect. This results in high throughput efficiency for data calls with short holding times. The throughput efficiency is theoretically limited to a maximum of e^{-1} where congestion on the transmission link causes so many packet collisions that the system crashes. In actual practice, the throughput is limited to about 20% to achieve satisfactory performance. Even so the use of this type of data communications is becoming one of the most popular for satellite bypass of the terrestrial networks especially by users who transmit only a few packets at a time a few times a day. The network flexibility, which refers to the ability to

adjust transmission capacity to the traffic flow pattern, is relatively poor compared to that possible with circuit switching. Consequently, the capacity between some up and down links, if under utilized, is not rapidly reassignable. This is not an unreconcilable limitation since if the terminals are equipped for burst time plan reconfiguration under control of the NCC, provision can be made to reconfigure the capacity to conform to long term changes in traffic flow. With regard to earth station complexity, it is simpler than that of the station that operates in the fully variable circuit switched environment provided the structure of the channel satellite slots (established by the up and downlink burst time plans and the onboard switch plan) used to accommodate the transmission links remain the same over long periods of time. However, if the ability to respond automatically to system wide burst time plan changes is to be included, then the terminal will be of the same complexity as a circuit switched system terminal. Regarding the onboard processor complexity, it is the same as that required for the circuit switched operation which is comparable to that of the ACTS. The realization of the mode of operation represented by this case does not require any additional onboard processing.

The 3rd case is that using an onboard packet node. With this capability the data packets are disassembled on the satellite, the destination and originating station addresses are read and the packet is selectively sent on to its destination. One of the most important consequences of this onboard processing capability is to eliminate the proliferation of upbeam channels needed to achieve full access to all downlink beam dwells. Only one uplink channel is required per uplink beam dwell to achieve connectivity to all downlink beam dwells. Thus in an N beam dwell system, a minimum of N preassigned uplink channels are required for full connectivity. This is to be compared with a minimum of N^2 preassigned uplink channels without the onboard packet processing node (Case 2). Each uplink channel used to carry data packets is preassigned and always available without connect and disconnect delay. This results in high throughput efficiency for data calls with short holding times. Downlink packets are also carried on on preassigned channels with a minimum of one for each downbeam dwell containing a data packet destination. Depending on traffic demand, more than one channel will be provided in any up or down beam dwell. This mode of operation has two additional desirable results due to the halving of the propagation delay between the packet nodes on the satellite and at the originating and destination stations: it reduces the buffer storage capacity in the earth station terminals and it improves the throughput over the link

by approximately 10% at a channel BER of 10^{-6} if go back N ARQ is used for error control. To accomplish this, packet node processing must be implemented on board the satellite.

In summary, a satellite system configured with many beams to improve uplink G/T and downlink e.i.r.p. and thereby make it possible to operate with many widely distributed, small, low power earth stations an onboard packet node processor operating via preassigned channels in the up and downlink beam dwells is clearly the best choice. Without the onboard packet processor, either call processing using onboard circuit switching or preassigned end-to-end channels are the only choices. The former is very inefficient for the popular short holding time packet use and the latter is wasteful of satellite channel capacity.

TABLE 2.7

COMPARISON OF THREE ONBOARD SWITCH IMPLEMENTATIONS

CASE 1: CIRCUIT SWITCHED DATA TRANSMISSION

**CASE 2: RANDOM ACCESS DATA TRANSMISSION WITH
PREASSIGNED CHANNELS**

CASE 3: ONBOARD PACKET NODE DATA TRANSMISSION

PARAMETER	CASE 1	CASE 2	CASE 3
• Time to Establish Circuit	580 ms	0 ms	0 ms
• Time to Disconnect Circuit	580 ms	0 ms	0 ms
• Transmission Efficiency	Limited by need to set up and disconnect circuit plus the need of ARQ for ACK/NACK	Limited by random access contention and need of ARQ for ACK/NACK between end users	Limited by random access contention and need of ARQ for ACK/NACK between satellite and end users

TABLE 2.7 CONTINUED

(ARQ works
with 1/2 delay
and less noise)

	N	N ²	N
• Minimum Number of Preassigned Channels			
• Suitability for Small Packets (Short Holding Time)	Poor	Good	Superior
• Suitability for Large Packets (Long Holding Time)	Superior	Poor	Poor
• Networking Flexibility	Good	Poor	Good
• Earth Station Complexity	Requires channel assigned protocol	Simpler No channel assigned protocol	Simpler No channel assigned protocol
• Onboard Complexity	Same as ACTS	Same as ACTS	More complex than ACTS
• NCC Complexity	Same as ACTS	Same as ACTS	Low

2.6 ADVANCED SATELLITE TELECOMMUNICATIONS OPTIONS

Using the ACTS as a baseline, it is currently implemented as a circuit switch in orbit in which the instructions controlling the interconnections from channels in the uplinks to channels in the downlinks are stored in an onboard program control memory but are changed in response to call requests processed in a network control center (NCC) in the master control station (MCS) located on the ground. Call request information is first intercepted at an originating earth station and the request sent to the MCS via a satellite orderwire link. Using the current status of network connectivities underway and the ensemble of requests from all stations, the network control processor of the MCS generates new burst time plans for all stations of the network, new switch commands for the onboard connectivities between up and downlink channels and new beam dwell patterns. These are distributed to the network via an orderwire link to the earth stations and an orderwire link to the satellite. A coordinated time plan change in which the the traffic stations invoke their new time plan changes so that the changes are precisely synchronized at the satellite with the onboard switch connection and beam dwell changes can be made once every 300 ms.

In this advanced onboard processing and network control study, two options are considered. The NCC and its call processing function could be located onboard. This would reduce the amount of uplink communications for switch control since the onboard switch is "smarter" and generates its own switching instructions. Another option is to incorporate destination directed packet switching in which each transmission burst has a destination address in its header that is used onboard to direct the message contents to the destination. These two configurations are discussed in the following and the later has been selected for more extensive examination in section 3 of this report.

In addition, the following text discusses of two ancillary issues that are important to the future satellite system architecture, namely, minimizing the size of the onboard storage by using to as great an extent as possible the idea of "storage in space" and the integration of other services and in particular mobile satellite communications.

2.6.1 ADVANCED NETWORK CONTROL

2.6.1.1 Call Processing On Board The Satellite

NAS3-24886 FINAL REPORT

The possibility of locating the Network Control Center (NCC) and its call processing function on board the satellite was analyzed. In this case the signalling information is detected in the ground station and sent over an order wire to the satellite where it is used to perform the same NCC functions presently performed on the ground. This requires that the satellite disseminate the new traffic burst time plans to all of the affected traffic stations as well as determining and executing the onboard switch connectivities and beam dwells.

An onboard NCC circuit switched alternative is made possible by introducing common channel signaling. In common channel signalling the signalling message is divorced from the channels with which it is associated and the messages for all channels are sent over a common channel. This is type of signalling that is being implemented in CCITT signalling system No. 7. It could be sent directly to the satellite from a single earth station and used for onboard NCC. Onboard the satellite it would be used in the same way as signalling detected at the ground stations and sent to the satellite via the orderwire.

The principal advantage of locating the NCC function on the satellite would be a reduction in the transmission load on the control link to the satellite. An investigation to estimate the level of the reduction was made and concluded that the savings would not be very great even for a relatively large number of hopping beams (up to 10) and would likely not justify the increased complexity, weight and power on the satellite. The details are included as Appendix 1 and an associated Appendix 2.

2.6.1.2 Destination Directed On Board Switching

There exists the possibility that the voice circuits set up over the system be virtual circuits similar to those used for data packets. This could be accomplished by attaching to each burst of voice signal information a destination port address in the system. An earth terminal operating in this way would not be concerned about the specific location of a channel in its frame since the destination address renders this unnecessary. All the station needs is sufficient time slots in the TDMA frame to handle its total traffic load. Voice signal bursts would be sent only when the voice signal is actually present and thus the system would in addition realize a speech interpolation activity advantage. Similarly, there would be a data activity advantage. When these destination addressed bursts are received onboard, they will be decoded and used to direct the bursts to their proper destination port by assigning the bursts to a downlink TDMA burst in the beam dwell containing the destination

station. Call setup would be conducted by similar destination directed bursts. This concept could significantly simplify the network control protocol in the area of dynamic assignment of individual channels in the traffic burst time plans.

Because of the great promise of the destination directed message approach, a large fraction of the effort expended under this study has been devoted to the implementation of such a system. It is closely related to the concept known as fast packet switching that is currently receiving attention in all forms of voice data and teleconference communications. Section 3 of this report deals exclusively with this approach. This study considers the use of virtual circuits set up by destination addressing with a virtual switching node located on board the satellite, identifies the onboard implementation requirements, defines the features in the earth station needed to operate with such a network and develops a protocol for capacity and beam dwell adjustment among the stations.

2.6.2 MEMORY IN SPACE

Onboard Memory is essential to implementing an onboard switch. Without it, it is not possible to redistribute the channels grouped contiguously according to origin station arriving in uplink bursts into downlink bursts grouped contiguously according to destination station. The ability to reroute individual channels is the feature that distinguishes the ACTS system from systems without memory such as SS-TDMA operating with a MSM. As described previously, it greatly reduces the number of individual traffic bursts and of beam hopping dwells.

The ACTS as it is presently designed uses separate input and output memories, each comprising a pair of memories operating in a ping-pong manner. At the input (uplink) one member of the pair stores the arriving uplink channels while the other plays back the uplink channels stored on the previous frame into a space switch that interconnects the beams. The roles of the memories reverse from frame to frame an action referred to as ping-pong. At the output (downlink) a pair of ping-pong memories operate in a similar manner to accept the output channels from the space switch and format these into the downlink groupings. This arrangement requires a memory having a total size equal to four times the size of a TDMA frame. The size of the memory can be decreased by a strategy described in the following which uses the fact that the next channels to be switched are stored in space and this storage can be used as part of the switching operation.

By recognizing that the next channels to be switched reside in the space immediately lying in front of the antenna and by designing the memory control to use this fact to advantage, the operations of storage and rearrangement into the desired downlink groupings can be performed in a memory having the capacity of a single frame. For destination packet like switching this design requires that the destination directing information be transmitted in the header of a burst arriving one frame before the burst containing the message to be switched. It also requires that the memory be operated so that a channel just arriving occupy the location of the channel that just departed on the downlink. This basic concept is used in the design of the destination directed packet switch on board system described in Section 3 of this report.

2.6.3 INTEGRATING IN OTHER SERVICES

2.6.3.1 Capability to Accommodate Different Services

Future satellite communications payloads may be required to serve a multiplicity of different communications services integrated into the same package. This multiple service capability is greatly aided by the presence of onboard demodulation of the uplink signals, channel level switching and its associated storage and remodulation on the downlink. The reason for this is that the signals onboard are reduced to the common digital baseband denominator and can all be treated in a similar manner. The differences lie in the demodulators and modulators that must render the signals to the form that is needed to accommodate the type of service.

Probably the most different combination of services that can be imagined would be the marriage of continuous SCPC digital mobile services operating in a wide area coverage beam with the destination directed burst telephone services operating in a hopping spot beam environment. From the point of view the type of service rendered and the ground station equipment and protocols needed, these are widely different. Thus in section 4, the integration of SCPC mobile services into destination directed burst telephone services is used to demonstrate how a future satellite would accommodate different services. This is sufficiently representative to allow for the extension to integrating many other services.

2.6.3.2 Synchronization Among Different Services

One of the principle keys to integrating various services is

synchronization to a common timing base onboard the satellite. In TDMA systems, this is accomplished as a consequence of the synchronization discipline that is inherent in the acquisition and synchronization process. As long as all of the uplink signals are controlled by the same discipline it is possible to keep the individual bits that comprise the channel information properly aligned relative to the onboard clock with at most a small alignment buffer to accommodate small timing variations. Thus, the combination of different types of TDMA service in a common onboard processor even though each may use a different transmission burst rate does not pose a problem. This includes transmission over intersatellite links which can be viewed as simply the interface of another antenna beam.

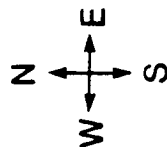
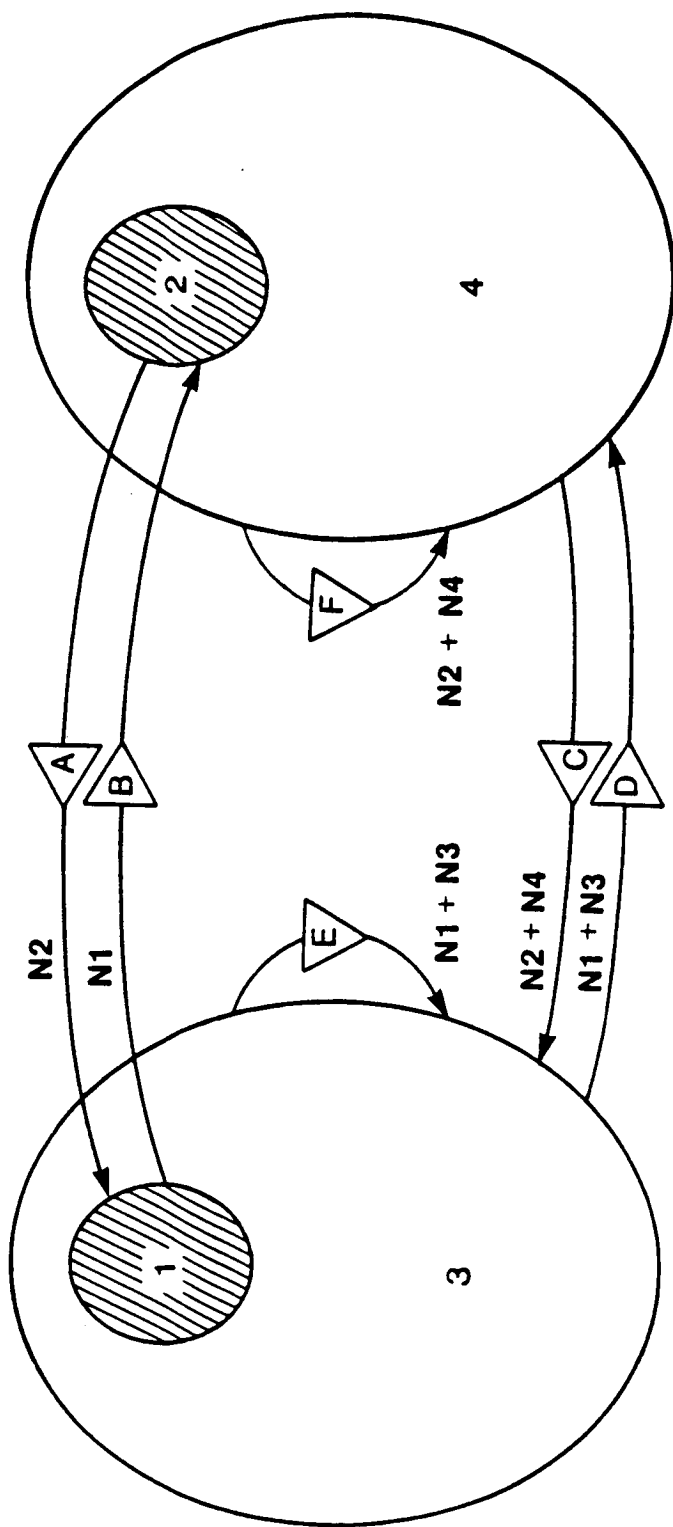
This synchronization requirement does pose a problem that needs to be resolved when it comes to continuous SCPC transmission signals. Such transmissions are normally free from frame synchronization requirements because they are unframed. However, in an onboard system that has a frame structure discipline, it is necessary to establish one. To do this it will be necessary to insert into the SCPC transmission a framing discipline that can be used on the satellite to align the signals with those derived from the other services.

With regard to downlink transmissions, the situation is not as complicated as on the uplink. This is because all signals are time aligned to the onboard timing and are inherently in a synchronous format that easily accommodates reformatting into various down link transmission schemes to meet the needs of various types of service. The onboard processing will in all likelihood treat all signals the same regardless of their service origin. Thus, those channels associated with each type of service can be supplied to the appropriate downlink interfaces equipped with buffers to perform rate conversion. The downlinks may be high speed TDM/TDMA carriers that are beam hopped to various destinations in which case a burst forming buffer performing rate upconversion is needed. If the the downlink rate happens to coincide with the rate used in the onboard processor, the switching memory may serve as the burst forming buffer. If the downlinks appear as continuous SCPC signals then a rate conversion buffer that converts the onboard processor's channel bursts into continuous transmissions are needed.

2.6.3.3 Source Coding Considerations

There is one more issue that needs consideration when mixed services

are concerned and that relates to the method of source coding used. It would be most desirable if all services used the same source coding method. If this were so, no matter the nature of origin or destination of the service it would always be in a compatible format. However, this may not always be possible. For example, mobile services might well use a heavily coded 4800 bit/s vocoder format to combat the vagaries of the mobile transmission link and operate from small low powered earth terminals while the trunk telephone services are likely to use one of the source coders designed for toll quality service such as 64 kb/s PCM or 32 kb/s ADPCM. One solution to accommodate this difference is to include onboard transcoders that convert the low bit rate formats to the standard toll telephone format. An alternative is to carry the coded low bit rate mobile service vocoder signals back to the earth terminals serving the telephone service and perform the conversion there.



STATION CONNECTIVITIES



FIGURE 2.1 INTELSAT V BEAM CONNECTIONS

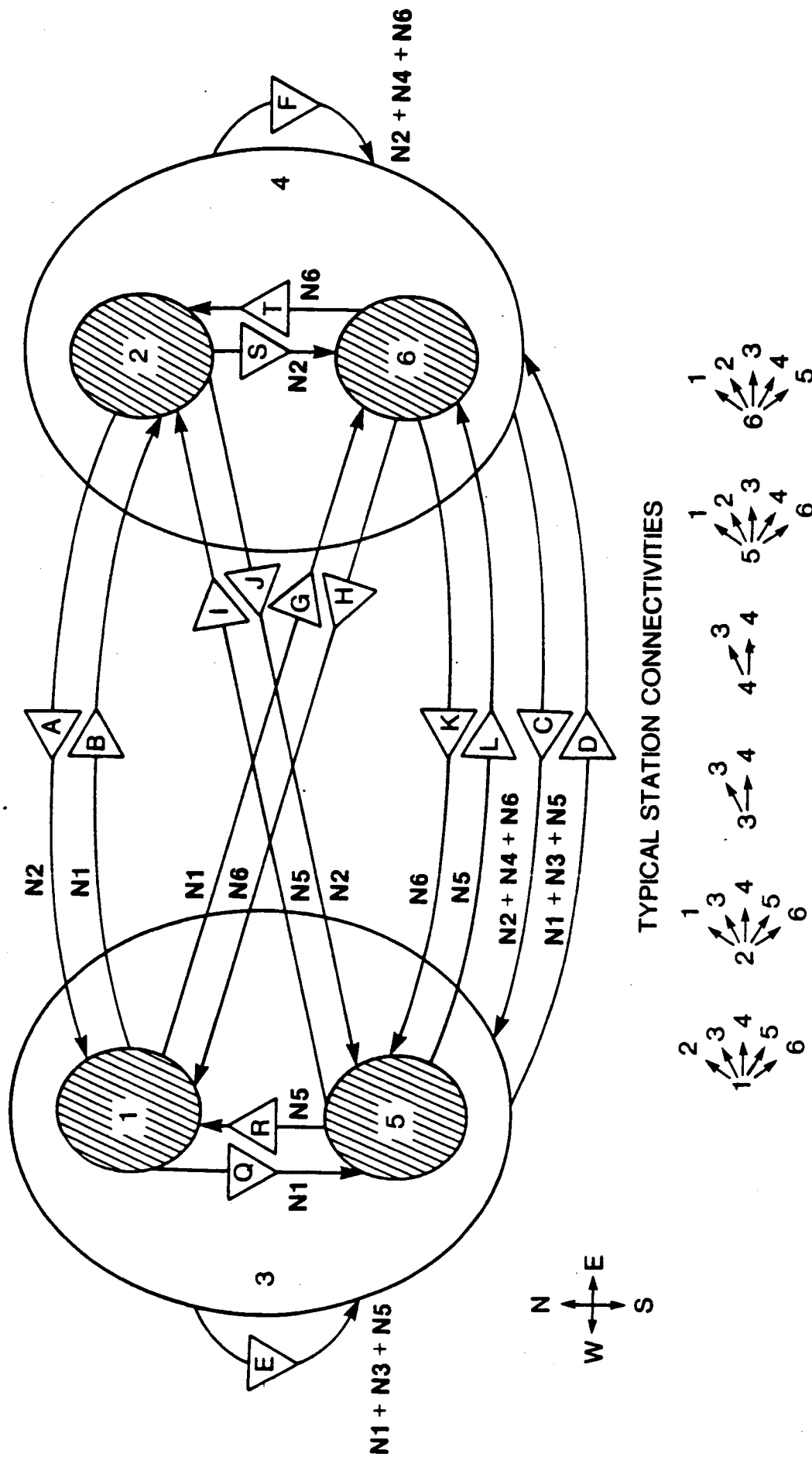


FIGURE 2.2 INTELSAT VI BEAM CONNECTIONS

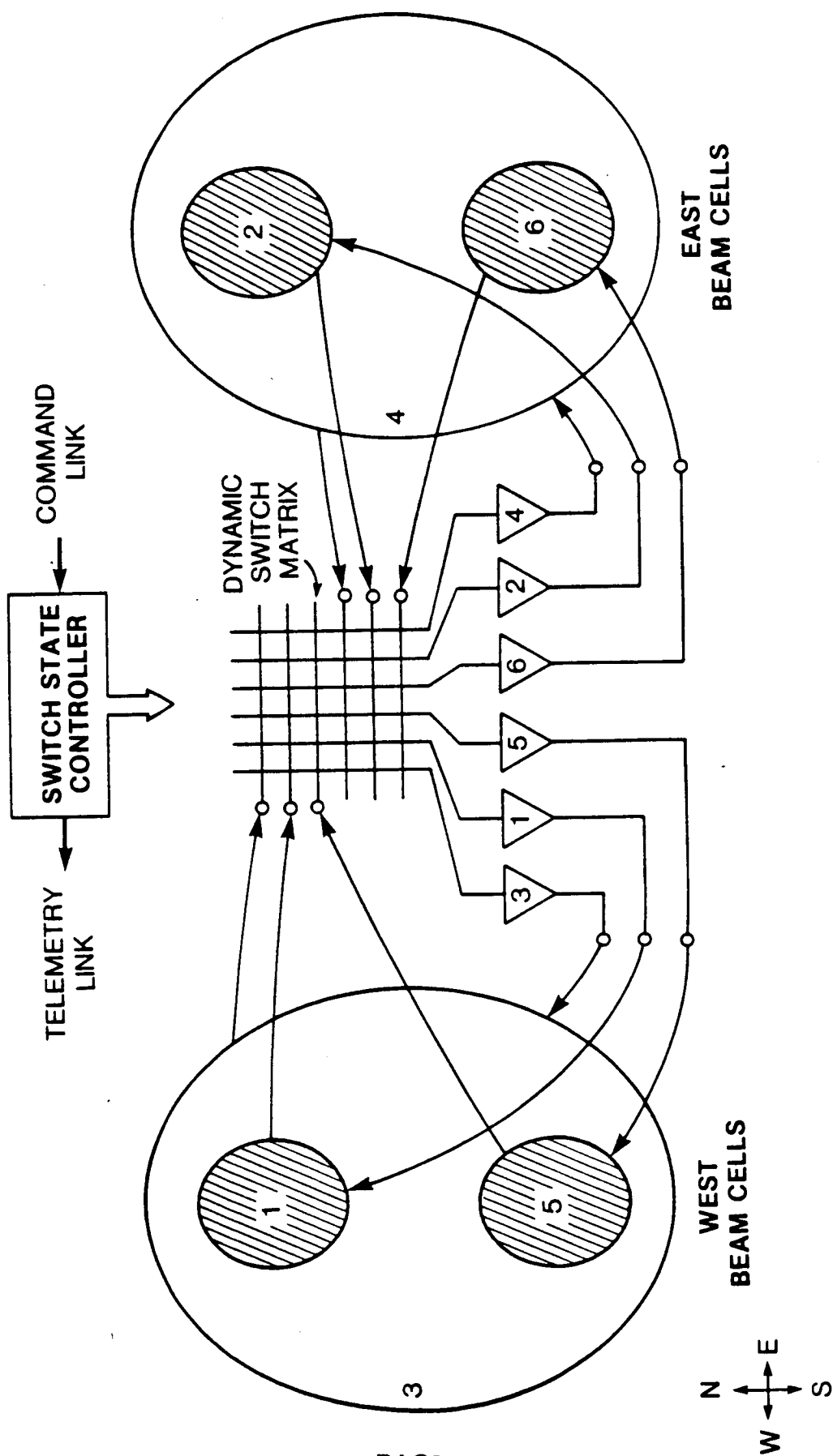


FIGURE 2.3 INTELSAT VI BEAM CONNECTIONS USING 6x6 MSM

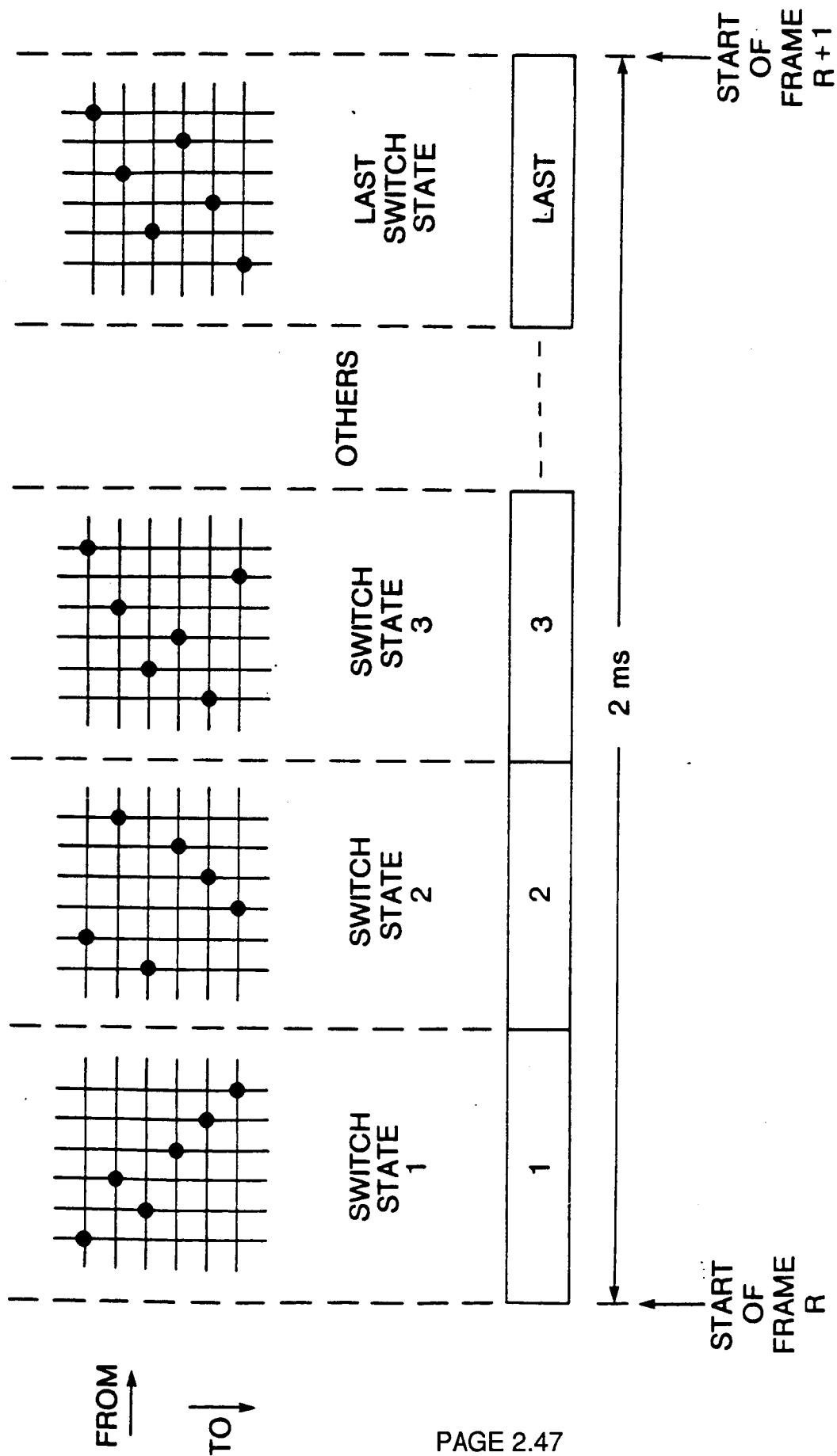
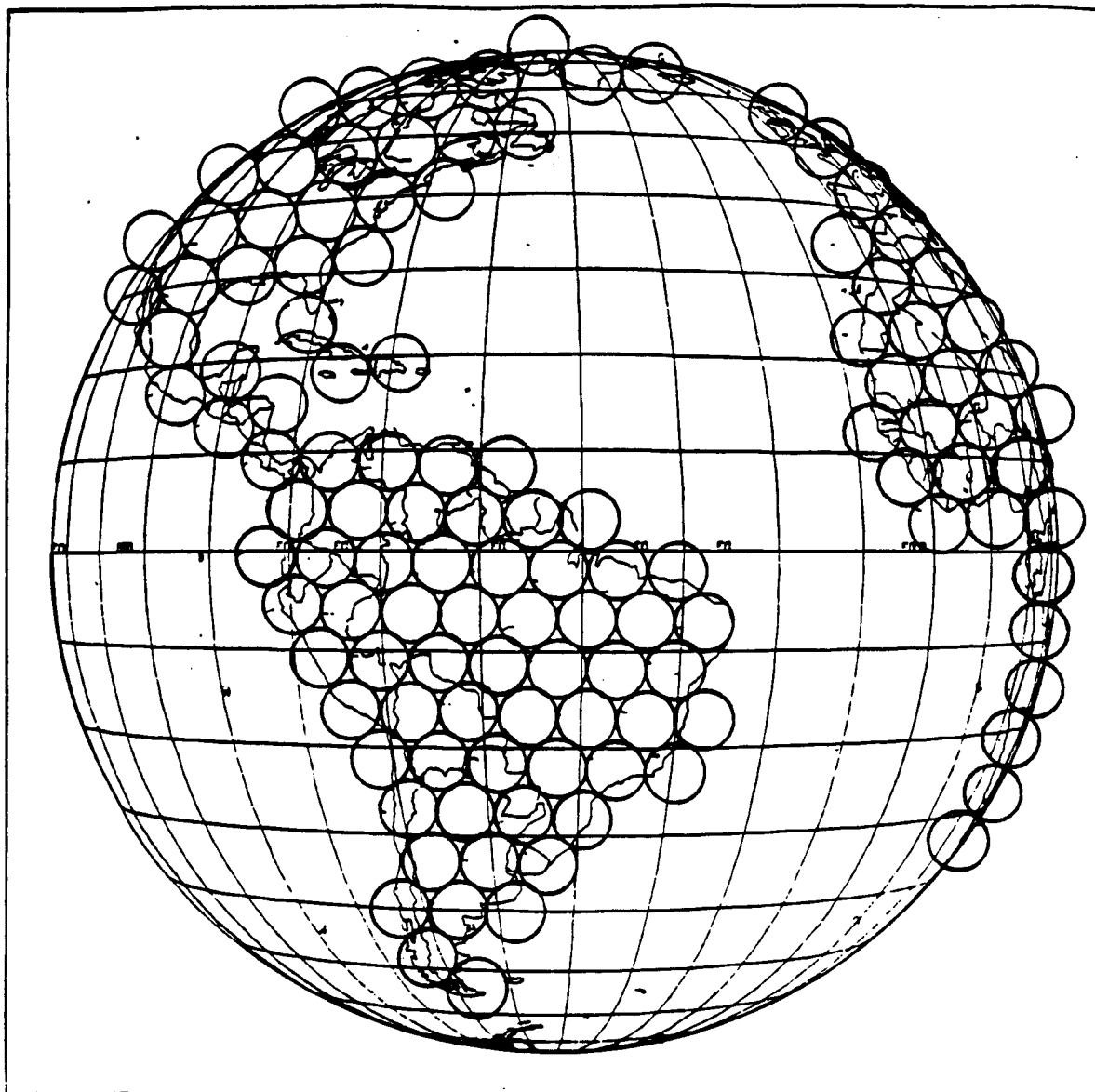


FIGURE 2.4 6x6 MSM SWITCH STATE TIME PLAN



**FIGURE 2.5 SPOT BEAM ANTENNA COVERAGE OF
ATLANTIC OCEAN BASIN COUNTRIES**

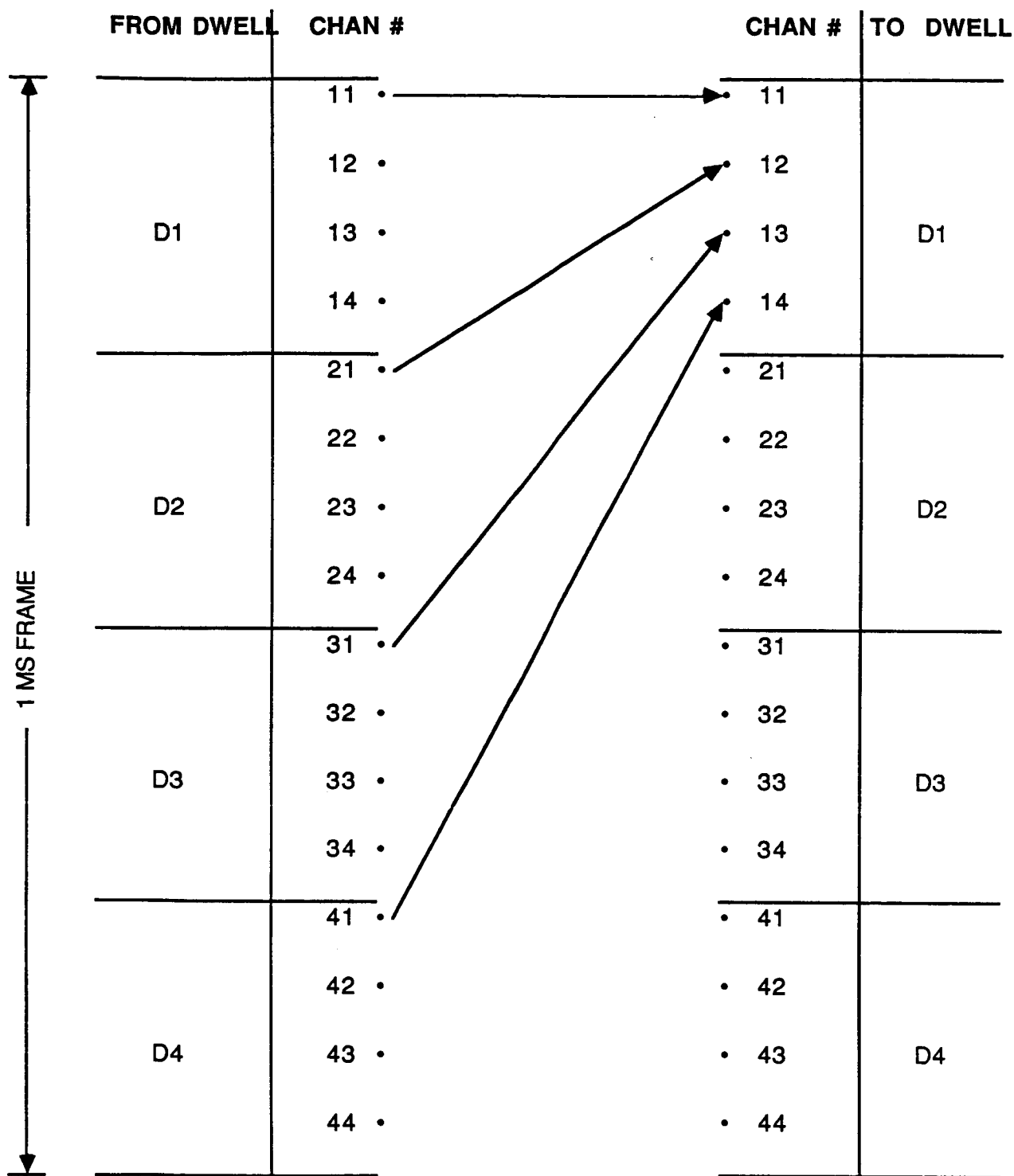


FIGURE 2.6
PREASSIGNED ROUTES FOR RANDOM ACCESS TDMA

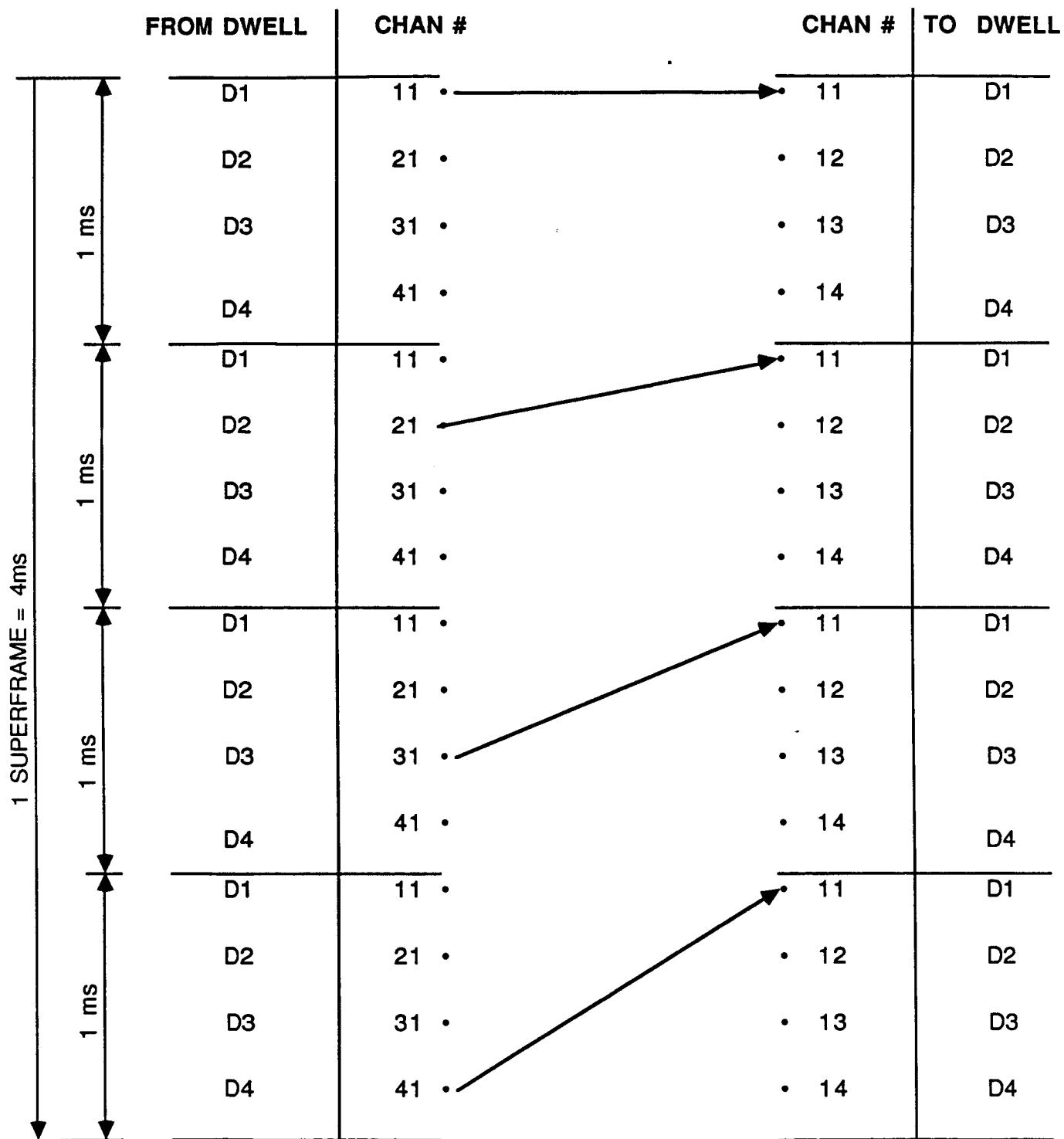


FIGURE 2.7
SINGLE DOWN BEAM DWELL

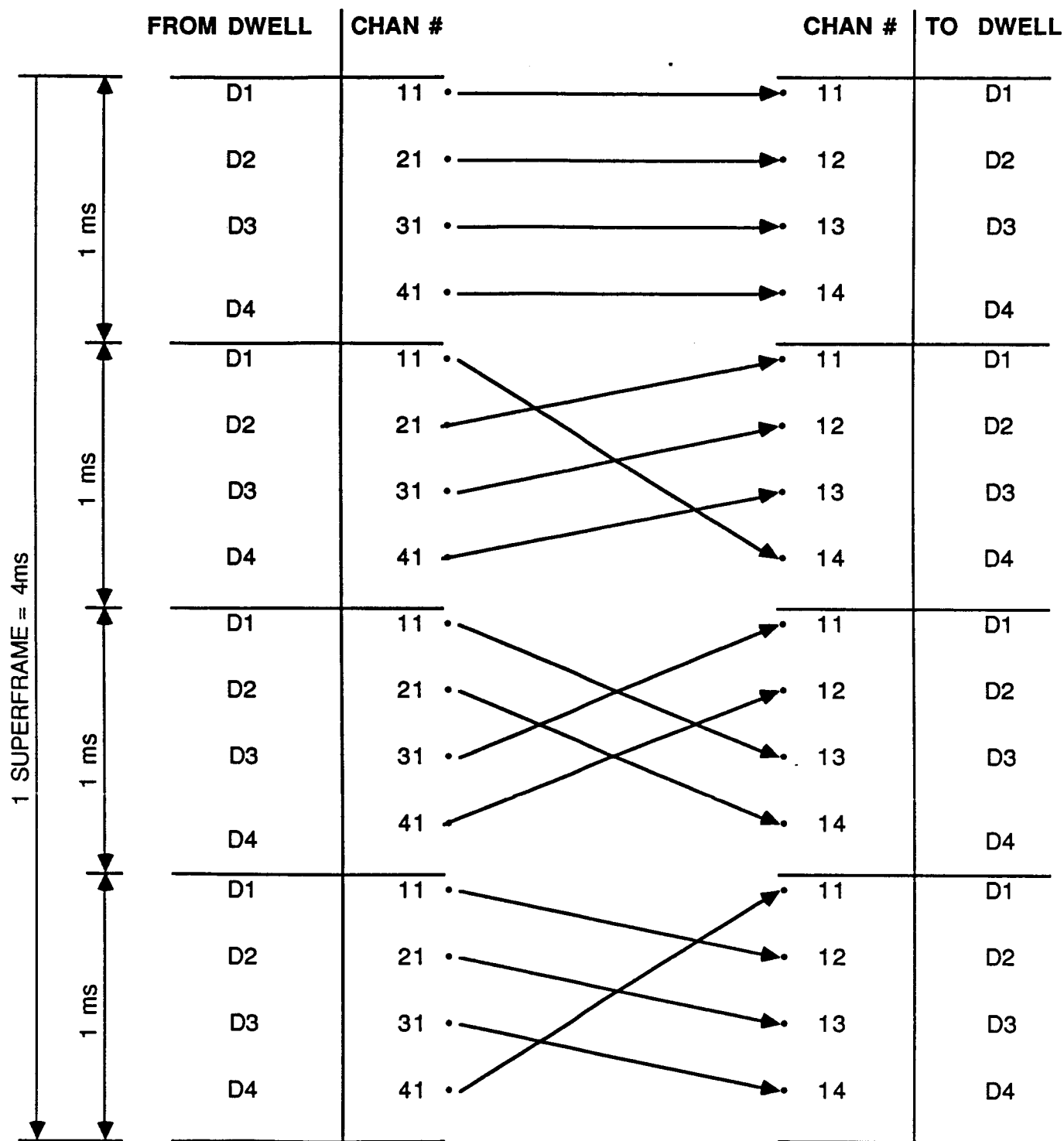


FIGURE 2.8
PREASSIGNED ROUTES IN SUPERFRAME
FOR RANDOM ACCESS

FIGURE 2.9

CIRCUIT SWITCHED DATA TRANSMISSION - CONTINUED

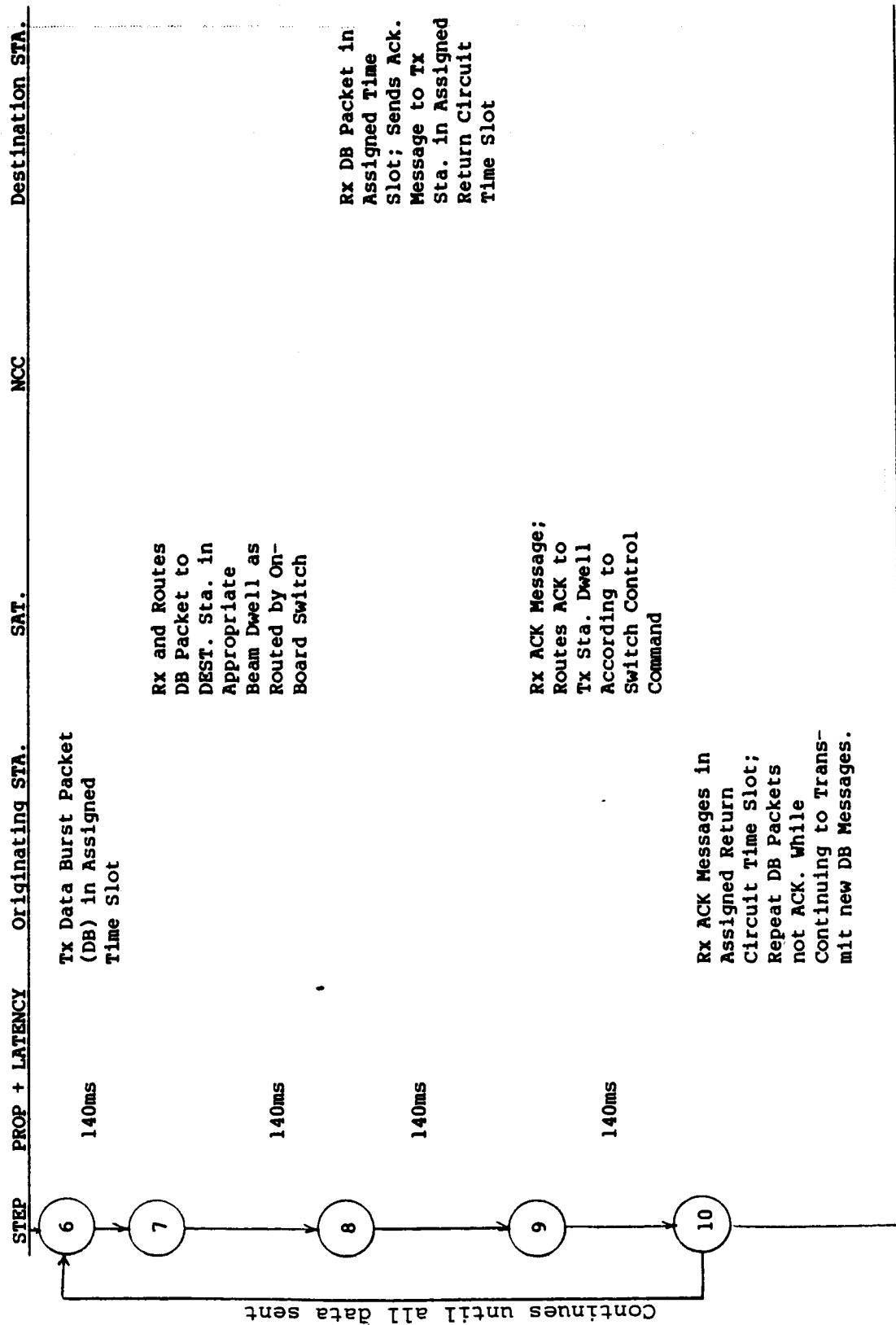


FIGURE 2.9

CIRCUIT SWITCHED DATA TRANSMISSION - CONTINUED

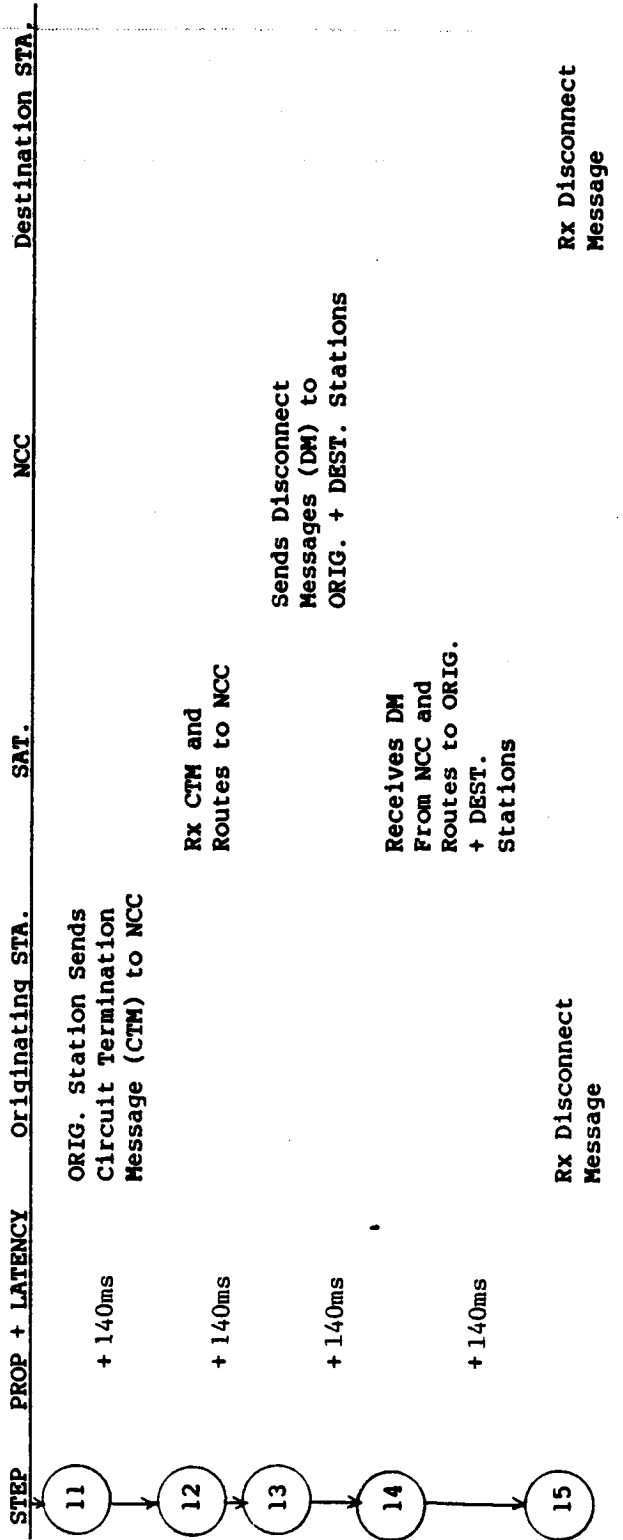


FIGURE 2.10

RANDOM ACCESS DATA TRANSMISSION WITH PREASSIGNED CHANNELS

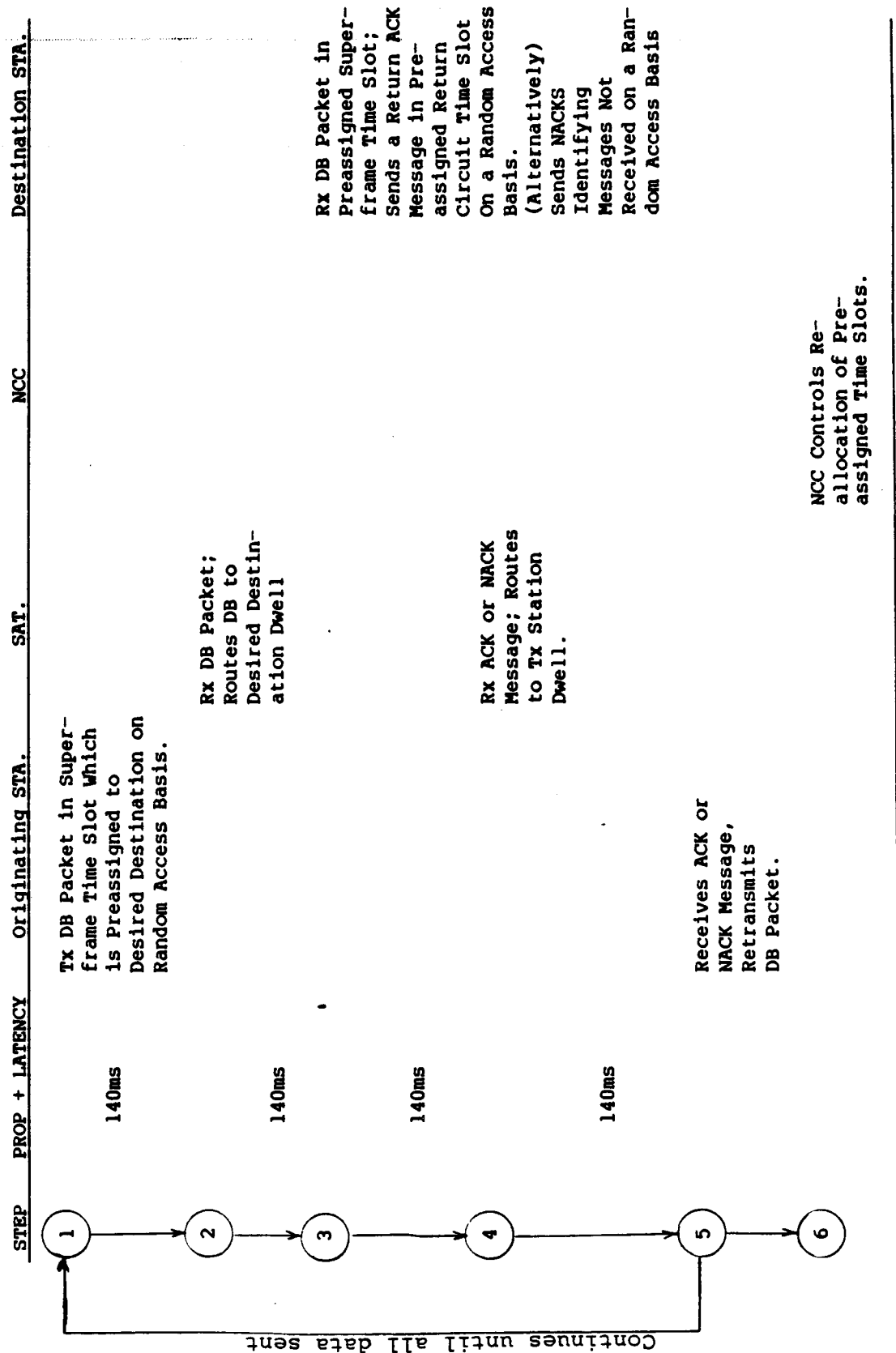
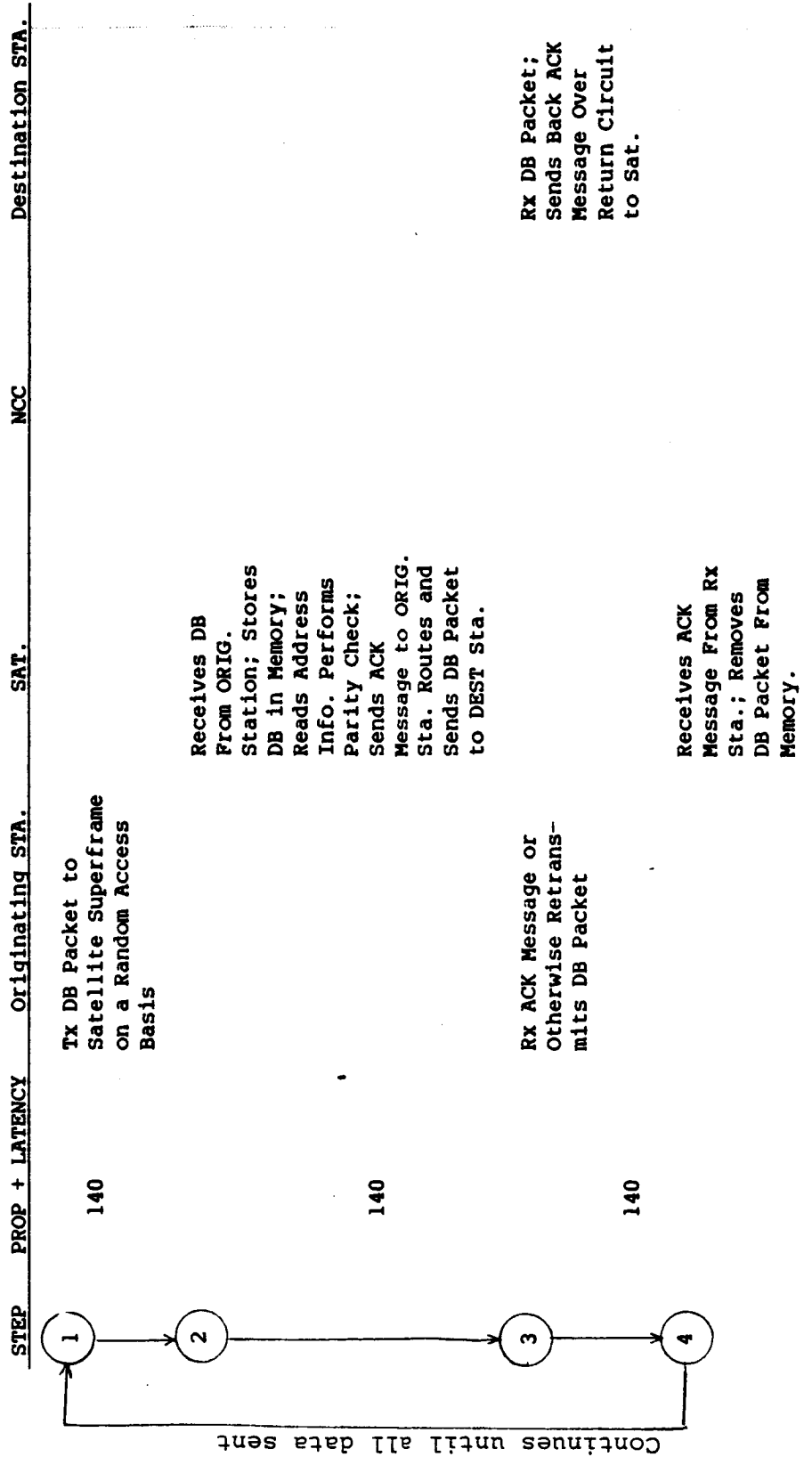


FIGURE 2.11

ON-BOARD PACKET NODE DATA TRANSMISSION



3. DESTINATION DIRECTED PACKET ON BOARD PROCESSING ARCHITECTURE

Two different onboard switching architectures have been identified, one using destination packet routing and the other using destination directed sub-burst routing. The destination directed packet approach encases each message in its own individual packet, each with its own destination address, while the destination directed sub-burst approach groups packets going to the same destination in a single sub-burst with one destination address for the group. The sub-burst approach provides increased efficiency in terms of TDMA frame utilization whenever more than one message is destined for a given destination. Increased frame efficiency permits the use of a shorter TDMA frame duration which reduces the size of the on board memory. This approach does however slightly increase the complexity of the earth station equipment since packets must be grouped according to their destinations before transmission. Conversely however, the onboard processor design will be slightly less complex since the packets arrive at the satellite grouped by destination instead of in a completely arbitrary fashion. Both architectures are described in greater detail in the following sections.

3.1 SYSTEM DESIGN

A description follows of a demand assignment satellite system that uses destination directed message packets with an onboard processing satellite in the manner described above. The system comprises terrestrial interfaces, earth stations, and the onboard processing satellite as illustrated in figure 3.1.

3.1.1 DEMAND ASSIGNMENT OF CAPACITY

Capacity is allocated by the onboard processor in response to demands of the earth stations. Circuits are assigned independently by each earth station processor within its current capacity allocation as established by the onboard network controller. Whenever the incoming demand on the terrestrial ports at a given earth station exceeds that of the current burst boundary (traffic burst boundaries), a request can be made directly to the onboard processor to increase its allocation. Alternatively, the onboard baseband processor will automatically adjust the capacity allocation by knowledge of the number of channels currently active at each earth station in the network.

If spare capacity exists, a reallocation will be made to a station

requiring additional capacity. If spare capacity does not exist, then the call will be blocked by busying out the terrestrial circuit of the calling party. Two examples of capacity reallocation are illustrated in figure 3.2. The time interval shown corresponds to the uplink frame which is subdivided into a number of uplink beam dwells. The first example shows the case when two bursts exchange capacity while the others remain unchanged. Note that this operation does not involve changing any of the beam dwell boundaries. The second example shows the case when all bursts change capacity. This does require changing the beam dwell boundaries. As can be seen, capacity reallocation may involve reducing the capacity of one or more bursts in the system which are not fully utilizing their current allocation(s) to increase the capacity of other bursts that have insufficient capacity.

3.1.1.1 Destination Addresses Packet Message

Within a given burst boundary allocation, terrestrial port to satellite time slot allocations are made by each earth station processor for each originating call. The uplink packet messages are mapped to the appropriate downlink time slots by the onboard processor by the process of reading the message packet header that contains the destination address and assigning the packet message to an available downlink time slot destined to the appropriate station. The packet messages are assigned to available downlink time slots on a random occurrence basis (in any order) only constrained by the current capacity allocation of the destination station.

By this approach, the function of the onboard processor is that of mapping uplink channels (time slots) into available downlink channels on a frame by frame basis under the control of the destination address information. In addition, the onboard processor must either accept requests directly from traffic stations or autonomously reassign capacity among the stations based on the current usage of satellite time slots. This process may be viewed as a simplified burst time plan change which involves changes to burst position and duration. Burst time plan changes are executed by synchronous burst time plan change procedures from on board the satellite. All other call setup elements such as port number to satellite time slot associations are carried out entirely by individual earth station control.

One consequence of using destination addressed message packet format for voice communications is in its inherent ability to serve as a digital speech interpolation (DSI) system. The incorporation of a speech

activity detector on each of the terrestrial ports enables packets to be sent only during the periods when speech activity is on the circuit, thus providing an effective DSI gain.

3.1.2 METHOD OF OPERATION

The steps involved in operating an onboard processing satellite that uses destination directed message packets is shown in Table 3.1. The basic operation of the system can be subdivided into three sets of procedures, namely: 1) call set-up, 2) call in progress and 3) call termination.

3.1.2.1 Call Set-up Procedure

The signalling information is decoded at each terrestrial port. When an off-hook condition is sensed on any terrestrial port, a call set-up message (CSM) is sent via any free satellite time slot. A destination address header is added to the packet which identifies the destination earth station and the originating terrestrial port and earth station. The data packet is assigned under local earth station control to any available time slot within the station's traffic burst capacity allocation.

The transmit time slot assignments can be considered as terrestrial port to satellite channel mappings which are performed by the transmitting earth station using destination addressed packet messages. Message packets will normally be assigned and reassigned to maintain channel loading of the lower numbered satellite channel time slots, i.e. those located closest to the leading edge of the traffic burst. This procedure is sometimes referred to as "herding" of the channels because they are confined to the leading portion of the burst. This procedure can simplify the burst boundary reallocation procedure especially for bursts which will be reduced in duration (capacity).

When the satellite processor receives the CSM, it decodes the packet header and routes the entire message to an available time slot destined to the addressed earth station. The onboard processor maps uplink message packets to downlink satellite channels as shown for the example given in figure 3.3. The onboard processor is free to select any available downlink time slot destined for the addressed station. Normally the processor will assign new channels and reassign existing channels to the lower numbered time slots to confine the channels toward the leading edge of the burst in a similar manner to what is done for the uplink assignments which are made at the earth stations. If downlink capacity is not available,

TABLE 3.1 System Operation for Destination Addressed Message Packet System

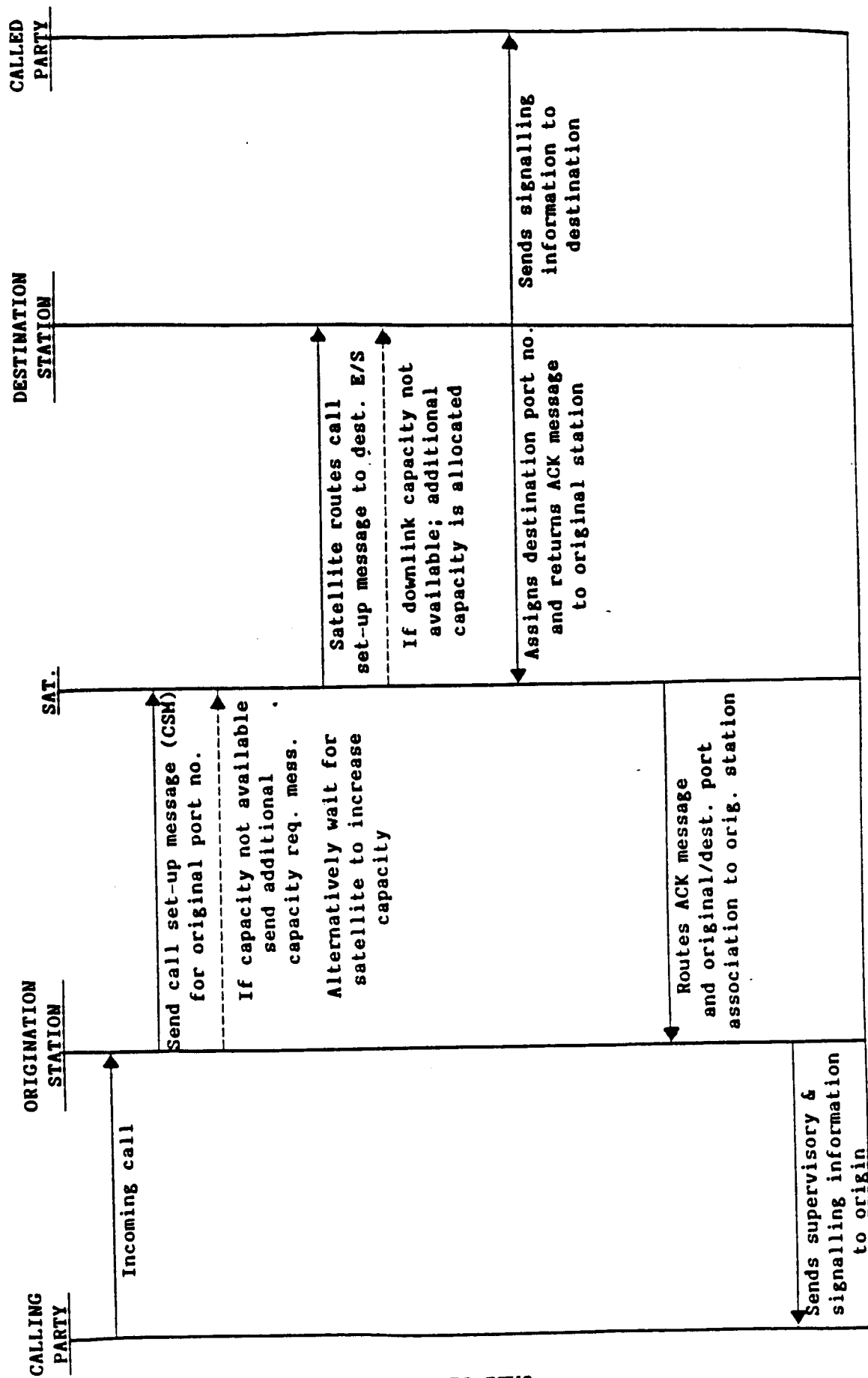


TABLE 3.1 System Operation for Destination Addressed Message Packet System (con't)

CALLING PARTY		ORIGINATION STATION	SAT.	DESTINATION STATION	CALLED PARTY
CALL IN PROGRESS		Active circuit message and supervisory signals	Active circuit is assigned to available uplink , satellite channel using	Satellite routes each uplink packet to appropriate downlink carrier and assigns it to an available downlink satellite channel	Active circuit message and supervisory signals
		Active circuit message and supervisory signals	Satellite routes each uplink packet to appropriate downlink carrier and assigns it to an available downlink satellite channel	Active circuit is assigned to available uplink satellite channel	Active circuit message and supervisory signals
On-hook at either end signals call termination		Sends call termination message (CTM)		Sends (CTM)	Normal supervisory disconnect signal
Normal disconnect ACK		Sends CTM ACK		Sends CTM ACK	Normal disconnect acknowledgment
CALL TERMINATION					

CALL IN PROGRESS

CALL
TERMINATION

additional capacity will be allocated by the onboard processor. This is done by notifying via the reference burst all affected stations of the changes to their burst position and duration. The onboard processor must also adjust beam dwells in accordance with these changes in the burst boundaries.

At the destination earth stations, an assignment is made of the received CSM to an available terrestrial port. At the time of call setup, normal signalling information is sent to the called party. In addition a CSM ACK is sent back to the originating earth station giving the association of the originating port to the destination port mapping.

For the case when satellite capacity is not available at the originating earth station, either a capacity request message (CRM) is sent over the order wire to the onboard processor to increase the station's capacity allocation or if the onboard processor is equipped to perform capacity reassignment by observing the number of channels that are active at each earth station within the network, the station waits for more capacity. Two allocation schemes are possible during the time lapse to assign additional capacity. The first is to block the call and allocate additional capacity for future voice calls. The other method is to queue the call until the reallocation is made. The reallocation delay can probably be kept to less than a few seconds and therefore the amount of memory required and post dialing delay will be minimal. This approach can be used both at the originating earth station for uplink satellite channels and onboard the satellite for downlink satellite channels.

Normal forward and backward signalling and supervisory signals are sent to both the calling and the called parties.

3.1.2.2 Call In Progress Procedure

Upon completion of the call set-up procedure, the active circuit message is sent over the circuit via destination addressed message packets. Each message packet contains a header with a destination (or origination) address and the call's destination (or origination) terrestrial port number. This will be described in detail in section 3.1.2.4. As described in the foregoing, the uplink satellite channel which is assigned to carry a voice message packets changes from frame to frame as a function of the happenstance of the activity on the voice ports. Also message packets are assigned to the lowest numbered channels in order to 'herd' the active channels to the leading edge of the traffic burst. Each downlink satellite circuit may also change from frame to frame under control of the onboard processor for the same reason.

NAS3-24886 FINAL REPORT

All message packets addressed to a particular destination address will appear in their order of arrival on the incoming port assigned to the call. When a message packet is not received due to a speech pause, an idle signal will be sent on the terrestrial connection terminating that port.

3.1.2.3 Call Termination

When either party hangs up, an on-hook signal is detected at the earth station which then initiates the transmission of a call termination message (CTM) directed to the corresponding earth station. This message is routed to the destination earth station by the onboard processor. The corresponding earth station receives the CTM and signals the corresponding party and also sends a CTM ACK to the corresponding earth station. Both stations send the normal disconnect signals to the end parties.

3.1.2.4 Mapping Functions

The entire DAMA/DSI system can be viewed as a three step mapping operation as illustrated in figure 3.4. Terrestrial ports are mapped into satellite time slots (channels) under independent earth station control by assigning destination addressed message packets to the satellite channels. These mappings can change on a frame by frame basis for the following reasons: 1) to maintain confinement of the channels to the leading portion of the burst as calls terminate and 2) to assign active speech to available channels on a random basis. Because of the packet header, no special assignment channel is needed on the receive side to demap the channels. On the transmit side, any active channel may be placed onto any available satellite time slot. This process is viewed as the transmit terrestrial port to satellite channel mapping. On the receive side, the received message packets carried on the satellite channels are demapped using the packet header which gives the destination terrestrial port number.

The third mapping function is performed onboard the satellite where uplink satellite channels are mapped into available downlink satellite channels. The only system constraint imposed on this mapping is that the downlink channel selected is available and that it is directed to the intended earth station, i.e. the one given in the packet header. This is equivalent to requiring that the packet is placed onto the proper downlink hopping beam dwell interval.

Figure 3.5 more precisely illustrates this three step mapping procedure for the destination directed packet system:

- 1) the call originating station maps originating terrestrial ports (TPos) into uplink satellite channels (SCUs),
- 2) the on-board processor maps the uplink satellite channels into downlink satellite channels (SCDs),
- 3) the call destination earth station maps downlink satellite channels into destination terrestrial ports (TPds).

A packet comprises a header followed by a message. Figure 3.6 shows the format of the packet header for a destination directed packet. Each packet header consists of a station I.D. number and a station terrestrial port number. Taking for example an 8 bit station I.D. and 8 bit station port number, the header defines 256 station I.D.s and 256 station port numbers. Another arrangement could be a 7 bit station I.D. and 9 bit port number to define 128 stations each serving 512 terrestrial ports. Taken together, these 16 bits define 65,536 unique terrestrial port numbers. As will be seen later, the format of the packet header for the destination directed sub-burst approach only requires the station port number and is therefore more frame efficient.

3.1.2.5 Detailed Call Set-up Procedure

The signalling information is decoded at the originating station. When an off-hook condition is sensed at the originating station, a terrestrial port (TPo) is assigned and a call set-up message (CSM) is sent. A link must be established between TPo and a port at the destination station TPd via the onboard satellite switch. The TPo , TPd associations form maps used to direct the calls. The procedure does not require storage of connectivity maps and their associated memory onboard the satellite. The procedure for doing this for both the destination directed packet (packet routing) and the destination directed sub-burst (sub-burst routing) approaches is described in Table 3.2 and Figures 3.7 and 3.8.

3.1.2.6 Detailed Call in Progress Procedure

Upon completion of the call set-up procedure, the active circuit voice or data messages are sent over the circuit via the destination directed message packets using the TPo , TPd associations established by either of the two methods described in Table 3.2. The message portion of each packet contains the active circuit voice or data message bits.

TABLE 3.2 CALL SET-UP PROCEDURE

<u>CHANNEL MAPPING</u> (See Figure 3.6)	<u>PACKET ROUTING</u> (See Figure 3.7)	<u>SUB-BURST ROUTING</u> (See Figure 3.8)
1. TPo to SCU	The call originating station sends a CSM packet in a free SCU within its burst allocation. The packet header identifies the call's TPo No. plus the destination station's I.D. (see figure 3.7A).	The call originating station sends a CSM packet in a free SCU in a multi-packet destination directed sub-burst within its burst allocation. The sub-burst header contains the destination station's I.D. and the number of packets within the sub-burst (See figure 3.8A). The CSM packet begins with a header identifying the TPo No.
2. SCU to SCD	The onboard processor reads all packet headers and routes each packet to a SCD within the burst designated to the destination station. The onboard processor replaces the destination I.D. within the packet header with the originating station's I.D. (See figure 3.7B).	The onboard processor reads all sub-burst headers and routes each sub-burst to the required number of contiguous SCDs within the burst directed to the destination station. The onboard processor replaces the destination I.D. in the sub-burst header with the originating station's I.D. (See figure 3.8B).

NOTE:

The terms "originating" and "destination" are used in the description of the process to distinguish the difference between the station originating the call set-up and the station responding to the call set-up. They are not part of the information used or stored. There is no difference between a TPo and TPd . These designations are used for only convenience of description.

TABLE 3.2 CONTINUED

3. SCD to TPd	The destination earth station reads the CSM packet header and assigns and stores in a map a TPd to TPo association.	The destination earth station reads each sub-burst header and CSM packet header and assigns and stores in a map a TPd to TPo association.
4. TPd to SCU	The destination station sends a return CSM packet in a free SCU within its burst allocation. The packet header identifies the TPd No. plus the originating station I.D. (See figure 3.7C).	The destination station sends a return CSM packet in a free SCU in a multi-packet destination directed sub-burst. The sub-burst header contains the originating station's I.D. and the number of packets within the sub-burst. The return CSM packet begins with a header identifying the TPd No.
5. SCU to SCD	The onboard processor reads all packet headers and routes each packet to a SCD within the burst directed to the originating station. The onboard processor replaces the originating station's I.D. with the destination station's I.D.(See figure 3.7D).	The onboard processor reads all sub-burst headers and routes each sub-burst to the required number of contiguous SCDs within a burst directed to the originating station. The onboard processor replaces the originating station's I.D. with the destination station's I.D. (See figure 3.8D).

TABLE 3.2 CONTINUED

6. SCD to TPo	<p>The originating station reads the return CSM packet header and assigns and stores in a map the TPd to TPo associations. Multiple new assignments are handled by the convention of assigning TPos to TPds in ascending order (lowest No. TPo to lowest No. TPd).</p>	<p>The originating station reads the sub-burst header and the CSM packet header and assigns and stores in a map the TPd to TPo associations. Multiple new assignments are handled by the convention of assigning TPos to TPds in ascending order (lowest No. TPo to lowest No. TPd).</p>
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NOTE:

As a consequence of the above process, packets identified in their header as originating on port TPo-I at the originating station will always be sent to the destination station's port TPd-J and vice versa until the call is terminated.

3.1.2.7 Detailed Call Termination Procedure

When either party hangs up, an on-hook signal is detected at the earth station which then initiates the transmission of a call termination message (CTM) in the packet format directed to the corresponding earth station. Either station may originate the call termination procedure. Both stations send normal disconnect signals to the switches serving them and delete the TPo to TPd associations by returning them to the pool of unused TPs. The CTM messages are routed in the same manner as the CSM messages described in Table 3.2.

3.1.3 PACKET FRAME EFFICIENCY

Figures 3.9 and 3.10 give calculations of frame efficiency for the packet routing and sub-burst routing approaches assuming a message

channel transmission rate of 32 kbits/s. For the packet routing approach, Figure 3.9 shows that to achieve a frame efficiency of about 94% (frame efficiency loss of 6%) requires a frame period of about 16 ms. Figure 3.10 shows that the sub-burst routing approach provides approximately the same frame efficiency with an 8 ms frame period. This represents approximately a 50% reduction in the required frame period which will translate into the same percentage of savings, i.e. 50%, in on-board memory. These frame efficiency estimates do not include the fraction of the frame needed for TDMA reference bursts, network control bursts and guard times.

3.1.4 DIGITAL SPEECH INTERPOLATION

As described above, if the system incorporates the use of digital speech activity detectors at each terrestrial port, digital speech interpolation (DSI) is automatically incorporated into system operation. By sensing speech activity, message packets need only be transmitted during periods of time when the circuit is active. This permits the satellite channels to be shared among multiple voice conversations.

Normally, the DSI gain depends on the number of channels carried by an earth station on a given link. The larger the link, the higher the gain. For very thin route links, e.g., < 24 channels, the DSI gain may be considerably less than 2.0. For this system however, the ensemble size is not limited by the size of the link or the number of channels in a given burst, but by the total capacity carried in a given beam dwell. This may be composed of many links each carrying only a few channels. In a conventional DSI system, the DSI gain would be low. However, if the burst boundaries change to meet changes in instantaneous circuit demand, the equivalent DSI gain will be higher since the total circuit ensemble will be composed of the total channels within the beam dwell and not limited by the number of channels on any given link.

3.1.5 ACQUISITION AND SYNCHRONIZATION CONTROL

The frame structure shown in figure 3.11 comprises the control and traffic fields. In the downlink frame, the control field distributes reference bursts to the traffic terminals, whereas in the uplink frame, the control field provides request channels for acquiring traffic terminals. The traffic field accommodates the traffic which is nominally one uplink and one downlink burst per traffic terminal.

3.1.5.1 Reference Bursts

The reference bursts are transmitted in the control field at the beginning of the frame. One reference burst per beam dwell is transmitted as shown in figure 3.11 for the case of N beam dwells. The reference bursts are transmitted into each beam dwell even in those in which traffic is not currently being carried. As will be explained, this provides the control and timing information to any terminal desiring to enter the frame and does so without significantly reducing the frame efficiency. Frame efficiency will be examined in section 3.1.6. The major advantage of placing the reference bursts at the beginning of the frame is that they will remain fixed within the frame during burst time plan changes, which reduces the information needed to implement the burst time plan while also simplifying the terminal design.

Within a given beam dwell, each traffic terminal is addressed by a single reference burst, once every 128 frames which is equal to one superframe (1.024s). Figure 3.12 shows the case of an 8 ms frame which permits addressing up to 128 traffic terminals per beam dwell.

The reference burst format is given in figure 3.13 which comprises the preamble, terminal short number (TSN), burst time plan (BTP) and the control and delay channel (CDC). With the exception of the preamble, the reference burst is rate 1/2 encoded. The preamble is used for carrier and bit timing recovery as well as unique word detection. The TSN identifies the traffic terminal in the beam dwell that is being addressed. The seven coded bits permit addressing up to 128 traffic terminals.

The BTP gives the terminal's transmit and receive burst position, and the associated burst duration (length) which is the same for both transmitted and received bursts. The transmit burst position (TTo), the receive burst position (RTo) and the burst duration (DT) are given in units of single 32 kb/s voice channels. There are a total of 3750 such time slots in one TDMA frame, and therefore requires a 12 bit code (12 symbols if rate 1/2 encoded).

The CDC gives the control code and transmit delay for the addressed terminal. The control code governs the status of the traffic terminal, by issuing for example, a 'do not transmit code', or by authorizing the terminal to enter the acquisition or synchronization phase. The transmit delay (Dn) is used by the terminal with the BTP information to determine its transmit side timing. The 19 symbol code consists of 17 symbols for Dn and 2 symbols for a parity check code. The 17, rate 1/2 encoded, bits are adequate to correct for a 131,072 symbol offset. This information is

used by the terminal for performing both frame acquisition and synchronization. For acquisition, the transmit delay is estimated by the onboard processor from a knowledge of the satellite's position relative to the acquiring traffic terminal. For synchronization, the value of transmit delay is refined based upon the burst's observed time of arrival at the satellite relative to the expected target position. Details of the acquisition and synchronization procedures are given in section 3.1.5.3.

3.1.5.2 Uplink Request Bursts

The uplink control field provides uplink beam dwells as shown in figure 3.11 which are coincident at the satellite with the downlink beam dwells that are used for reference burst transmission. The uplink dwells permit any station to request satellite access even those stations that are located in a beam dwell region that is currently not carrying traffic. As will be seen later, the uplink control field which is approximately equal in duration to the downlink control field will not significantly reduce the overall frame efficiency and therefore the beam dwells in the control field can be permanently assigned. Any terminal requesting satellite access will transmit a request burst (RQB) during its beam dwell and within its allocated frame within the superframe.

The RQB shown in figure 3.14 consists of 13 contiguous sub-bursts each of which comprise a carrier and bit timing (CTBR) sequence, unique word (UW) and the burst number (BN). The RQB is transmitted by an acquiring terminal in its allocated frame within the uplink superframe. As in the case for the reference bursts, there is a 1s superframe which accommodates up to 128 traffic terminals per beam dwell. An acquiring terminal will transmit in the time slot which corresponds to its terminal short number.

The burst is sufficiently long (884 symbols) that at least one of the 13 sub-bursts will fall within a 136 symbol uplink dwell acquisition aperture at the satellite. Since the sub-bursts are numbered, the onboard processor can determine the amount that the RQB must be advanced or retarded in time in order to move it to its nominal position within the acquisition aperture. Details of the acquisition and synchronization procedures follow in Section 3.1.5.3.

3.1.5.3 Acquisition and Synchronization Procedures

The process of terminal acquisition is performed using an open loop approach which uses a knowledge of the satellite's position with respect

to the location of the acquiring terminal to compute its transmission delay . It is assumed that the position of the satellite is known to better than ± 1.0 km from its actual position. This corresponds to a maximum uncertainty of about ± 400 symbols or 800 symbols peak-to-peak. Since the beam dwells can be arranged so that the RQB will not cause interference into another beam dwell due to the spacial isolation of the antenna beams, the RQB may be much longer than its allocated acquisition beam dwell. In this system the RQB is chosen to be slightly greater than the satellite's position uncertainty (800 symbols peak- to peak). In this way, one RQB sub-burst will always be detected at the satellite within an uplink dwell aperture. This aperture as shown in figure 3.15 is chosen to equal 2 times the length of the sub-burst (136 symbols).

The unique word aperture is initially opened to a window width equal to the sub-burst length plus one symbol or 69 (68+1) symbols. Upon detection of the unique word, the aperture is reduced to a window width that is equal to the unique word length and positioned at the instant of the observed unique word detection. This step is performed to reduce the probability of false unique word detection.

The uplink and downlink superframes are aligned at the satellite. To transmit the request burst , the terminal receives the reference burst directed to it and decodes the BTP and CDC. From this information, the terminal can transmit its RQB. The control code will normally contain a 'request burst authorized' code together with the values of D_n and TTo which will place the RQB in its proper acquisition slot. Upon proper reception of the RQB, the reference burst will change the control code to 'acquisition authorized'. The reference burst will also send the TTo and refined value of D_n which will permit the terminal to place its burst (less traffic) into its nominal position in the traffic field. The onboard processor must ensure that adequate capacity and beam dwell has been allocated to this terminal. Upon reception of the acquisition burst in its proper position in the traffic field, the reference burst will send the "Synchronization Code" to the terminal with a limited amount of capacity allocation (DT). If at any time the traffic burst moves outside of a specified aperture, for example, by more than ± 8 symbols, the reference burst control code will change to "Do Not Transmit" which takes the traffic terminal off the air.

3.1.6. OVERALL FRAME EFFICIENCY

The loss in frame efficiency caused by the presence of the control field is governed by the uplink frame since the uplink dwell that is needed

for the acquisition aperture (136 symbols) is slightly larger than the dwell that is needed on the downlink (128 symbols plus burst guard time). Based upon these considerations, the frame efficiency loss due to the control field is:

$$L = N(G_d + L_a)/F$$

where: N = number of beam dwells
 G_d = beam dwell switching guard time
 L_a = acquisition aperture (136 symbols)
 F = frame length

The loss in frame efficiency is computed for a frame length of 8ms (480,000 symbols) and 16 ms (960,000 symbols) and for N = 50 and 100 beam dwells. The results for two beam dwell switch implementations: G_d = 64 symbols for ferrite switches (today's technology) and G_d = 16 symbols for pin diode switches (advanced technology) are

FRAME LENGTH (F)	8 ms		8 ms		16 ms		16 ms	
BEAM DWELLS (N)	100	100	50	50	100	100	50	50
DWELL GUARD TIME (G _d)	16	64	16	64	16	64	16	64
FRAME EFF. LOSS (L%)	3.1	4.2	1.6	2.1	1.6	2.1	0.8	1.0

The frame efficiency loss due to guard times and preambles in the traffic field can be computed as follows:

$$L = [n(G_b + P_b) + N(G_d)]/F$$

Where: n = number of traffic bursts in the frame
 G_b = guard time symbols between bursts
 P_b = preamble symbols
 N = number of beam dwells in the traffic field
 G_d = beam dwell guard time.
 F = frame length

As an example, take n = 256, G_b = 8 symbols, P_b = 64 symbols, N = 50, G_d = 16 symbols and F = 8 ms (480,000 symbols) and 16 ms (960,000 symbols). The resulting frame efficiency loss due to the guard times and preambles in the traffic field is equal to about 0.8% for the 8 ms frame

and about 0.4% for the 16ms frame respectively.

Based upon these computations the frame efficiency can be determined for the overall system. The frame efficiency loss consists of the three elements: 1) control field loss, 2) packet header loss, and 3) guard time and preamble loss in the traffic field. The frame efficiency loss due to the packet headers was previously seen to be about 4% and 8% for 16 ms and 8 ms frames respectively. Making the appropriate additions to these, the overall system frame efficiency loss is estimated at $1.6 + 8.0 + 0.8 = 10.4\%$ for an 8 ms frame and $0.8 + 4.2 + 0.4 = 5.4\%$ for a 16 ms frame. The corresponding overall frame efficiencies are thereby 89.6% and 94.6% for the 8 ms and 16 ms frames respectively.

3.1.7 ON BOARD SWITCH ARCHITECTURES

It has been shown that for a destination directed packet system to achieve a high TDMA frame efficiency a fairly long frame period is needed. A 16 ms frame period will provide an overall frame efficiency of better than 91%. A frame period of this length requires a large amount of on board storage memory. For example, a single 120 Mbit/s TDMA carrier would require 1.9 Mbit of on board memory to store one frame of data. This is 16 times greater than that needed for a 1 ms frame, as used in the ACTS System. Because of this, architectures need to be examined which can reduce the on board memory requirement. To this end, two classes of on board switch architectures are examined, namely those that incorporate separate input/output memories and those that use a single unified memory.

3.1.7.1 Separate Input/Output Memory Architecture

The separate input/output memory architecture is shown in figure 3.16 which incorporates a space switch to route channels from a given uplink (input) memory to a given downlink (output) memory. The switch serves to route channels from various uplink memories to various downlink memories thereby reformatting the uplink channels into the downlink channels.

Each input memory (pingpong) is associated with an individual demodulator or set of demodulators. Normally a demodulator or a set of demodulators is permanently assigned to a given uplink antenna beam. This beam may either be fixed or may hop among several beam dwell regions. The downlink memories (pingpong) are associated with individual

modulators. These modulators normally are permanently assigned to a given downlink antenna beam. As for the uplink beams, the downlink beams may either be fixed or may hop among various beam dwell regions.

The ping pong action of the input memories stores the current frame of incoming channels while playing out channels from the previous frame into the space switch. The channels may be reordered in the input memories to eliminate contention between two or more input memories for routing to the same output memory. This reordering of the channels according to their destination also minimizes the number of switch states that are needed.

The pingpong action of the output memories stores the switched channels of the current frame while playing out the channels of the previous frame to its associated demod for downlink transmission. The use of separate input and output pingpong memories creates a latency of two frames in passage of the information through the system. Downlink channels are read and transmitted in a TDM form on a single carrier per beam. Alternatively, downlinks may use multiple carriers per beam each having the same or different bit rates. This may be preferred for mobile services operating in a single wide coverage beam for CONUS.

The separate input/output memory architecture with a space switch is what is being used in the ACTS System. The ACTS incorporates a 2X2 baseband switch to route the traffic between two uplink hopping and two downlink hopping beams. Although the ACTS system incorporates circuit switched operation, this basic architecture could be used in a message or packet switched scheme. This however will not likely be the most promising approach due to its relatively high on board memory requirements. The description of a unified memory architecture which reduces the on board memory requirements is presented in section 3.1.7.2.

3.1.7.2 Unified Memory Architectures

A unified pingpong memory architecture that uses destination addressed packet switching is shown in figure 3.17. This architecture can reduce the onboard memory requirements by a factor of two from that needed for the separate input/output memory architecture described above. A single pingpong memory is used in the baseband processor with each half serving as either the input or output memory with the roles alternating every frame. The input memory aggregates the uplink channels of the current frame while the output memory is read out for downlink

transmission of the channels from the previous frame.

For the case of destination addressed packet switching, each uplink channel is comprised of a packet which contains a header that gives the destination address. The destination addresses are written into the control processor as they arrive. These are used to establish the read order of the memory when it switches to its output role. This is necessary so that when the packets are read out they are routed to the proper modulator for transmission to the appropriate downlink beam dwell.

The time required for determining the read order of the output memory can be extended through the concept of storage in space. For example, if the packet header is sent one frame ahead of the associated message, then there will be one additional frame allowed for control processing. While the packet header is being processed, the message information is literally stored in space.

As mentioned above, the amount of on board memory is halved since one set of pingpong memories can be eliminated. In addition, the space switch and its associated controller are eliminated. Since this architecture uses a common memory, the input and output speed is higher by the ratio equal to the number of parallel memories used in the separate input/output memory architecture.

A further reduction in the size of the on board memory is made possible by replacing the pingpong memory with a dual port memory in the unified memory architecture. This is depicted in figure 3.18 where it can be seen that uplink channels are written into the dual port memory and stored "in place" until they are read out for transmission by their corresponding modulator. The concept of storage in space can also be used with the dual port memory to increase header processing time.

Although the memory size can be halved with respect to the unified pingpong memory and quartered with respect to the separate input/output memory architecture, the speed is twice that needed for the pingpong architecture. The control processor performs the same functions as for the unified pingpong architecture.

The "in place" operation of the dual port unified memory is illustrated in figure 3.19 where each new input channel (packet) is written into the memory location that has just been vacated by a packet from the previous frame. The example shows the case of four packets per frame and four on board memory locations. In the figure data is written into the memory from the left and read out to the right, i.e. data flows from the left into the memory and out to the right. Nine frames of data are shown, where the frame is designated by the number associated with each data

packet. At the top of the figure, the memory starts in the empty condition. At this point, the first frame of data (A1,B1,C1,D1) is being stored in space. In the second frame the data is stored in the on board memory. Data is read out for the first time in the third frame. In this example, the data is read out in the sequence of B,D,A,C, however it can be written out in any sequence. Each new input packet is written into the memory location of the just vacated memory location. Because of this process the packets can be seen to be stored in any of the four memory locations, independent of their origin or destination. The method of implementing this architecture is given in section 3.2.

3.2 BASEBAND PROCESSOR IMPLEMENTATION

Section 2 of this report described the advantages and call processing procedures of a destination-directed packet switching approach. This was expanded upon in section 3.1 where the protocols were defined for the on-board switch architecture. This section will describe three specific destination-directed onboard switch architectures and present block diagram level hardware implementations, showing the various performance, chip-count, and power trade-offs for each. The first architecture is similar to that of the ACTS, employing separate uplink and downlink memories coupled by a space switch. The other two architectures are based on a single, large "unified" memory utilizing storage in space.

3.2.1 SEPARATE INPUT/OUTPUT MEMORY ARCHITECTURE

Figure 3.20 shows the basic elements of the Separate Input/Output Memory architecture. Three individual upbeams and downbeams are shown although it could be expanded to many more. Individual demodulated packets arriving on upbeams A, B, and C are buffered in their associated input memory in their order of arrival. The input buffers must be large enough to store an entire frame of packets. The packets are then routed to the proper downbeam destinations through the 3 X 3 switch matrix. It will be assumed throughout this section that each packet contains its own destination address included in its packet header. The packets are buffered in the appropriate downbeam output memories before being remodulated and transmitted to the Earth. The memories could be either pingpong or dual-port arrays. This will be discussed in the hardware implementation section later.

Figure 3.20 represents the traditional time-space-time architecture as used in the ACTS. One important difference, however, is that the packets are message switched rather than circuit switched. Packets destined for various downbeams may arrive in any order within a given TDMA burst and do not have to be sent in any predefined sequence synchronized with the satellite network. The on-board processor will reorder the packets after they have been buffered in the input memories. The packets arriving in Figure 3.20 are labelled according to their destination addresses. The subscripts do not carry any significance except to illustrate the sequence of packets flowing through the architecture. Each packet is stored in a

unique memory address. For example, input memory for upbeam A occupies addresses 00 through 06. Each beam must have its own unique memory since all beams function simultaneously.

Note that the input packets are stored in their order of arrival. The packets must be reordered in coordination with the switch matrix so that for each switch state the packets sent to switch ports 1, 2, and 3 arrive at the appropriate switch output ports 4, 5, and 6. For a 3 X 3 switch as shown, there are a total of $2^9 = 512$ possible switch states. The computational load in calculating the proper switch states in real time (on a frame by frame basis) for a given frame of destination-directed packets would be enormous even for a simple 3 X 3 switch. As a result the switch states must be precomputed on-board based on the anticipated traffic between each pair of beams. This is a reasonable assumption for voice traffic which is only slowly time variant. The only drawback to this approach is that extra switch states must be included to make sure that every arriving packet can be assigned to a valid switch state. The total system capacity will be reduced by the amount of unused switch overhead. In addition, calculating switch states at a very slow rate still requires a complex processor and the switch would not easily adapt to rapidly changing data traffic. The switching algorithm must be optimized to simultaneously route valid packets to every downbeam for maximum throughput.

The incoming packets are reordered by means of an input memory map. Every input memory location has a corresponding control memory location, as shown in Figure 3.21. There is a separate bank of control memory for each upbeam A, B, and C. Each bank is partitioned into three groups reserved for downbeams A, B, and C. A group's size is precomputed according to the number of switch states reserved for that specific upbeam-downbeam pair. Each time a packet is written to the input memory, the input memory address is written to the next available location in control memory in the group corresponding to the packet's destination. For example, in Figure 3.20 the packets labelled A1 and C1 are written to locations 00 and 01 of upbeam A input memory. The address 00 is written to location 00 of upbeam A control memory (first location of group reserved for downbeam A) and the address 01 is written to location 05 of upbeam A control memory (first location of group reserved for destination C). Each control memory group has a unique downbeam pointer as shown in Figure 3.21. The group boundaries are determined by the initial values of the pointers. Whenever input memory is written, the proper pointer is

selected according to the destination contained within a packet's header. Input memory addressing has two levels of indirection as a pointer addresses control memory which in turn addresses the input memory. The pointers are post-incremented after an access to point to the next free control memory address. Note that each group must contain extra locations to avoid overflow. At the end of a frame, the values of the pointers will give the statistics on traffic between each pair of beams. The on-board processor can read the pointers to calculate the next frame's switch states.

Once the control memory has been filled with an entire frame a second set of pointers is initialized to the top of each group and the input memory can be downloaded to the output memory through the switch matrix. The switch states are sequenced through a precomputed set of states stored in switch state memory. The switch states select the pointers to address the packets with the desired downbeam destinations. The output memories are simply loaded in sequence and do not require any special addressing techniques. Similarly, the pointers are simply incremented in sequence after each access. The table in Figure 3.21 shows the sequence of switch states and the corresponding input memory addresses read from control memory to load the output memory. Switch states I and IV are repeated 3 times due to a large amount of traffic anticipated between their associated nodes. In both cases the switch states are only required twice and the control memories must be disabled during the third occurrences. The first occurrence of switch state I makes the following upbeam/downbeam connections: A/A, B/B, C/C. The pointers select control memory addresses 00, 12, 26 which select input memory locations 00, 10, and 23 respectively and packets A1, B1, and C1 are put in output memory. Once the output memory has been loaded, packets are transferred to the downbeams by simply sequencing through the output memories in order. Additional logic must be added to turn off a downbeam (or generate an idle bit pattern) when the last valid output memory location has been read.

3.2.1.1 Separate Input/Output Memory Hardware Implementation

For purposes of comparison the following design example will be used throughout the remainder of this report:

- * 10 IDENTICAL UPBEAMS, 120 MBPS EACH
- * 10 IDENTICAL DOWNBEAMS, 120 MBPS EACH
- * FRAME LENGTH = 16 ms (SEE SECTION 3.1.3)

- * FRAME SIZE = 10 X 120 MBPS X 16 ms = 19.2 MBITS
- * TOTAL NO. OF 1-WAY 32 KBPS VOICE CIRCUITS =
(19.2 MBITS/FRAME) / (544 BITS/PACKET) = 35,000
(UP TO 70,000 WITH INHERENT DSI ADVANTAGE)

3.2.1.1.1 System Memory Requirements

Assuming a 2:1 DSI advantage, the example architecture would have a voice circuit capacity slightly greater than 50% of the INTELSAT VI. Due to the extremely long frame length, the driving force in this new architecture is the size and power requirements of the on-board memory.

In the ACTS system the input and output memories are pingpong arrays requiring two frames of storage per input or output memory. Packets from the current frame are written into one half while packets from the previous frame are read from the other half. Both halves reverse roles once the current frame is complete. This approach allows both read and write cycles to occur simultaneously. Another possible implementation would be to use a single frame of dual ported memory. A dual ported memory has two sets of address and data busses to allow simultaneous read and write cycles to different addresses. A dual ported RAM would be an effective approach if it was at least half as dense as an equivalent single ported RAM since only half the amount of storage is required. Today's dual ported RAM devices are not an effective solution since their densities are typically 4 times less than the densest available single-ported RAM.

Another way to implement dual ported RAM is by using a single ported RAM of twice the required speed and time-sharing the bus between read and write cycles. In this approach, a full frame is buffered in the memory and then every time a word is read, a new word is written over it in the same location. This "in-place" approach was illustrated in Figure 3.19. The control memories will have to be pingpong to keep track of the input memory read and write addresses. This turns out to be an excellent trade-off since the control memory is much smaller than the input memory.

As an example, suppose the input memories are loaded as shown in Figure 3.20 and the control memories are loaded as shown in Figure 3.21. On the next memory bus cycle the input memory will begin writing its contents to the switch matrix. If A1 is written to the switch, then input

NAS3-24886 FINAL REPORT

memory location 00 will be free. On the following memory bus cycle the direction of the input memory busses will reverse. The next arriving packet on upbeam A will then be written to input memory location 00. 00 will be written to either group A, B, or C of upbeam A control memory depending on the packet's destination. Thus the control memories map the 'free' input memory locations as well as sort the incoming packets by destination. Upon system initialization the on-board processor will fill one side of the pingpong control memories with a unique set of addresses to provide a complete map of free input memory locations.

For this 'in-place' method to work, the control memories must be accessed every bus cycle whether a valid packet is accessed or not. This allows the next 'free' input memory address to always be latched for the next input memory write. Consequently, if a particular upbeam burst does not occupy its entire allotted time, then the control memory will just cycle through new addresses at the end of the burst without actually accessing any packet data. The input memory must somehow be labelled to indicate which input memory addresses contain empty packets. See Section 3.2.1.1.1.4 for further details.

There are a total of four different memory storage subsystems for this architecture: input/output memories, control memory, switch state memory, and packet header memory. They are outlined in the following sections.

3.2.1.1.1 Input/Output Memory Requirements

This section outlines the storage requirements for the input and output memories. Both require equal amounts of storage. These 2 subsystems store only the 512-bit data portion of a packet and not the header information. The "in-place" technique is used.

The 120 Mbps serial data streams are much too fast for conventional memory devices. The serial data must be converted to parallel to slow down the rate of bus transfers. There is a distinct trade-off between memory speed and parallel memory width. The wider the memory width the more bus lines that must be physically routed in the system, increasing the system's size. In addition, many bus lines switching simultaneously can cause power distribution and crosstalk problems. On the other hand, very fast memory speeds require much higher power devices (CMOS, the most desirable technology for memory in space applications, has a power

NAS3-24886 FINAL REPORT

dissipation directly proportional to frequency). The ACTS system uses a memory width of 64 bits as the widest practical implementation. 64 bit busses appear to be about optimum for the given example here also. Thus the 512 data bits of a packet are stored as 8 64-bit words.

The memory's maximum address access time is then just the serial bit period times 64. This rate must be divided by two to account for the bus sharing between read and write cycles.

$$T_{acc} = \frac{.5 \times 64}{120 \text{ Mbps}} = 267 \text{ ns}$$

To allow for bus delays and to maximize system reliability, actual memory speeds on the order of 120 - 150 ns are required. This is well within the capability of today's CMOS memories.

The amount of data storage (exclusive of header information) required per memory bank is

$$120 \text{ Mbps} \times \frac{16 \text{ ms}}{\text{frame}} \times \frac{512}{544} = 1.8 \text{ Mbits per bank}$$

Allowing for 10% overhead, approximately 2 Mbits are required. Considerably more is needed to provide redundancy. Since there are 10 input banks and 10 output banks, 40 Mbits are needed or 20 banks of 32K X 64.

3.2.1.1.1.2 Control Memory Requirements

The control memories only need to store one input memory address for every 8 input memory locations because a packet is stored as 8 consecutive 64-bit words. Storing the address of the packet boundary is sufficient. Therefore the control memory is organized as 10 banks of 4K X 12 X 2. The X 2 is to account for the pingpong arrangement. A width of 12 bits is sufficient to address the 32K address space of the input memories if 3 additional bits are appended to them to address one of the 8 64-bit words within a packet boundary. A simple 3-bit counter will do the job. Generous overhead must be supplied so that no groups within a boundary will ever overlap. All groups must be enlarged in case a burst of traffic arrives destined for one particular group. Doubling the memory to 8K X 12 X 2 (192 Kbits total per group) will have a minimal impact on the actual device

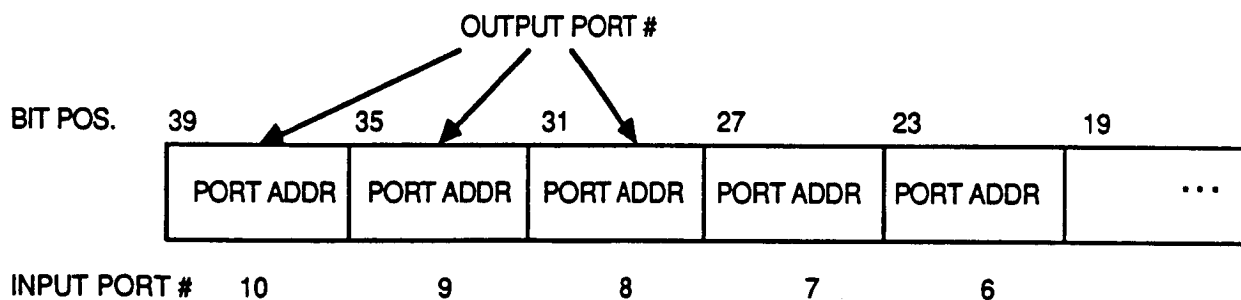
count. Note that the control memory is only 10% of the input/output memory size.

The control memory does not have a time shared bus and can have an access time twice as long (240 -300 ns) as that of the input/output memories. Actually the control memory is only accessed once per packet period which is once every 8 words and the access time could be increased by a huge margin if needed. Care must be taken to properly pipeline the control memory accesses with the input memory and switch matrix accesses.

3.2.1.1.1.3 Switch State Memory Requirements

The sequence of switch states for each complete frame must also be stored in a separate memory array. It should be a pingpong array so that the on-board processor can leave one set of switch states undisturbed while it operates on the other set and updates it based on new traffic statistics. Since there are 10 ports on each side of the switch matrix, a port number can be represented by 4 bits. A switch state consisting of 10 port connections can be represented by a 40 bit word. The input port number is given by the bit position of the 4-bit value within the word and the output port number is given by the value of the 4 bits (see below).

There are a total of approximately 3500 switch states per frame. An



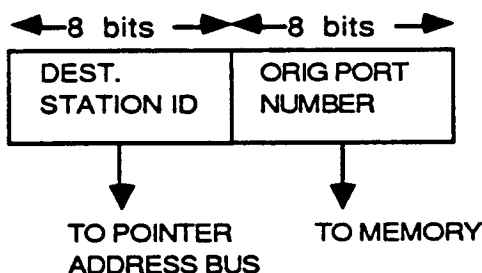
SWITCH STATE MEMORY WORD FORMAT

array of 4K X 40 X 2 (320K total) is required. Very little overhead is necessary except for redundancy. A new switch state is generated once per packet period (4.5 microseconds) so that the access time can be extremely slow. 300 ns static RAM is specified here. Since many switch states will probably occur more than once, the switch state memory could probably be

compressed, but the additional control required would probably not be worth it.

3.2.1.1.1.4 Packet Header Memory and Control

The packet header occupies the first 32 bits of a packet. It is assumed that it has been encoded with a rate 1/2 error correction code. The headers must be decoded to 16 bit values on board. The packets' source and destination station ID numbers are intrinsically known from the input memory bank and group numbers. Therefore only the half of the packet header representing the originating port number needs to be stored (see Figures 3.7 and 3.8). The packet headers are composed of two 8-bit fields as shown below. The destination station ID is used to select the proper control memory pointer. It will be stripped off the packet and replaced by the originating station ID later. The originating port number must be stored and will remain part of the packet header for transmission on the downbeam. A 4K X 8, 300 ns static RAM is required per beam. As in the case of the switch state memory, access time can be slower if desired. The memory uses the same addresses as the input memory. The memory does not have to be pingpong since the in-place technique is used. The header memory is broken down into header input memory and header output memory and is interfaced to the switch matrix in an identical manner to the data input/output memories.



The header memory serves a second purpose. If a unique bit pattern for the originating port number is reserved, it can be used to label whether a particular packet contains valid data or is empty. Thus if the unique pattern is read, the input memory access (read or write) would be ignored. This pattern could be used to disable the modulator if valid data is not present.

Table 3.3 summarizes the total memory requirements for the example.

TABLE 3.3 - MEMORY REQUIREMENTS FOR SEPARATE MEMORY ARCHITECTURE . TOTAL FOR 10 120 MBPS BEAMS

<u>SUBSYSTEM</u>	<u>TOTAL BITS</u>	<u>ACCESS TIME</u>
INPUT MEMORY	20 M	150 ns
OUTPUT MEMORY	20 M	150 ns
CONTROL MEMORY	1.9 M	300 ns
SWITCH STATE MEMORY	320 K	300 ns
HEADER INPUT MEMORY	320 K	300 ns
HEADER OUTPUT MEMORY	320 K	300 ns

TOTAL NUMBER OF BITS = 42.9 MEGABITS

The 32-bit, rate 1/2 header decoder must be fast enough to supply valid addresses to the control memory pointer array. In turn, the contents of the control memory must be read before the first data bits following the packet header are overrun in the input shift register. For this reason, no appreciable header decoding delay can be tolerated and a simple block coding scheme is recommended. The encoders and decoders can then be implemented with simple combinational logic. In addition, the incoming data bits should be placed in a small delay line so that the header can be decoded early before the data bits must be stored. This allows more time for both the decoder and the pointer and control memory accesses.

3.2.1.1.2 Separate Memory System Block Diagram

A block diagram of the total system is shown in Figure 3.22. Each upbeam has its own demodulator and input memory subsystem. Each downbeam has its own output memory subsystem and modulator. Note that it would be very simple to configure the system for any number of beams provided that the switch matrix can handle the load. The subsystems have been designed to operate independently with little outside control. The main function of the on-board processor block is to provide centralized intelligence for system initialization, switch state calculations, burst time plan coordination, fault monitoring, and command processing. Each subsystem contains its own internal timing control to cycle the memories. The baseband switch matrix could be implemented in a custom VLSI device similar to the 3X3 switch in the ACTS. Larger arrays can be made from cascaded arrays of smaller building blocks. The switch can actually be

much slower than the ACTS switch. Switch states change only once every 4.5 usec. The only tight timing requirement is to minimize the settling time when a new switch state is selected. One possibility is to disable the bit stream while the switch is changing states. Upbeam data could build up in a FIFO while it is waiting for the switch to change and then data can be read from the FIFO at a rate slightly faster than 120 Mbps in order to catch up. Thus the switch can be implemented with high speed CMOS technology. Refer to Table 3.4 for a summary of devices and power dissipation for each subsystem. Note that the memory power dissipation figures given assume a 10:1 power savings when the RAMs are not chip selected. Most CMOS static RAMs have such a power down feature. The memories listed are the standard sizes currently available. Radiation hardening has not been assumed.

3.2.1.1.2.1 Input Subsystem Block Diagram

The input memory subsystem is shown in Figure 3.23. Serial data arriving from the demod is sent to a unique word (UW) detector to detect the proper frame synchronization. Every Input subsystem must be synchronized to the same internal bit and frame clocks or the switch will not work properly. The framing information from the UW detector is sent to two different devices. It is sent to a 32-bit FIFO which serves three purposes. The FIFO aligns the bits with the frame clock (there should not be more than about 4 bits of ambiguity) and it delays the data to allow time for control address decoding and generation. It also acts as a buffer during switch state transitions as discussed above. The framing information is also supplied to the block decoder which decodes the packet header information. The decoder is implemented as a custom VLSI device containing a 32-bit serial to parallel input register, a 32-bit parallel decoder, and a 16-bit output latch.

The delayed data bits from the FIFO are converted to parallel in a 64-bit serial to parallel register. The register also has an output latch to hold the word during a write to the input memory. This device will require 4 16-bit custom chips as designed for the ACTS. The input memory has a bidirectional bus that receives data from the S/P register and writes data to a P/S register connected to the switch matrix. The P/S register can use the same 4 custom chips by just changing the inputs to their control pins. Note that the FIFO, UW detector, decoder, and the S/P and P/S registers must all operate at 120 Mbps, a rate presently too fast for CMOS implementation (the ACTS uses ECL technology for this application).

The control memory pointers comprise another custom VLSI chip. It is arranged as an array of 10 13-bit read pointers and 10 13-bit write pointers. The device has its own increment logic and separate read and write pointer output latches. The pointers are selected from one of two sources. A pointer is selected for control memory write cycles from the switch state memory. A pointer is selected for control memory read cycles from the destination address decoded from the header (the upper 8 bits of the decoder output latch).

The pointer latches are connected to the control memory address bus. The control memory data bus is routed to the upper 12 bits of the input memory address bus. It is also tied to the address bus of the originating port number (header) memory. The control memory data bus is also looped back to itself for "in-place" addressing. The control memory latch is used to hold a value just read so it can be written back into the control memory at a new address. The lower 3 bits of the input memory address bus are connected to a 3-bit modulo 8 counter which increments every time a new 64-bit word within a packet is transferred. Note that the on-board processor can also drive the control memory address bus for initialization and diagnostics. It is assumed that the timing signals (memory read and write strobes, bit clocks, etc.) and control logic can be implemented in 1 or 2 medium density semi-custom VLSI devices.

3.2.1.1.2.2 Output Subsystem Block Diagram

The output memory subsystem block diagram is shown in Figure 3.24. It is very straightforward and only requires several devices. The S/P register consists of the same 4 16-bit devices in the input subsystem and converts serial data from the switch matrix to parallel words for the output memory. Words are read from the output memory into the P/S register where they are sent to the downbeam modulator. Again, the same 4 custom devices are used for the P/S register. The P/S register can also be loaded from the packet header memory. The header memory is read by a custom block encoder chip. A hard-wired 8-bit value is also connected to the block encoder to program the originating station ID. The header memory is connected to the output memory data bus and is written from the same S/P register. The output memory is addressed by a custom address generator chip. The chip consists of a 15-bit counter, separate read and write pointers, and an output latch. It is interfaced to the on-board processor for initialization and diagnostics. The output memory subsystem also has its

own custom timing generator chip. It is similar to the one used in the Input subsystem but much simpler. One pin-programmable device could serve both applications. Note that a special bus cycle must be generated when serially transferring header information since its width is only 32 bits.

TABLE 3.4 - SUBSYSTEM DEVICE COUNT AND POWER DISSIPATION

A. INPUT MEMORY SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
32-BIT FIFO	CUSTOM ²	10	10 WATTS
64 BIT S/P	CUSTOM, 16-BIT ¹	40	36
64 BIT P/S	CUSTOM, 16-BIT ¹	40	36
8 BIT S/P	CUSTOM, 16-BIT ¹	10	9
BLOCK DECODER	CUSTOM ²	10	10
POINTER ARRAY	CUSTOM CMOS ³	10	2
UW DETECT	CUSTOM ²	10	10
TIMING GENERATOR	CUSTOM ²	10	15
INPUT MEMORY	16K X 4 CMOS SRAM	320	32
CONTROL MEMORY	8K X 8 CMOS SRAM	40	4
HEADER INPUT MEMORY	8K X 8 CMOS SRAM	10	2
SUBTOTAL:		510 CHIPS	166 WATTS

B. OUTPUT MEMORY SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
64 BIT S/P	CUSTOM, 16-BIT ¹	40	36
64 BIT P/S	CUSTOM, 16-BIT ¹	40	36
ADDRESS CNTR	CUSTOM CMOS ³	10	2
TIMING GENERATOR	CUSTOM ²	10	15
OUTPUT MEMORY	16K X 4 CMOS SRAM	320	32
HEADER OUTPUT MEMORY	8K X 8 CMOS SRAM	10	2
BLOCK ENCODER	CUSTOM ²	10	10
SUBTOTAL:		440 CHIPS	133 WATTS

C. MISC.

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
SWITCH MATRIX	CUSTOM	1	1
SWITCH MEMORY	8K X 8 CMOS SRAM	5	1
SUBTOTAL:		6 CHIPS	2 WATTS
TOTAL:		956 CHIPS	301WATTS

NOTES:

1. Assumes custom ECL chips used for ACTS. GaAs would be preferable for lower power dissipation and higher reliability.
2. Power dissipation figures approximate. Highly dependent on device technology chosen. CMOS may not meet speed requirements. GaAs is preferred for higher speed and reliability.
3. Could utilize current CMOS gate array or standard cell technologies.

3.2.1.2 Conclusions - Separate Memory Architecture

The overall size of the architecture is driven by the memory storage requirements. The amount of memory could be cut in half using the sub-burst routing method described in section 3.1 (8 ms frame length). A 16 ms frame was used in the examples as a worst case. The individual packet routing method used in this design also provides more flexibility. The sub-burst routing method would complicate the overall system control slightly, but probably would have a negligible impact on the total control chip count.

The power dissipation is mainly dependent on the 120 Mbps custom devices such as the S/P and P/S registers. The power given for these devices assumes the same ECL technology employed by the ACTS. The dissipation figures could be lowered however, if GaAs technology is used in place of ECL.

The biggest advantage of this architecture is its ability to be expanded

to any number of beams. It lends itself very well to rate conversion as well. Each beam is modularized and the aggregate bit rate of the satellite can be increased by adding more modules. The biggest disadvantage is the inflexibility caused by the switch matrix. This architecture will be relatively inefficient for rapidly changing data traffic. In addition, the memory requirements are very high and considerable complexity must be added to the on-board processor to calculate switch states and control the switch matrix.

However, a glance at Table 3.4 shows that the majority of the system can be built with standard, existing technology. The S/P, P/S registers and the switch matrix have previously been developed for the ACTS. The memories and address generators can be built with standard CMOS technology. The new developments required are the 120 MBPS FIFO, encoder, decoder, UW detector, and timing generators. They could all be implemented with existing ECL technology although GaAs technology would be preferred for reduced power dissipation and increased resistance to radiation. The architecture size can be reduced in the future as memory densities improve.

3.2.2 UNIFIED MEMORY ARCHITECTURE

Figure 3.25 shows the basic elements of the unified memory architecture. Rather than having separate modules dedicated to each beam, one "unified" memory is time-shared between all the beams. Since only 1 beam can access the memory at a time, there is never any possibility of bus contention. Multiple packets simultaneously arriving destined for the same downbeam are buffered in the memory one at a time. For this reason, the switch matrix can be eliminated. Packet switching is handled by means of addressing the memory in the appropriate manner. This is all done at the expense of increasing the memory speed requirements. This architecture can be viewed as centralized processing versus the distributed memory processing of the separate memory architecture.

The signal flow shown in Figure 3.25 is very straightforward. The memory alternates between the beams in the following sequence: upbeam A write cycle, downbeam A read cycle, upbeam B write cycle, downbeam B read cycle, upbeam C write cycle, and downbeam C read cycle. The packets shown are identical to those in Figure 3.20. The memory array is divided into separate groups for destinations A, B, and C. As each packet arrives, the header is read and the packet is placed in the appropriate destination

group. The header selects one of three downbeam pointers which supplies the next available memory address. The pointers are post-incremented after each access. The packets are thus stored in their order of arrival sorted by destination. No control memory is necessary because the packets are sorted before they are written to the data memory. The memory is output to the downbeams by initializing a second set of pointers to the top of each group and then simply sequencing through each group in order. The packets are sent to the downbeams in their order of arrival. This was not the case for the separate memory architecture.

There is an inherent problem with the unified memory architecture if only part of a packet is written to memory at a time. For example, if the memory bus is 64 bits wide and a packet is 512 bits wide, then the packet will require 8 separate memory writes. The problem is that the 8 writes cannot occur consecutively because once 64 bits are written from one upbeam the other upbeams must be processed to allow enough time for 64 more bits arrive. As a result, the packets can end up scrambled as shown in Figure 3.26.

The figure shows 3 packets arriving on separate upbeams. All of them are destined for downbeam A. The packets are shown broken down into 64-bit words labelled by their superscripts. The subscripts indicate whether the packets originated from A, B, or C. The memory is alternately written words from the S/P registers of upbeams A, B, and C. The words are written to Group A of the unified memory in order. The final result is that the 8 words from the 3 beams will become interleaved with each other within the memory group. This presents a difficult problem when the memory is being read. There is no way of knowing how to recover the original packets because the number of packets being interleaved at a time is random, depending on the traffic on each upbeam. If 8 packets arriving on separate beams are destined for A, then they will all be interleaved.

One possible solution would be to write one entire packet to memory at a time. 8 consecutive write cycles would occur for upbeam A followed by 8 consecutive write cycles for upbeam B, However this would require a large amount of buffering to store all the incoming bits while the beams wait their turn to access memory. In a 10-beam system each beam would have to wait for 72 write cycles (4608 bits) before having access to memory. This would require very large high-speed FIFOs on each beam.

Another solution to the problem is to use a more sophisticated memory

addressing scheme. When a packet is written to a group of memory, 8 consecutive locations must be reserved. A pointer must be dedicated to that packet until all 8 words have been written. The next packet to be written to that group must reserve another 8 locations. For an N beam system a maximum of N pointers will be needed within a downbeam group. N^2 pointers are required for the whole system. Only N pointers are ever used at a time but N^2 are needed to handle all possible source/destination combinations.

An example of a 3 beam system is shown in Figure 3.27. A pointer counter is required within each group to select one of the 3 pointers. This means there is another level of indirection for memory accesses. The pointers within group A are initialized to 000, 008, and 010. Group B of the memory starts at address 100. The three B pointers are initialized to 100, 108, and 110. Similarly, the group C pointers are initialized to 200, 208, and 210. Thus the pointers point to the first 3 8-word boundaries within each group. The 3 pointer counters are initially zeroed.

Figure 3.27 shows 3 packets destined for A. The packet arriving from A will access the first pointer counter, store the first packet word in location 000, increment the first A pointer to 001 and increment the A pointer counter. The pointer counter will now point to the second A pointer and the first word of the packet arriving from B will be stored in location 008. Likewise the second A pointer will be incremented to 009 and the pointer counter will again be incremented. The first word of the packet from C will be stored in location 010 in a similar manner. Then the pointer counters will be reset and the second words arriving from A, B, and C will be stored in locations 001, 009, and 011 respectively. Once all 8 words of each packet have been loaded, the entire pointer array must be updated to get ready for the next wave of new packets. The pointers are updated according to the maximum value attained by the respective pointer counter during the last packet period. In this case the highest memory location filled was 017 by the last word of the packet from C. The A pointers must then be reinitialized to 018, 020, and 028. The first A pointer is incremented by $1+8N$, where N = the maximum value latched by the pointer counter. The second A pointer is incremented by $1+8(N+1)$ and the third A pointer is incremented by $1+8(N+2)$. Note that the three pointers within each group always differ by 8 from each other. All the pointers will not be used during any given packet period but they must all be initialized in case many incoming packets are simultaneously destined for the same group.

NAS3-24886 FINAL REPORT

The pointer logic must have a speed equal to the memory access time and can easily be implemented in a single semi-custom logic device. Separate output pointers will be required but they are very simple. Only 1 pointer is required per group since more than 1 packet cannot be written to the same destination at the same time. These pointers can be implemented in the same logic device.

The biggest advantage of this architecture is the tremendous flexibility and simplicity resulting from the elimination of the switch matrix. The switch matrix counts on the fact that a certain number of packets will arrive on each upbeam destined for the various downbeams and no more. The unified memory architecture does not care about the distribution of packets between the various beams. For example, all the packets arriving on upbeam A could be destined for downbeam B during one frame and destined for downbeam C during the next frame. In fact, the aggregate sum of all packets arriving destined for a certain downbeam could temporarily exceed the capacity of the downbeam as long as the number of packets for that destination decreases during the next frame. Extra overhead must be included in each memory group to handle these short-term overloads. The separate memory architecture overloaded if any one upbeam had too many packets for one destination (switch overload) but the unified architecture only overloads if the aggregate upbeam traffic for a given destination exceeds the destination's downbeam overload capacity (memory overload).

3.2.2.1 Unified Memory Hardware Implementation

For purposes of comparison, the same design example of 10 120 Mbps beams given in section 3.2.1.1 will be used.

3.2.2.1.1 System Memory Requirements

The unified memory architecture only has two separate banks of memory: Data memory and Header memory. The memories will have the same 64-bit width as discussed in the separate memory architecture. The 267 ns access time calculated for the separate memory case (assuming time-sharing of the memory between read and write cycles) must be divided by 10 to account for time-sharing of the memory between 10 beams. This gives an access time, $T_{acc} = 27$ ns, not including any margin between adjacent bus cycles or any safety factor. Such a speed is impractical for a large memory array, especially if CMOS is desired. Such a large number of bus lines switching at those speeds would cause very large

current surges and many noise problems would result. For these reasons, a pingpong array is recommended. That would decrease the speed requirement by a factor of 2 to 53 ns. Allowing for a 50% safety factor, 25 ns memories are required, the fastest CMOS memories currently available.

3.2.2.1.1 Unified Data Memory Requirements

The amount of storage is essentially the same as before except the memory is organized differently. The memory size is

$$120 \text{ Mbps} \times 16 \frac{\text{ms}}{\text{frame}} \times \frac{512}{544} \times 10 \text{ Beams} = 18 \text{ Mbits}$$

or 20 Mbits for a 10% overhead. Since the memory is a pingpong array, 40 Mbits are required. The density of 25 ns memories is currently about 4 times less than that of the memories in the previous architecture.

Each half of the memory is addressed as 8 separate columns of 40K x 64 bits. Each packet has a unique address and each 64-bit word within a packet has its own column number.

3.2.2.1.2 Unified Header Memory Requirements

One minor drawback of this architecture is that the originating station ID information is lost when the packets are stored. Both the originating station ID and originating port number must be stored in a separate 16 bit wide header memory array. Thus a 40K X 16 X 2 (pingpong) array is required. The packet period is 4.5 usec, requiring a memory access time of 450 ns to share the memory bus between 10 beams. A 200 ns memory should be sufficient to allow for a 50% safety factor. The memory requirements are summarized in Table 3.5.

TABLE 3.5 - MEMORY REQUIREMENTS FOR UNIFIED MEMORY ARCHITECTURE . TOTAL FOR 10 120 MBPS BEAMS

<u>SUBSYSTEM</u>	<u>TOTAL BITS</u>	<u>ACCESS TIME</u>
I/O DATA MEMORY	40 M	25 ns
HEADER MEMORY	1.25 M	200 ns
<hr/> TOTAL = 41.25 MEGABITS FOR 10 BEAMS		

3.2.2.1.2 Unified Memory System Block Diagram

A complete system block diagram of the unified memory architecture is given in Figure 3.28 and a detailed diagram of the control sections is given in Figure 3.29. Each beam has its own modulator, demodulator, and control subsection. The address pointer array described in section 3.2.2 is implemented in a single CMOS custom chip. The headers decoded by the control subsections are multiplexed onto the control address bus and select an input pointer from the pointer array. The input pointers are latched into 2 separate latches. One latch drives the data memory address bus and the other drives the header memory address bus. The addresses change every 400 nsec so the internal logic does not have to be extremely fast. A modulo 8 counter is used to select 1 of 8 64-bit columns in the data memory array. Data latched into the control subsection S/P registers is output to a 64-bit multiplexed data bus and is written to the data memory. The header 8-bit originating port numbers are also brought out on this bus and are stored in the header memory. An 8-bit counter provides the originating station ID number to the header memory.

Similarly, the output pointers are latched into 2 separate latches to address the data and header memories. Both header and data information are multiplexed onto the same data bus and are written to the P/S registers in the control subsections. Note that special shortened bus cycles are required for the 16-bit header memory accesses. The bus timing cycles are generated by a single custom timing chip. The chip must be very high speed (> 40 MHz) but may be just within the capabilities of today's CMOS technology. Refer to Table 3.6 for a summary of devices and power dissipation for each subsystem.

TABLE 3.6 - SUBSYSTEM DEVICE COUNT AND POWER DISSIPATION-
UNIFIED MEMORY ARCHITECTURE

A. UNIFIED MEMORY SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
POINTER ARRAY	CUSTOM CMOS ³	10	2
TIMING GENERATOR	CUSTOM ²	1	5
DATA MEMORY	4K X 4 CMOS SRAM	2560	1000/300 ⁴
HEADER MEMORY	8K X 8 CMOS SRAM	20	2
MISC. COUNTERS	STANDARD ECL	2	2
SUBTOTAL:		2593 CHIPS	1011/311 ⁴ WATTS

B. CONTROL SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
32-BIT FIFO	CUSTOM ²	10	10
64 BIT S/P	CUSTOM, 16-BIT ¹	40	36
64 BIT P/S	CUSTOM, 16-BIT ¹	40	36
BLOCK ENCODER	CUSTOM ²	10	10
BLOCK DECODER	CUSTOM ²	10	10
UW DETECTOR	CUSTOM ²	10	10
SUBTOTAL:		120 CHIPS	112 WATTS

TOTAL: 2713 CHIPS 1123⁴/423 WATTS

NOTES:

1. Assumes custom ECL chips used for ACTS. GaAs would be preferable for lower power dissipation and higher reliability.
2. Power dissipation figures approximate. Highly dependent on device technology chosen. CMOS may not meet speed requirements. GaAs is preferred for higher speed and reliability.

3. Could utilize current gate array or standard cell technologies
4. First figure assumes no power down of SRAM devices.
Second figure assumes 4:1 power savings when SRAM devices are not chip selected.

3.2.2.1.3 Unified Memory Control Subsystem Block Diagram

The control subsection contains the same basic elements as the input and output subsections of the separate memory architecture. A 32-bit FIFO tied to the demodulator is used for timing synchronization and to provide enough time delay for the header decoding process. A unique word detector detects proper frame timing. A custom block decoder chip decodes the header bits. The chip contains its own internal input S/P register and output parallel latch. The chip should be implemented with either GaAs or ECL due to the speeds involved. The input data bits are converted to 64-bit words by the custom 64-bit S/P register. Again, the 16-bit custom ECL devices designed for the ACTS could be used. The same devices could also be used for the 64-bit P/S register which is loaded from the data memory and sends a serial bit stream to the modulator. Note that this serial stream is multiplexed inside another custom chip, the block encoder. The 16-bit header memory data bus writes to the block encoder and the resulting 32-bit words are latched in the internal P/S register. The mux then selects either header or data bits as determined by the central timing device. The encoder chip also has tight timing constraints and should be either ECL or GaAs.

3.2.2.2 Conclusions - Unified Memory Architecture

The advantages in system efficiency have been shown for unifying the system memory into one time-shared array. The packet switching becomes trivial and is simply a matter of generating the proper memory addresses in a single custom address generator device. The architecture is limited by one single problem - that of obtaining fast enough memory devices. The example given here probably represents the uppermost throughput limit. Throughput is dependent only on the aggregate system bit rate, not on the number of beams or the individual beam bit rates.

The figures given in Table 3.6 are so much worse than those given for the previous architecture because of the extremely fast memory speed

requirements. The higher speed RAMs have a 4:1 density disadvantage and the power down savings are not so great. A separate power figure was given for RAMs without a power-down feature because at the speeds involved, it is questionable whether the RAMs can be powered down at all. They may have to have their chip select lines constantly asserted. The memory data busses would then be controlled by a separate output enable line which typically has a faster response time.

However, the removal of the switch state calculations from the on-board processor system has not been factored in to Table 3.6. The overall system has been tremendously simplified and the processor requirements are mainly for system initialization, diagnostics, and command control. The unified memory architecture would be the architecture of choice if the aggregate bit rate was reduced from 1.2 Gbps to about 200 Mbps. At the slower speed, denser 16K x4 120 ns CMOS RAMs could be used, making the system device count and power dissipation better than the separate memory architecture. Such a system could easily be implemented with existing technology. Faster bit rates would require major advances in memory technology such as the development of very dense (16K X 4) GaAs SRAM.

3.2.3 ALTERNATIVE UNIFIED MEMORY ARCHITECTURE

One of the main drawbacks of the preceding unified memory architecture was the necessity of pingpong memory. If the memory speed requirements were substantially reduced then the "in-place" approach discussed in section 3.2.1.1.1 could be implemented, thereby reducing the memory size by a factor of two. This type of architecture is illustrated in Figure 3.30. The basic principle is the same as for the separate memory architecture of section 3.2.1. Since the control memories are time-shared between all the upbeams, a separate bank of control memory is dedicated to each downbeam. The memories are not partitioned into groups as before. Consequently each control memory requires only a single pointer (that is, a single read pointer and a single write pointer).

The data memory is simply filled in the order packets are received. The data memory addresses are written to the proper control memory bank, as determined by the packet header's destination addresses. The packets are reordered when the memory is read out to the downbeams. As a result, the overhead requirements of the data memory are substantially reduced. An extra amount of overhead can be added at the bottom of the memory, to

be shared between all the upbeams. The previous 2 architectures required overhead dedicated to each beam. Therefore this architecture is the most immune to temporary overload situations. However the control memories still require extra overhead for each bank.

The basic idea behind this architecture is to make the data memory as wide as an entire packet, reducing the speed requirements to an acceptable level. This would in turn eliminate the scrambling problem present in the last architecture and also eliminate the mod 8 counters used to address the 64-bit words within packets. It would also reduce the width of the memory address busses. The next section will discuss the hardware requirements to make this architecture possible.

3.2.3.1 Alternative Unified Memory Hardware Implementation

As mentioned previously, increasing the memory bus width beyond 64 bits is highly impractical due to physical bus routing constraints. However, if the upbeams and downbeams are interfaced to the unified memory over a serial link then the physical routing problems are eliminated. The serial data from the 10 upbeams must be multiplexed into one extremely high-speed serial link and then converted to 512-bit slow speed parallel data by a single 512-bit S/P register. The S/P converter only requires a single local bus to the memory array, making interconnects very simple.

Similarly, data read from the memory array can be latched into a single P/S converter and the extremely high speed serial bit stream can be demultiplexed to the 10 downbeams. Although the speed requirements of the logic required has been increased tremendously, all data transfers are now serial, reducing chip I/O requirements and board space substantially.

A block diagram of the alternative unified memory architecture is shown in Figure 3.31. The 10 120 Mbps serial bit streams from the upbeams must be time division multiplexed into one 1.2 Gbps serial bit stream. The multiplexed bit stream will be composed of contiguous groups of 512 data bits from each packet minus the header bits. The 1.2 Gbps stream is converted into a 512-bit word in a custom S/P shift register. When the shift register is full, the word is transferred to an integrated parallel latch connected to the memory bus. The memory bus is local to the S/P register during write cycles and to the custom P/S register for write cycles. The P/S register transfers data serially to the downbeam

demultiplexer at a 1.2 Gbps rate. The memory bus is confined to a small area, eliminating physical routing problems. Of course now the problem has been shifted to one of developing a reliable digital mux and demux capable of operating at a speed of 1.2 Gbps. The hardware will be analyzed in further detail in the following sections.

3.2.3.1.1 System Memory Requirements

The alternative unified memory architecture has 3 separate types of memory: data memory, control memory, and header memory. The key point of this architecture is to reduce the memory requirements to a minimum, yet permit the use of standard high-density CMOS SRAM. The data memory access time can be increased to 110 ns because the bus is 8 times wider than in the last architecture. This figure includes the fact that the access time must be cut in half to time share the bus between read and write cycles. A 50% safety factor is included as before. The data memory requirements have been cut in half to 20 megabits (40K X 512) due to the elimination of the pingpong arrangement. The memory does not need separate column addresses as before.

The header memory also requires a 110 ns access time and is addressed using the in-place method. It is addressed using the same address bus and timing as the data memory. The memory width is just much less. The header memory is organized the same as before except for the elimination of the pingpong arrangement (see section 3.2.2.1.1.2). Both the originating station ID and originating port number must be stored in a 16-bit word. This requires a total of 768K (48K X 16). The array size has been increased from 40K x 16 previously because 16K x 4 SRAM chips are used here due to their increased reliability at the higher speed.

The control memory must be pingpong and a total of 1.5 megabits are required (48K X 16 X 2). This is enough to address 40K of packet memory plus a 20% overhead capability. The access time can be increased to 220 ns because of the pingpong arrangement. The total memory requirements are summarized in Table 3.7. The total number of bits has been nearly cut in half over the 2 previous architectures while substantially increasing the overflow capability.

TABLE 3.7 - MEMORY REQUIREMENTS FOR ALTERNATIVE UNIFIED MEMORY ARCHITECTURE . TOTAL FOR 10 120 MBPS BEAMS

<u>SUBSYSTEM</u>	<u>TOTAL BITS</u>	<u>ACCESS TIME</u>
UNIFIED DATA MEMORY	20 M	110 ns
CONTROL MEMORY	1.5 M	220 ns
UNIFIED HEADER MEMORY	768 K	110 ns

TOTAL NUMBER OF BITS = 22.3 MEGABITS

3.2.3.1.2 Alternative Unified Memory Hardware Block Diagram

The basic memory architecture shown in Figure 3.31 is very similar to the previous architectures presented. A custom CMOS 20 X 16 pointer array is used to address the control memory. The read and write pointers have separate output latches. The chip must supply a new address every 110 ns, well within the capability of CMOS. The 16-bit pointer value is used to address the control memory array. The control memory provides a read address to the data SRAM and then loops back that value into the next free control memory location to store the next "free" data memory address. The control memory can also be loaded from the central on-board processor during system initialization. The data memory and header memory both receive the same addresses. The first byte of the header memory is written with the originating port number from the block decoders in the input mux subsection. The originating station ID is written from an 8-bit counter connected to the bus.

The same custom device can serve the purpose of S/P and P/S register. Since the parallel bus on the chip is designed to interface to a relatively slow speed bus, the chip's I/O bus drivers can be made very small for a significant reduction in power consumption. The only high-speed interface is the serial data line. This chip must be implemented in GaAs to handle the 1.2 Gbps speed requirement. A device with a 16-bit bus should be quite feasible even at that speed. It could be implemented in a gate array of approximately 350 gates. Even wider chips will be quite feasible in the future (see section 5.0). Extreme care would have to be exercised to equalize the clock delay between all 32 chips required for a 512-bit register. The timing and bus control chip shown in the figure can be built with a standard CMOS gate array to supply the memory bus timing signals. The 110 ns access time of the data SRAM array is about the fastest available without suffering a loss in chip density for greater speed. 120 ns radiation-hardened RAMs are available today as well. A summary of the architecture hardware requirements is given in Table 3.8. The memory power dissipation figures assume the memories have a 10:1 power-down advantage when not selected.

3.2.3.1.2.1 Alternative Unified Memory Serial Input Mux Block Diagram

A block diagram of the serial input mux is shown in Figure 3.32. 120 Mbps data from each beam is input to both a 544-bit serial FIFO and an input subsystem. The input subsystem contains a unique word detector chip and a block decoder chip as in the previous architecture. Note that the packet header information is stripped off separately and is not multiplexed onto the serial bus. The FIFO is long enough to store an entire data packet plus allow some time delay and also perform frame synchronization. Once an entire packet has been loaded into the FIFOs, each FIFO in turn outputs 512 bits at a rate of 1.2 Gbps. The FIFO read and write clocks are generated by a custom GaAs timing chip. The chip is within the capabilities of today's GaAs gate array technology but again, extreme care must be taken to equalize the clock delays when interconnecting the devices on a PC board.

The most difficult aspect of this entire architecture is the implementation of the FIFOs, both because of their size and their speed. Approximately 10,000 gates are required - more than five times today's practical limits. In addition, the entire chip must operate at the maximum 1.2 Gbps clock rate, making interconnections within the chip very difficult. The FIFOs could possibly be made by interconnecting 8 68-bit devices. Power dissipation should not be too severe since the chip only has two high-speed data pins. Of course this will have a serious impact on the system parts count and power dissipation figures. Refer to section 5.0 for a discussion of GaAs technology and its future.

3.2.3.1.2.2 Alternative Unified Memory Serial Output Mux Block Diagram

The serial output demux is shown in Figure 3.33. The FIFOs are identical except that data is written into the FIFO at 1.2 Gbps and is read at 120 Mbps. The read and write clocks have been reversed. The timing generator chip is essentially the same as in the input MUX. It is much easier to implement because the output clocks are at a slower rate of 120 Mbps. The timing generator chip enables the 1.2 Gbps serial data stream into one of the 10 FIFOs at a time. The FIFOs output their data at a constant 120 Mbps to the output subsystems. The output subsystems mux the data with the data derived from a custom block decoder chip loaded from the header memory. The block decoder chip is the same as for the previous

NAS3-24886 FINAL REPORT

architecture. Again, the limiting factor of the demux is the ability to produce a large FIFO at these speeds.

TABLE 3.8 - SUBSYSTEM DEVICE COUNT AND POWER DISSIPATION -
ALTERNATIVE UNIFIED MEMORY ARCHITECTURE
(BASED ON 1987 TECHNOLOGY)

A. UNIFIED MEMORY SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
512 BIT S/P	CUSTOM, 16-BIT GaAs ²	32	38
512 BIT P/S	CUSTOM, 16-BIT GaAs ²	32	38
8 BIT COUNTER	STANDARD CMOS	1	0.1
POINTER ARRAY	CUSTOM CMOS ²	1	0.2
TIMING, BUS CNTRL	CUSTOM CMOS ²	1	0.5
DATA MEMORY	8K X 8 CMOS SRAM	320	25
CONTROL MEMORY	16K X 4 CMOS SRAM	24	2
HEADER INPUT MEM	16K X 4 CMOS SRAM	12	1
SUBTOTAL:		423 CHIPS	105 WATTS

B. INPUT MUX SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
BLOCK DECODER	CUSTOM ¹	10	10
UW DETECTOR	CUSTOM ¹	10	10
TIMING GENERATOR	CUSTOM GaAs	1	1
544 BIT FIFO	CUSTOM 68-BIT GaAs	80	160
SUBTOTAL:		101 CHIPS	181 WATTS

C. OUTPUT DEMUX SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
BLOCK ENCODER	CUSTOM ¹	10	10
TIMING GENERATOR	CUSTOM GaAs ²	1	1

544 BIT FIFO	CUSTOM GaAs	80	160
SUBTOTAL:		91 CHIPS	171 WATTS
TOTAL:		615 CHIPS	457 WATTS

NOTES:

1. Power dissipation figures approximate. Highly dependent on device technology chosen. CMOS may not meet speed requirements. GaAs is preferred for increased speed and reliability.
2. Could utilize current gate array or standard cell technologies

3.2.3.2 Conclusions - Alternative Unified Memory Architecture

This architecture has reduced the chip count by 35% from the separate memory architecture although the power dissipation has increased by 50%. However both the chip count and power dissipation figures are greatly improved as compared to the previous unified memory architecture. This architecture uses standard CMOS memory devices. Note that the on-board memory accounts for 75% of the chip count totals but only 10% of the power dissipation totals. This architecture has virtually eliminated the feasibility problem of implementing the on-board memory array and has reduced the packet switching function to several custom logic chips that can be produced with today's technology. The system has the potential to efficiently switch at nearly 100% total capacity and can handle short-term capacity overloads of a beam quite easily through the use of the control memories. The architecture described has a total throughput of 1.2 Gbps.

However, several extremely high speed custom GaAs logic devices must be developed before this architecture can be proven. The throughput of the system is limited by the capability of the serial mux and demux circuits required. As GaAs is a relatively new technology, it can be expected that the power and chip count figures given here can be reduced substantially. The gating item for this architecture is the development of a 1.2 Gbps FIFO long enough to buffer an entire packet. If the packet size was decreased to 256 bits using the sub-burst routing method then the FIFO size could correspondingly be reduced. However the smaller word width would require either faster memory or the capability of storing 2 packets simultaneously

NAS3-24886 FINAL REPORT

in 512 bit wide memory. Several questions remain regarding the reliability of a system utilizing logic at these speeds. The 1.2 Gbps throughput rate probably represents an upper limit of feasibility by today's estimates. Section 5.0 will discuss the feasibility of this architecture in the future by analyzing future trends in semiconductor technology.

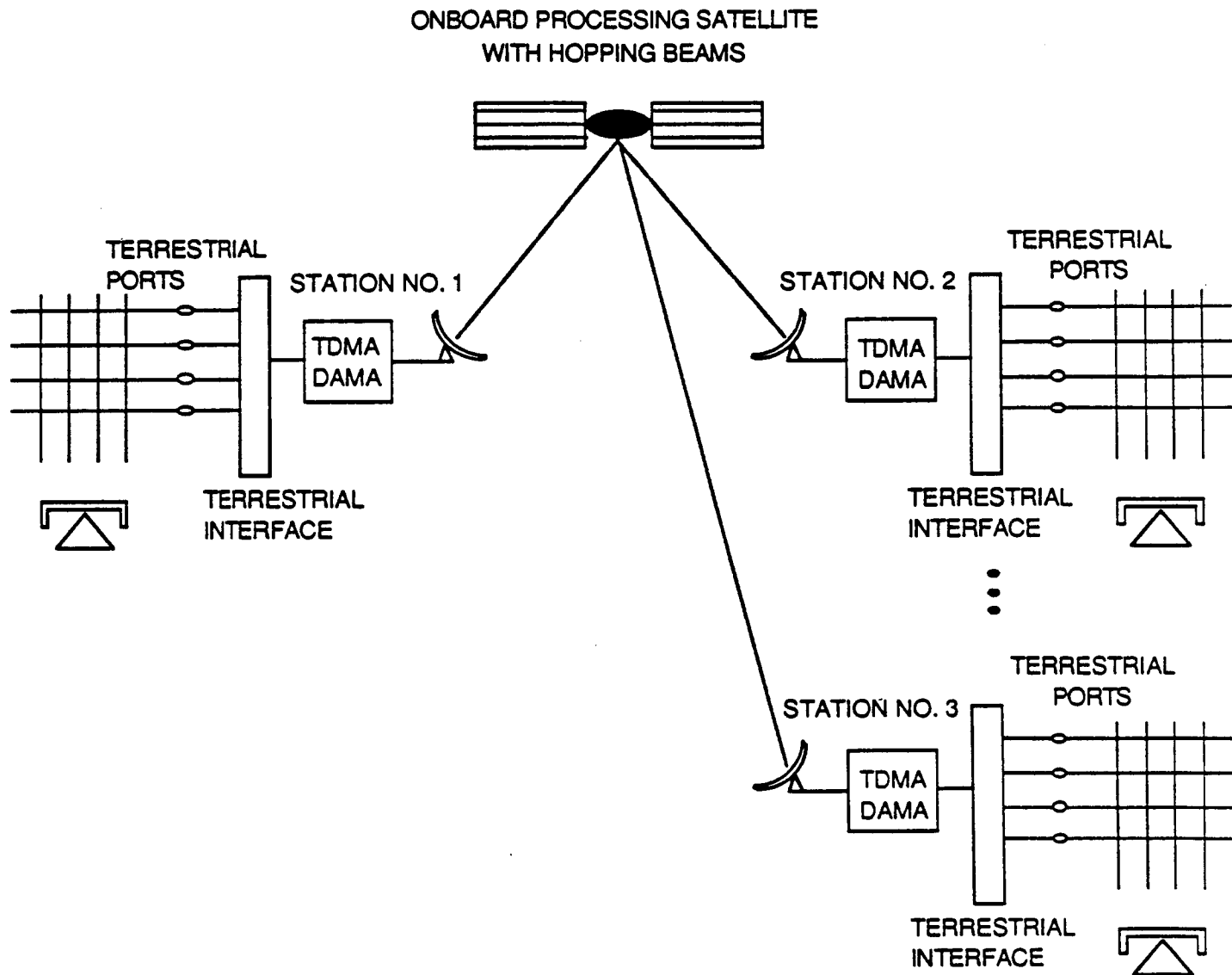


FIGURE 3.1: TDMA/DAMA SYSTEM WITH ONBOARD PROCESSOR

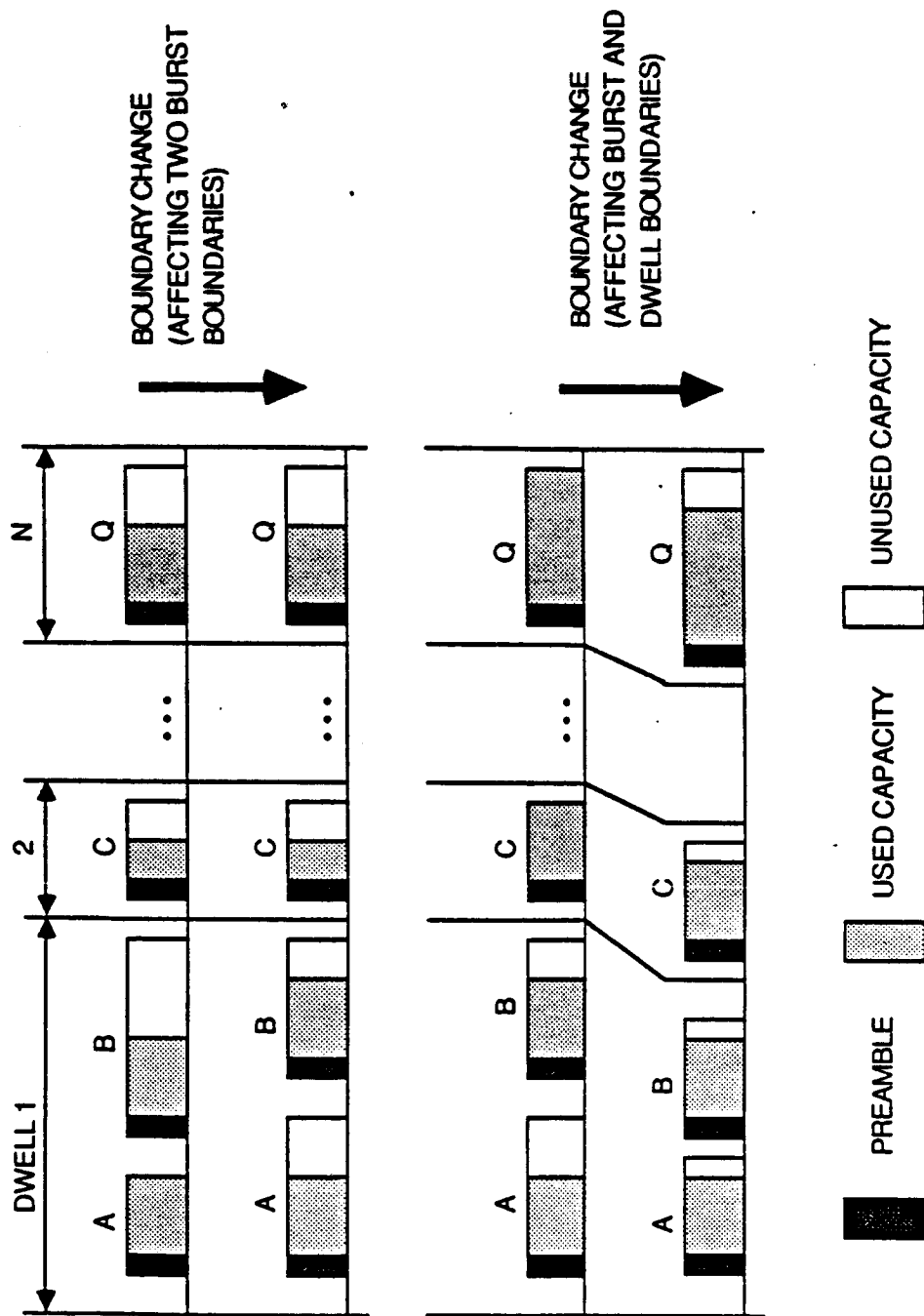


FIGURE 3.2 UPLINK CAPACITY REALLOCATION

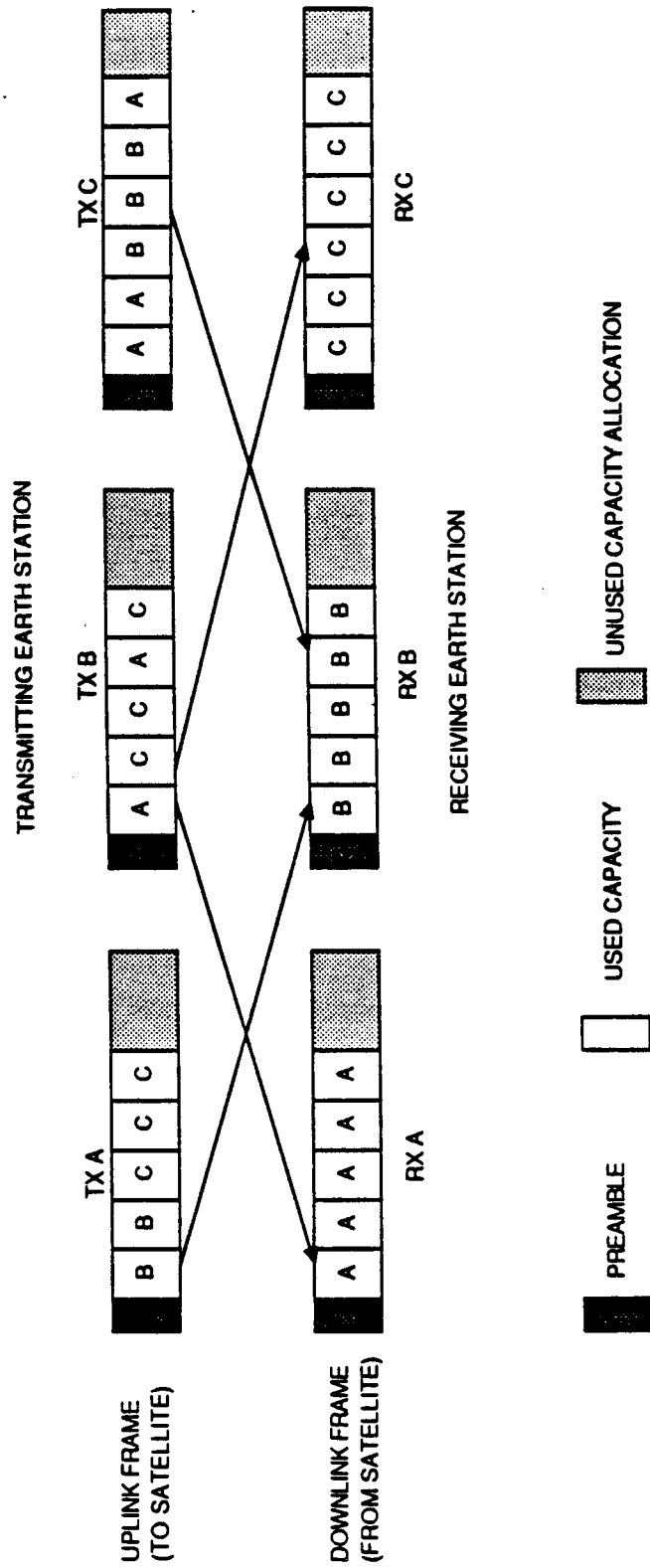
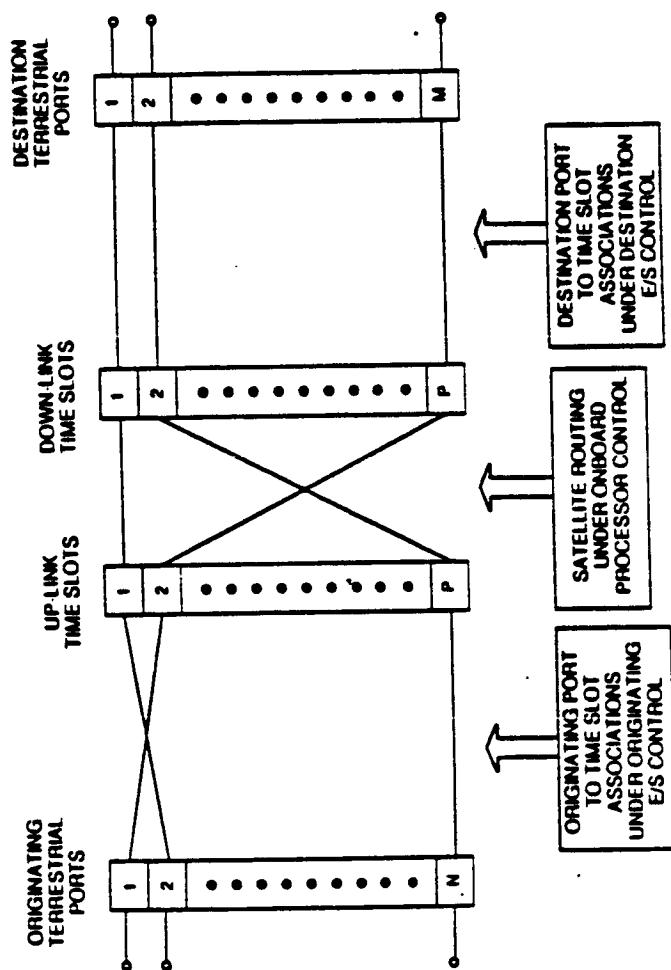


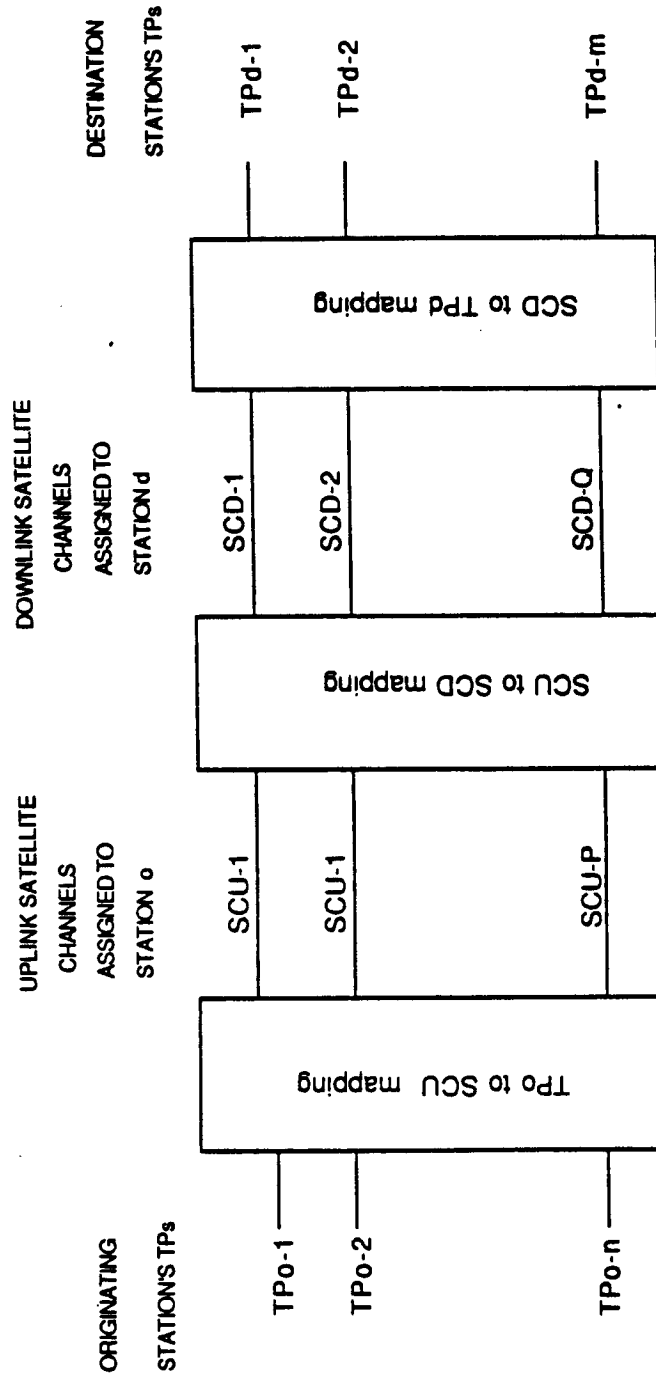
FIGURE 3.3 ONBOARD SATELLITE CHANNEL MAPPING



Terrestrial Port to Time Slot Mapping and Up-Link
to Down-Link Satellite Channel Mapping For
Destination-Directed Message Switching

FIGURE 3.4

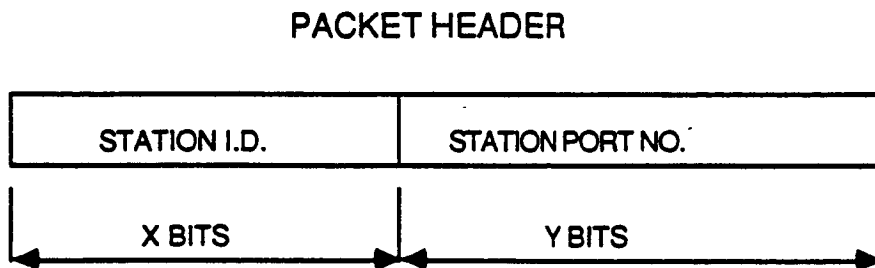
FIGURE 3.5 DESTINATION DIRECTED PACKET SYSTEM MAPPING



TP = TERRESTRIAL PORT
 TPo = TP AT CALL ORIGINATING STATION
 TPd = TP AT CALL DESTINATION STATION
 SC = SATELLITE CHANNEL
 SCU = UPLINK SATELLITE CHANNEL
 SCD = DOWNLINK SATELLITE CHANNEL

P = NUMBER OF UPLINK SATELLITE CHANNELS
 ASSIGNED TO STATION o
 Q = NUMBER OF DOWNLINK SATELLITE CHANNELS
 ASSIGNED TO STATION d
 n = NUMBER OF PORTS AVAILABLE AT o
 m = NUMBER OF PORTS AVAILABLE AT d

FIGURE 3.6 PACKET HEADER STRUCTURE



X BITS DEFINE STATION I.D.

Y BITS DEFINE STATION TERRESTRIAL PORT NO.

X+Y BITS DEFINE NETWORK TERRESTRIAL PORT NO.

EXAMPLE:

X = 8 DEFINES 256 STATION I.D.s

Y = 8 DEFINES 256 TERRESTRIAL PORT NO.s

X+Y = 16 DEFINES 65,536 NETWORK TERR. PORT NO.s

FIGURE 3.7 TRAFFIC BURSTS FOR PACKET ROUTING

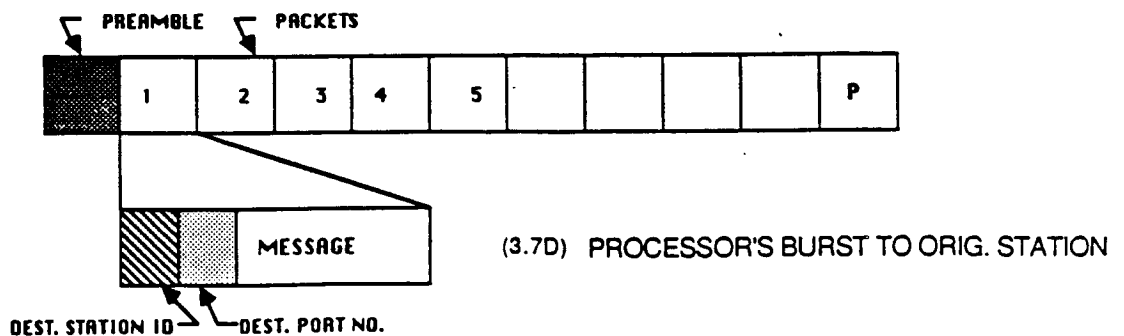
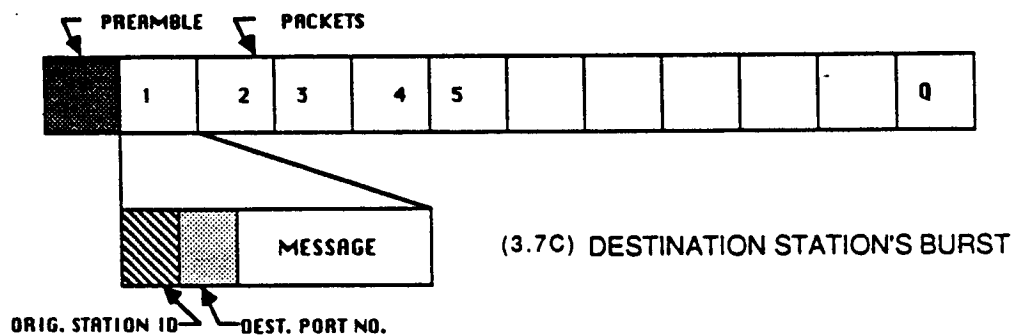
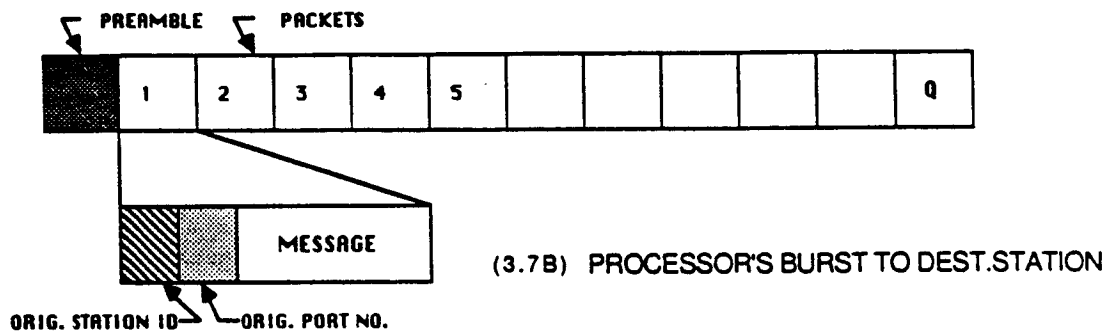
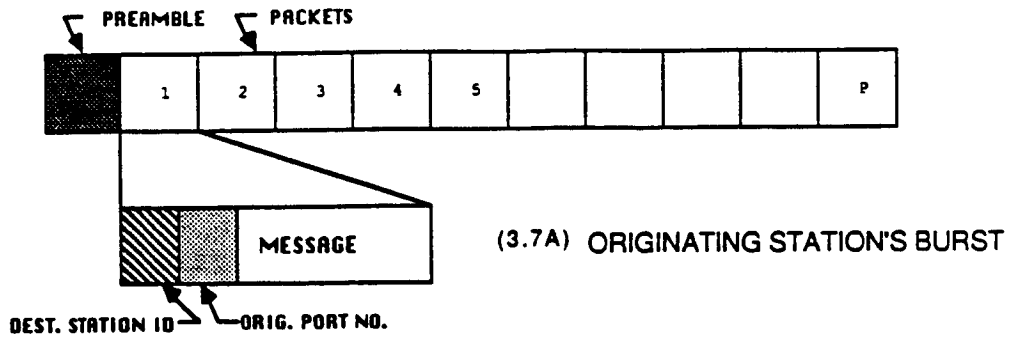
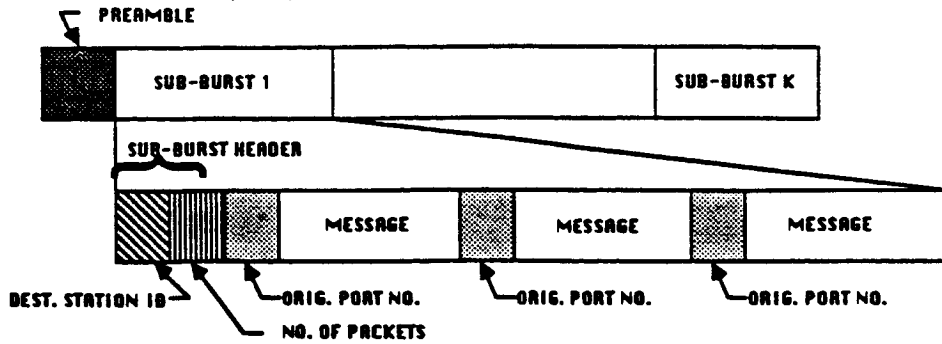
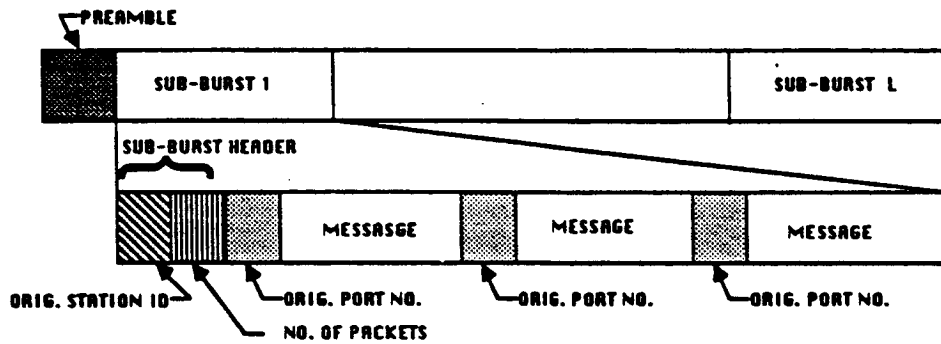


FIGURE 3.8 TRAFFIC BURSTS FOR SUB-BURST ROUTING

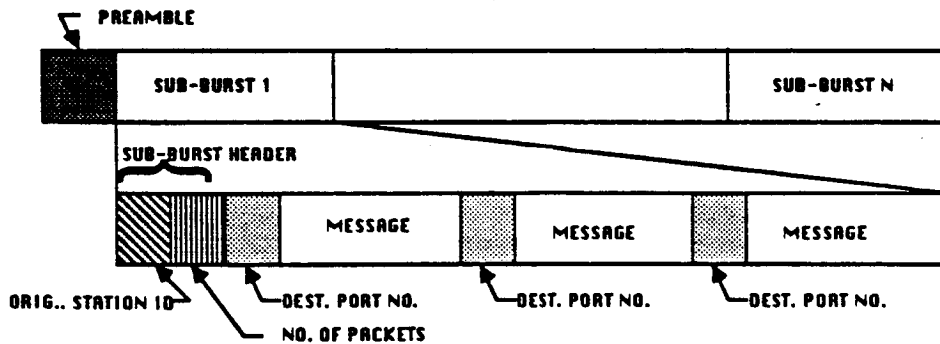
(3.8A) ORIGINATING STATION'S BURST



(3.8B) PROCESSOR'S BURST TO DEST. STATION



(3.8C) DESTINATION STATION'S BURST



(3.8D) PROCESSOR'S BURST TO ORIG. STATION

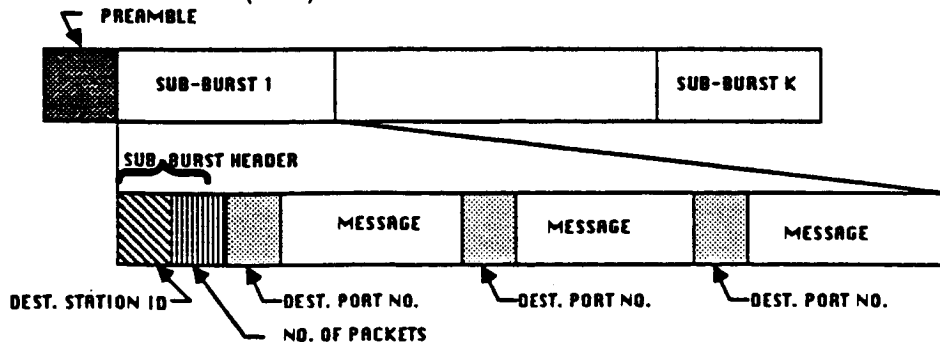
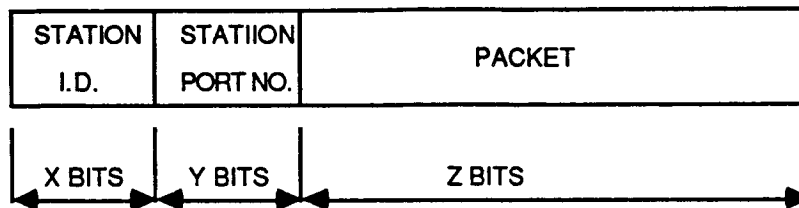


FIGURE 3.9 PACKET HEADER EFFICIENCY FOR INDIVIDUAL PACKET ROUTING

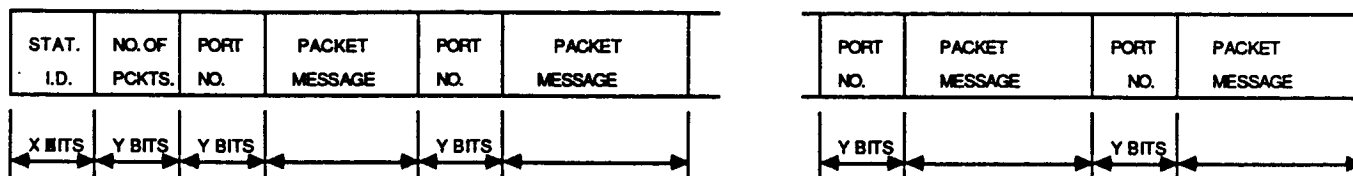


If voice channel bit rate is 32 kbits/s and the frame period is equal to F ms, then Z is equal to $32 \times F$ bits. For the example of $X=8$ bits and $Y=8$ bits, $X+Y=16$ bits. Assuming that the header is protected with a rate $1/2$ code, thus yielding a 32 bit header. For this example the frame efficiency loss due to the header can be written:

$$L = 32 / (32 + 32 \times F)$$

To achieve a frame efficiency loss of less than 6% would require a frame period of about 16 ms.

FIGURE 3.10 PACKET HEADER EFFICIENCY FOR SUB-BURST PACKET ROUTING



EXAMPLE:

As in the previous example, we assume that both X and Y equal 16. This will provide 256 station I.D.s and 256 station port nos. when rate 1/2 FEC is used, thus providing 65,536 network port nos.

If the number of packets per destination is equal to N, the efficiency loss due to the packet header is given by:

$$L = (32 + Nx16) / (32 + Nx16 + Nx32 \times F)$$

where F = TDMA frame period

The efficiency loss is shown in the table for both 8 and 16 ms frame periods and for a range of N.

EFFICIENCY LOSS (PERCENT)		
N	F=8ms	F=16ms
5	8.0	4.2
10	6.9	3.6
20	6.4	3.3

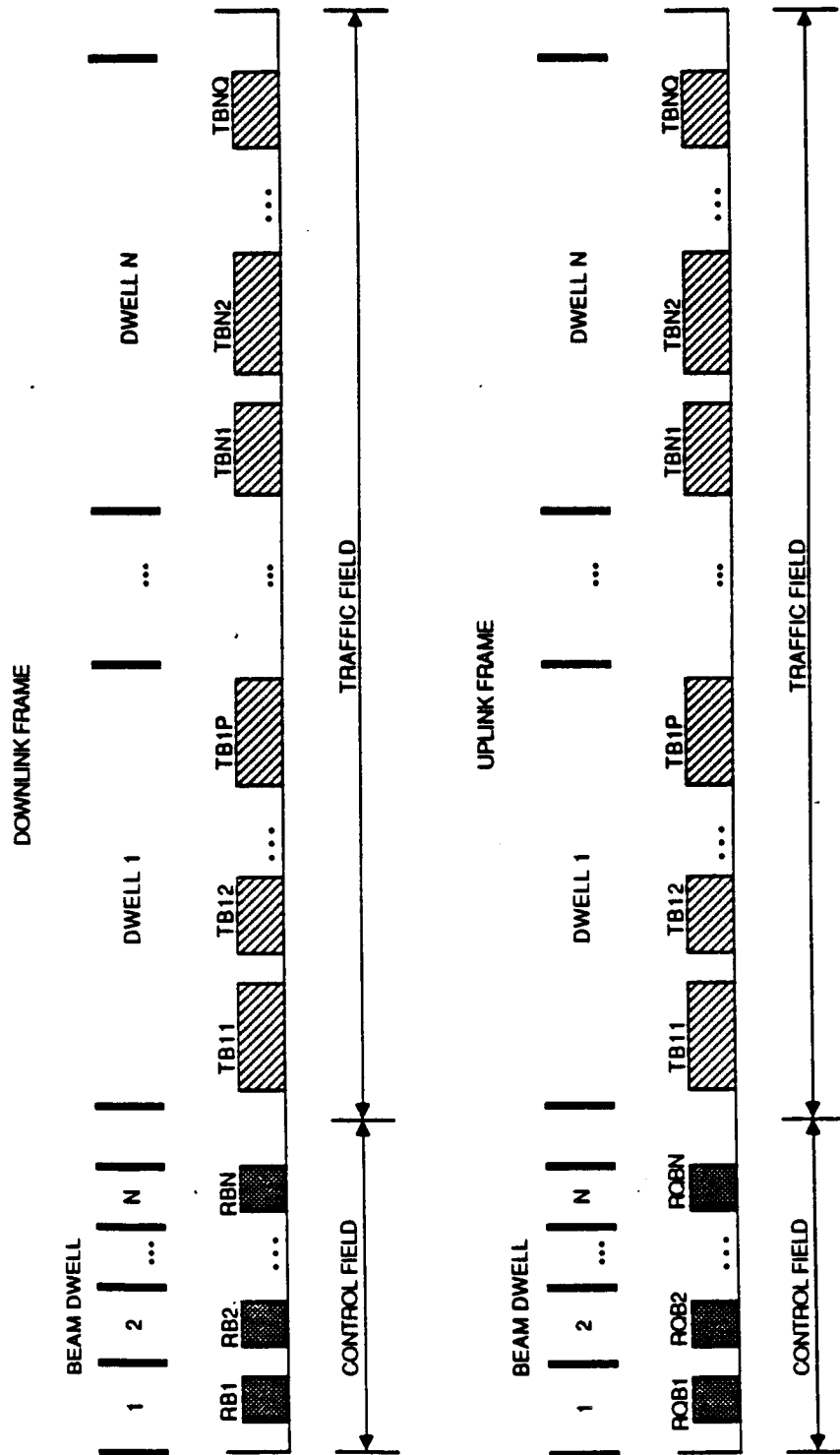


FIGURE 3.11
FRAME FORMAT

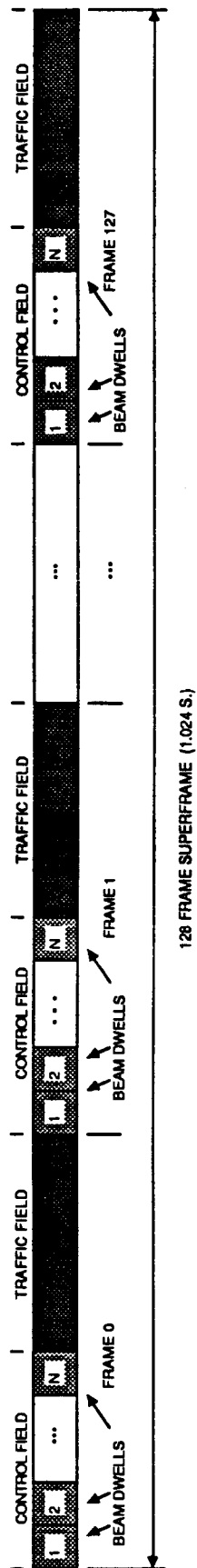
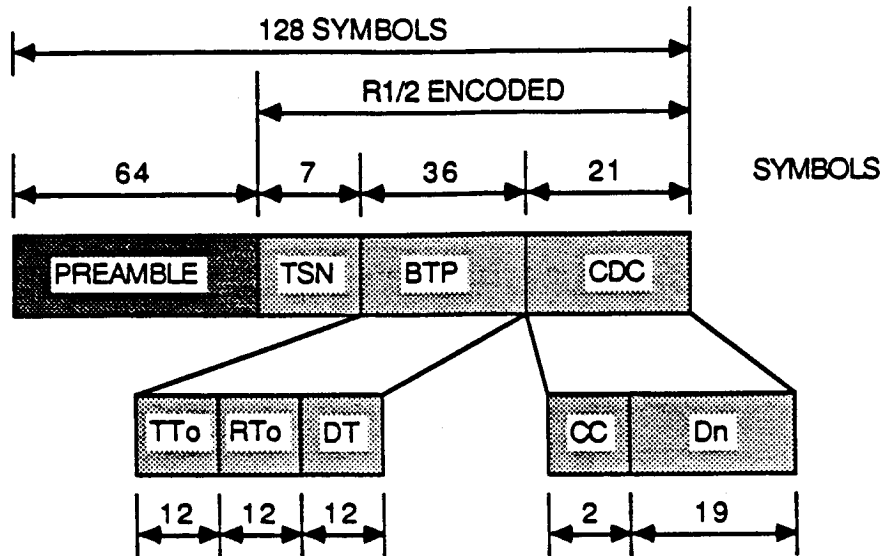


FIGURE 3.12 SUPERFRAME STRUCTURE



DEFINITIONS:

TSN: TERMINAL SHORT NUMBER
 BTP: BURST TIME PLAN
 CDC: CONTROL AND DELAY CHANNEL
 TTo: TRANSMIT BURST POSITION (OFFSET FROM START OF FRAME
 IN CHANNEL INCREMENTS)
 RTTo: RECEIVE BURST POSITION (OFFSET FROM START OF FRAME
 IN CHANNEL INCREMENTS)
 DT: BURST DURATION (GIVEN IN CHANNEL INCREMENTS)
 CC: CONTROL CODE (E.G.. ACQUIRE, SYNC,ETC.)
 Dn: TRANSMIT DELAY

FIGURE 3.13
REFERENCE BURST FORMAT

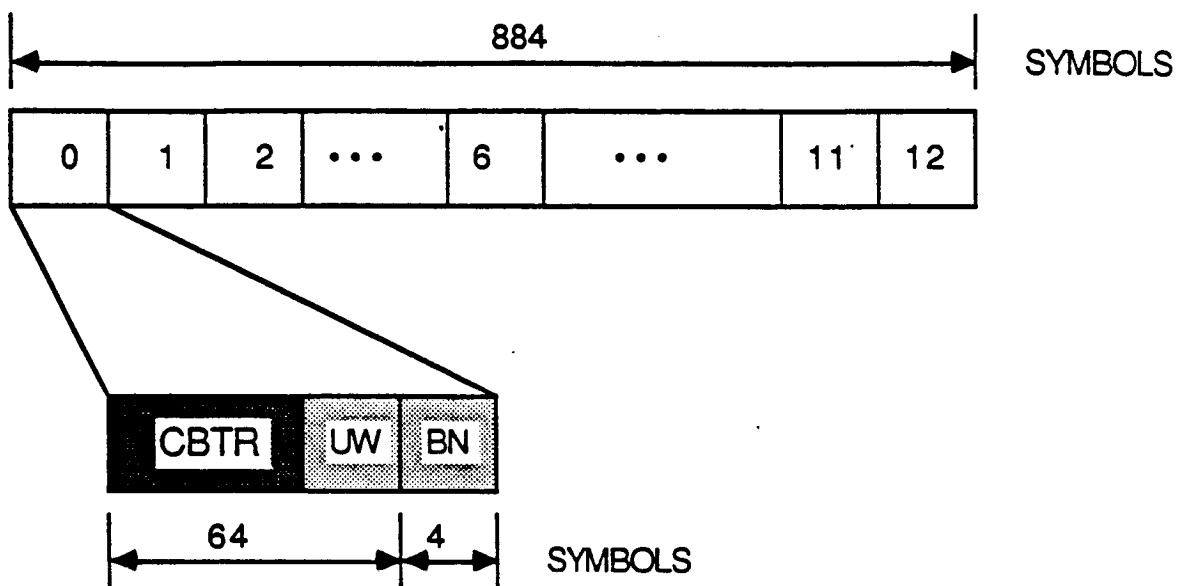


FIGURE 3.14
REQUEST BURST (RQB) STRUCTURE

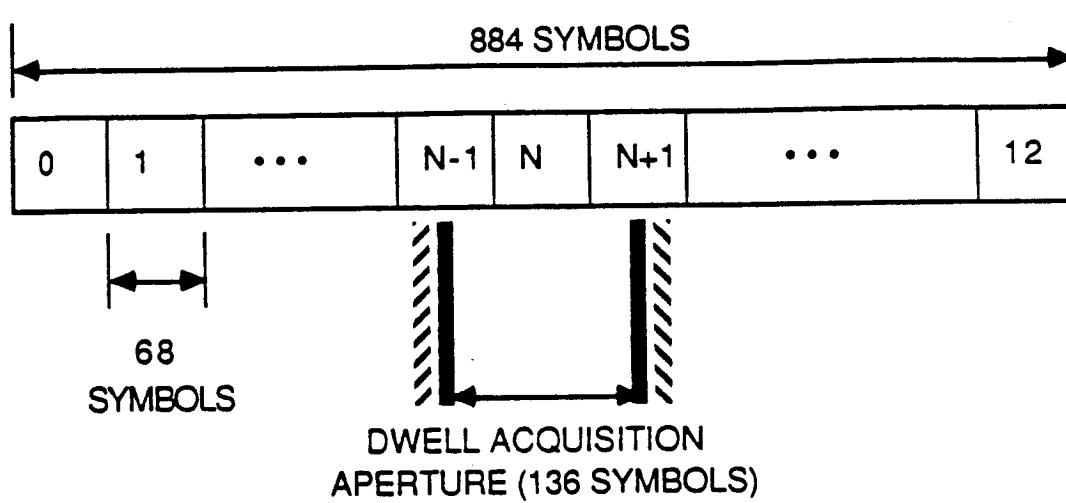


FIGURE 3.15
RELATIONSHIP BETWEEN BEAM DWELL AND SUB-BURST

FIGURE 3.16
SEPARATE INPUT/OUTPUT MEMORY ARCHITECTURE

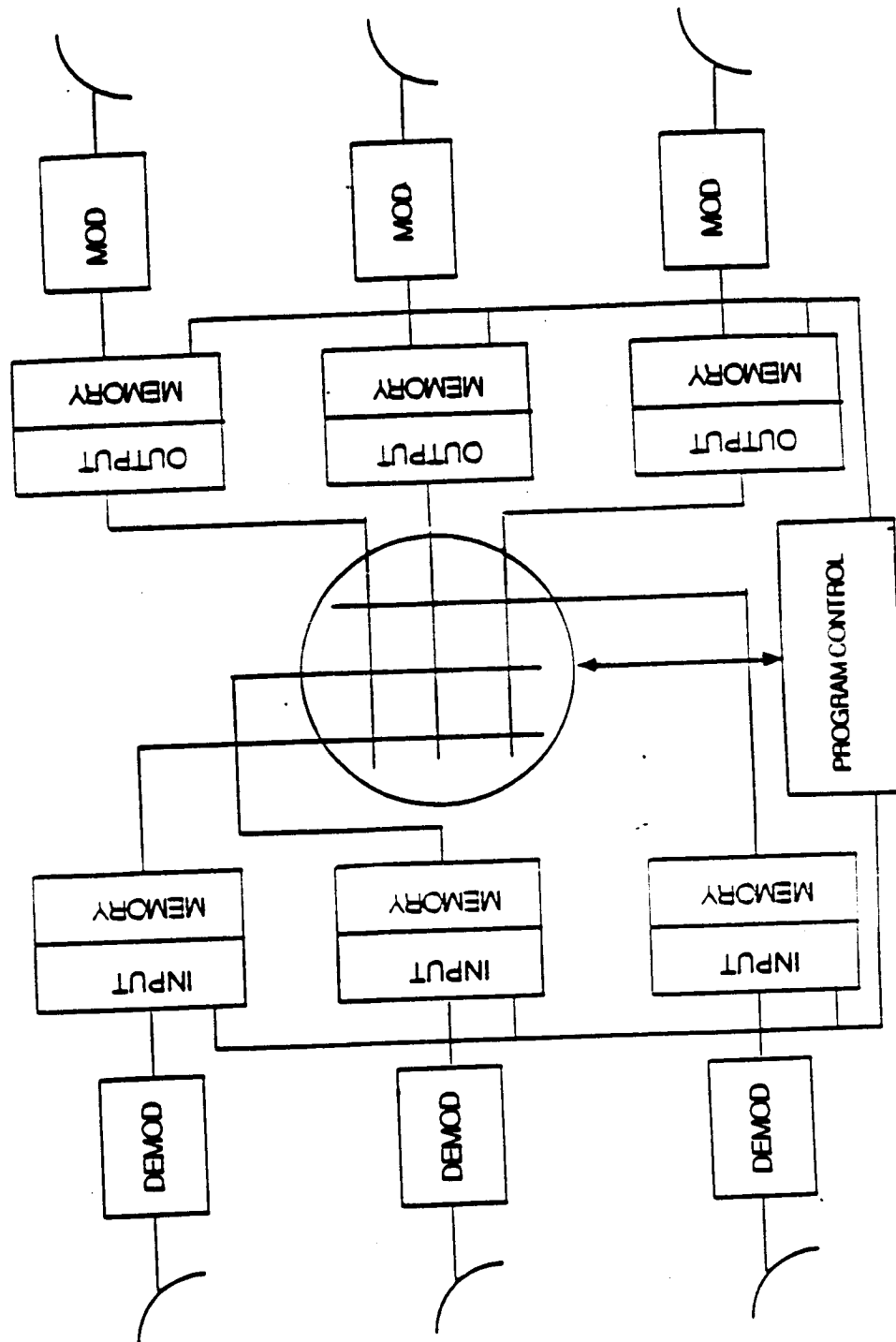


FIGURE 3.17

UNIFIED PINGPONG MEMORY ARCHITECTURE

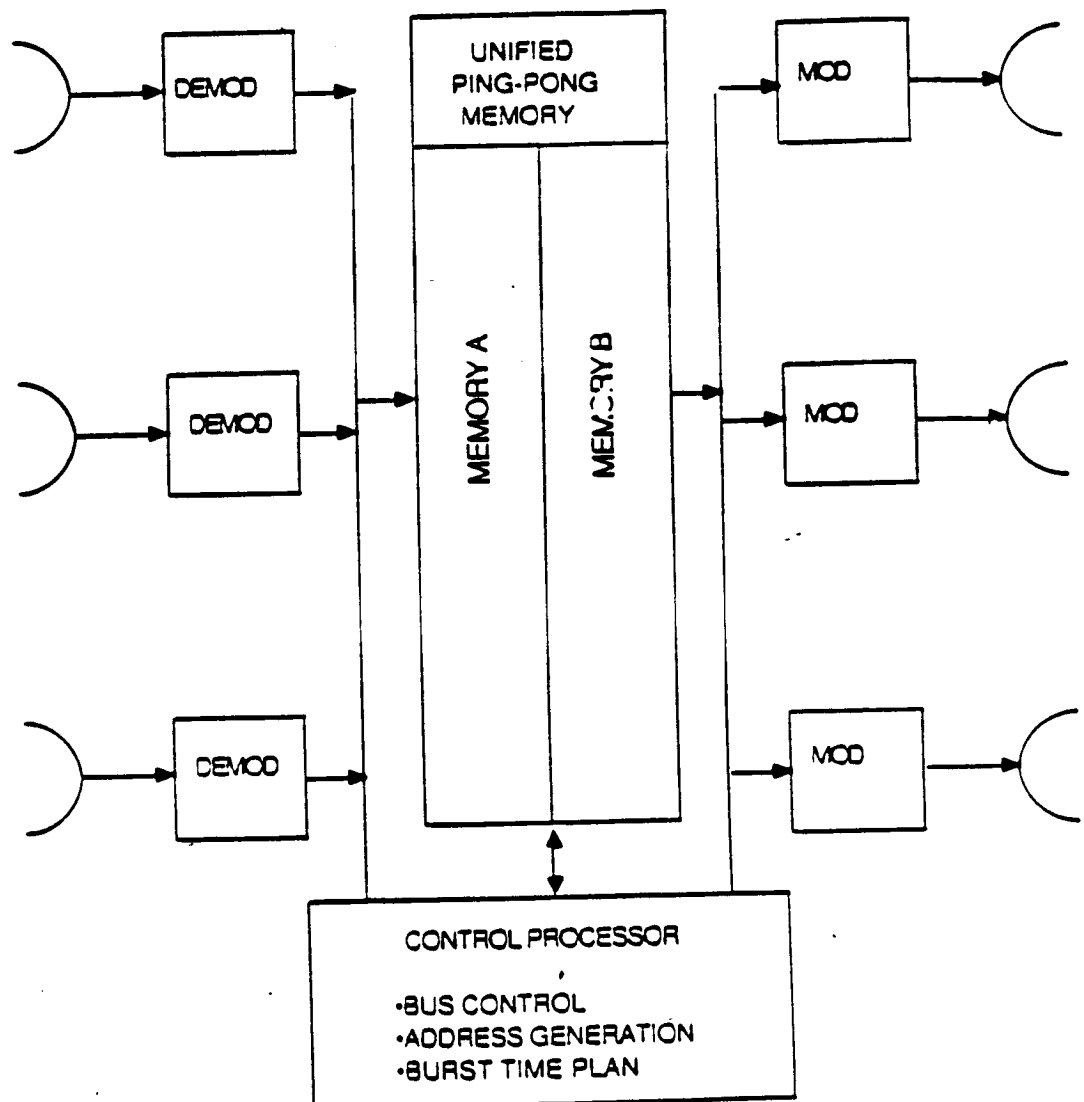
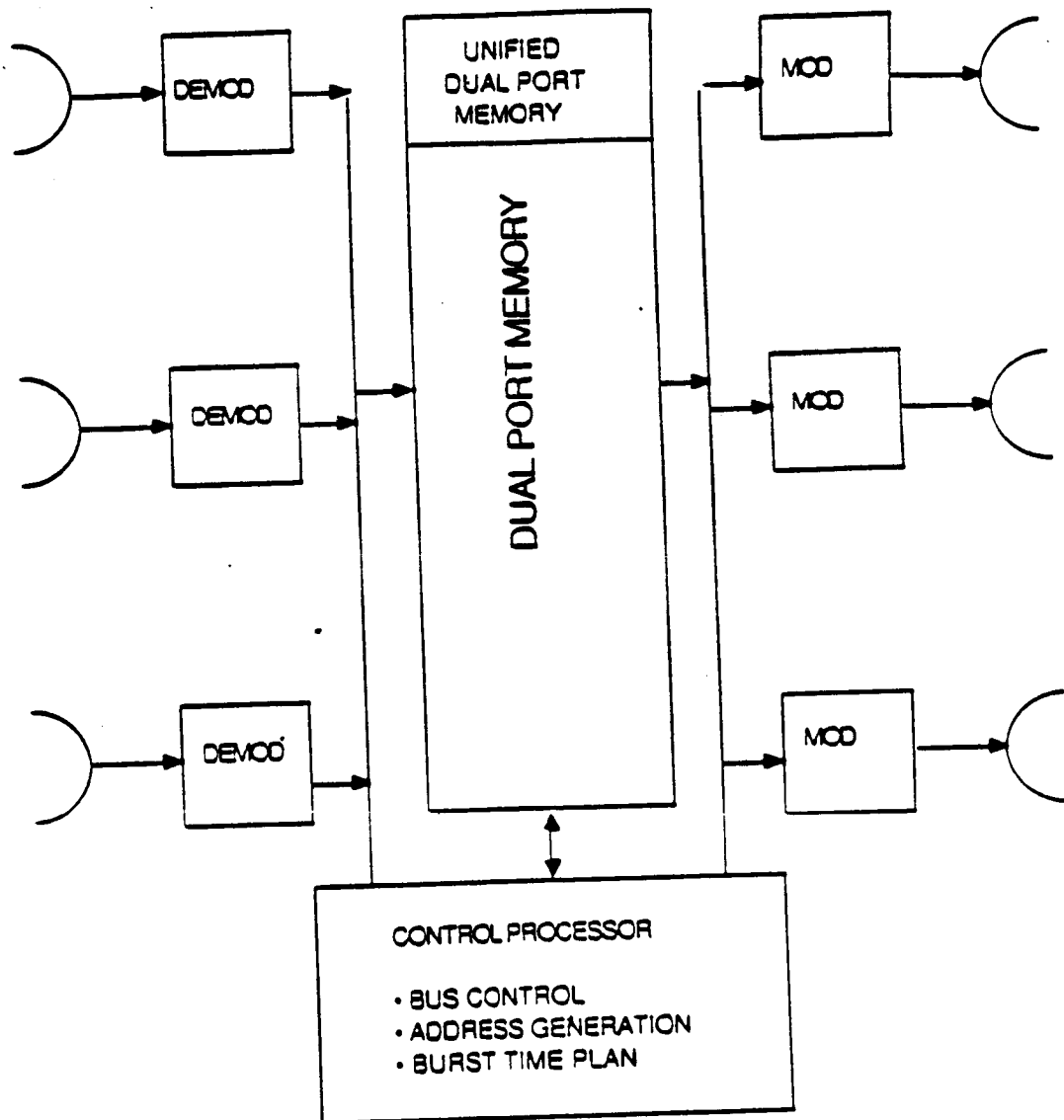


FIGURE 3.18

UNIFIED DUALPORT MEMORY ARCHITECTURE



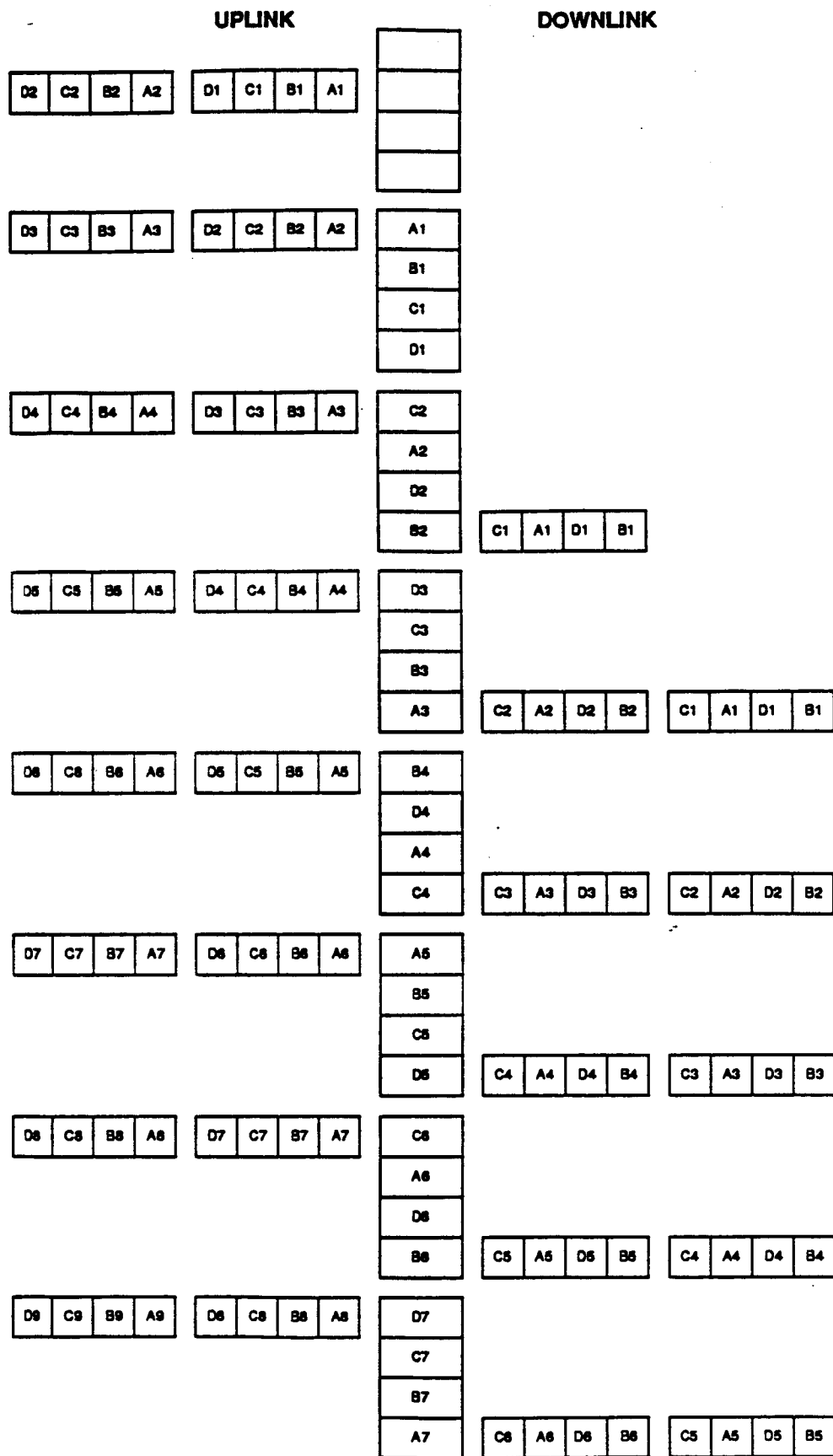


FIGURE 3.19 ON BOARD DUAL PORT SWITCH OPERATION

UPBEAM DESTINATION
ADDRESSES

DOWNBEAM

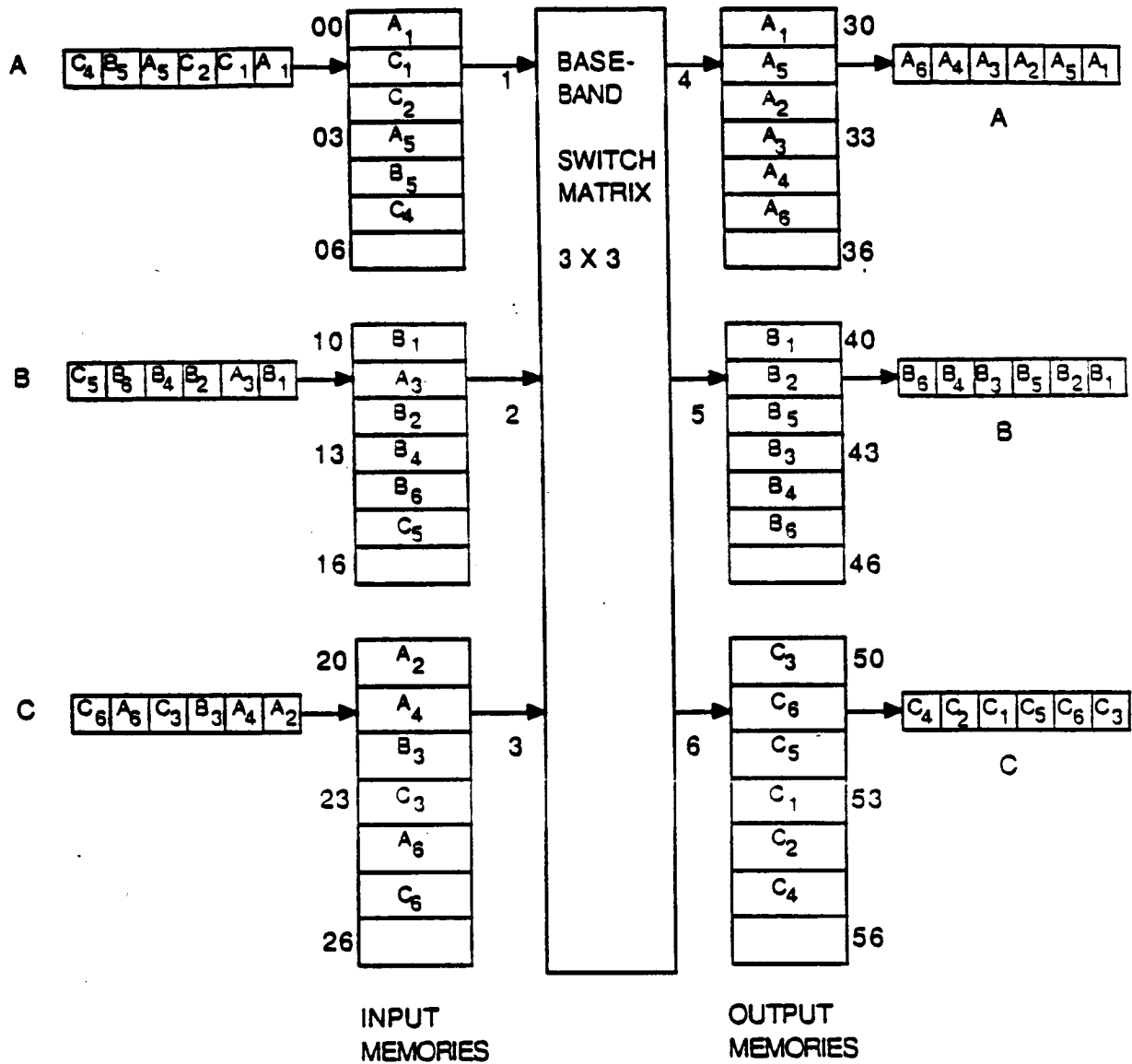
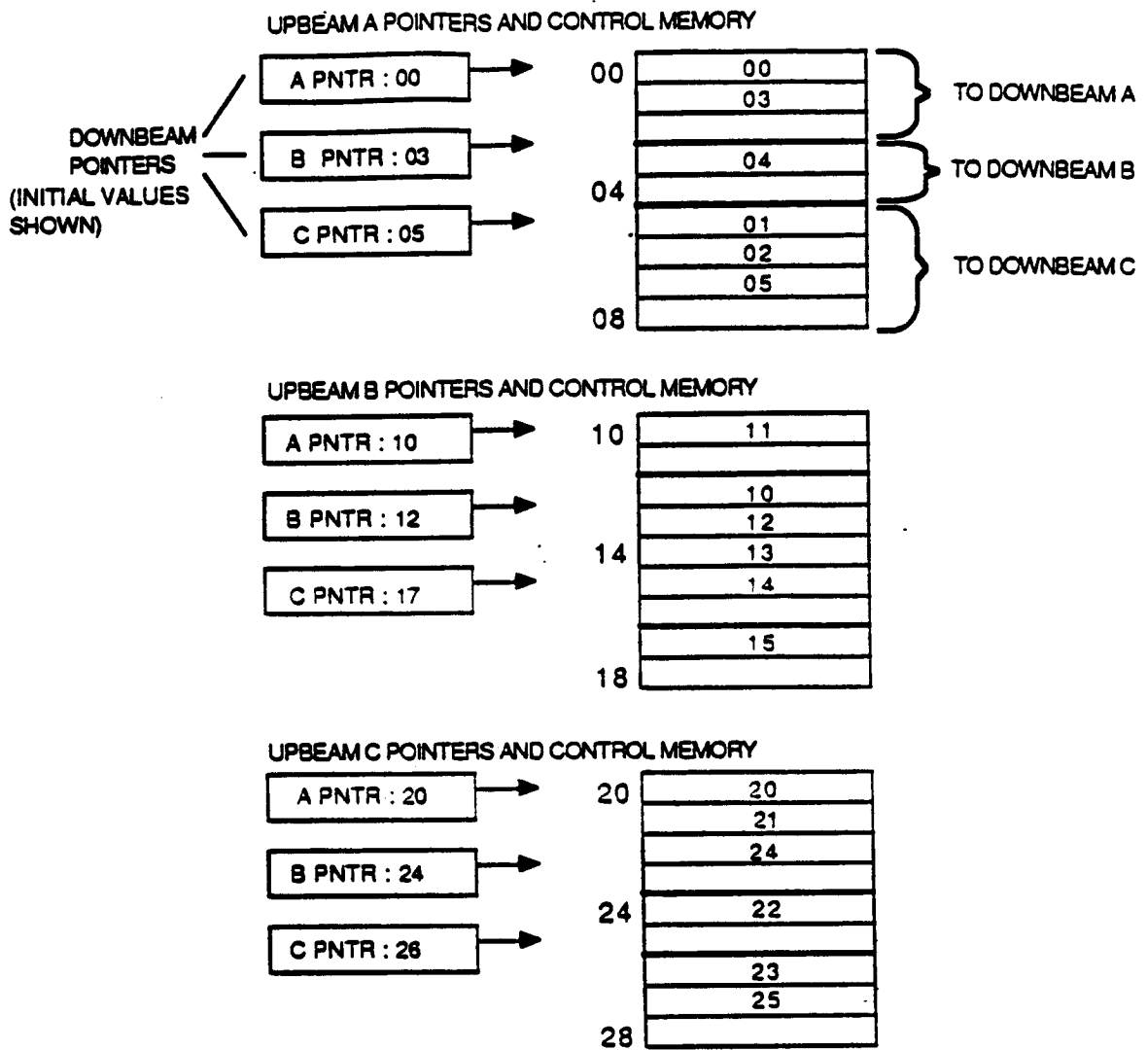


FIGURE 3.20 - SIGNAL FLOW FOR SEPARATE MEMORY ARCHITECTURE
DESTINATION-DIRECTED SWITCHING BETWEEN BEAMS



TO:	SWITCH STATES			INPUT MEMORY ADDRESSES		
	A	B	C	A	B	C
I	1-4	2-5	3-6	00	10	23
I	1-4	2-5	3-6	03	12	25
I	1-4	2-5	3-6	XX	XX	XX
II	1-5	2-6	3-4	04	15	20
III	1-6	2-4	3-5	01	11	22
IV	1-6	2-5	3-4	02	13	21
IV	1-6	2-5	3-4	05	14	24
IV	1-6	2-5	3-4	XX	XX	XX

FIGURE 3.21 - CONTROL MEMORY MAPS AND POINTERS FOR SEPARATE MEMORY ARCHITECTURE OF FIGURE 3.20

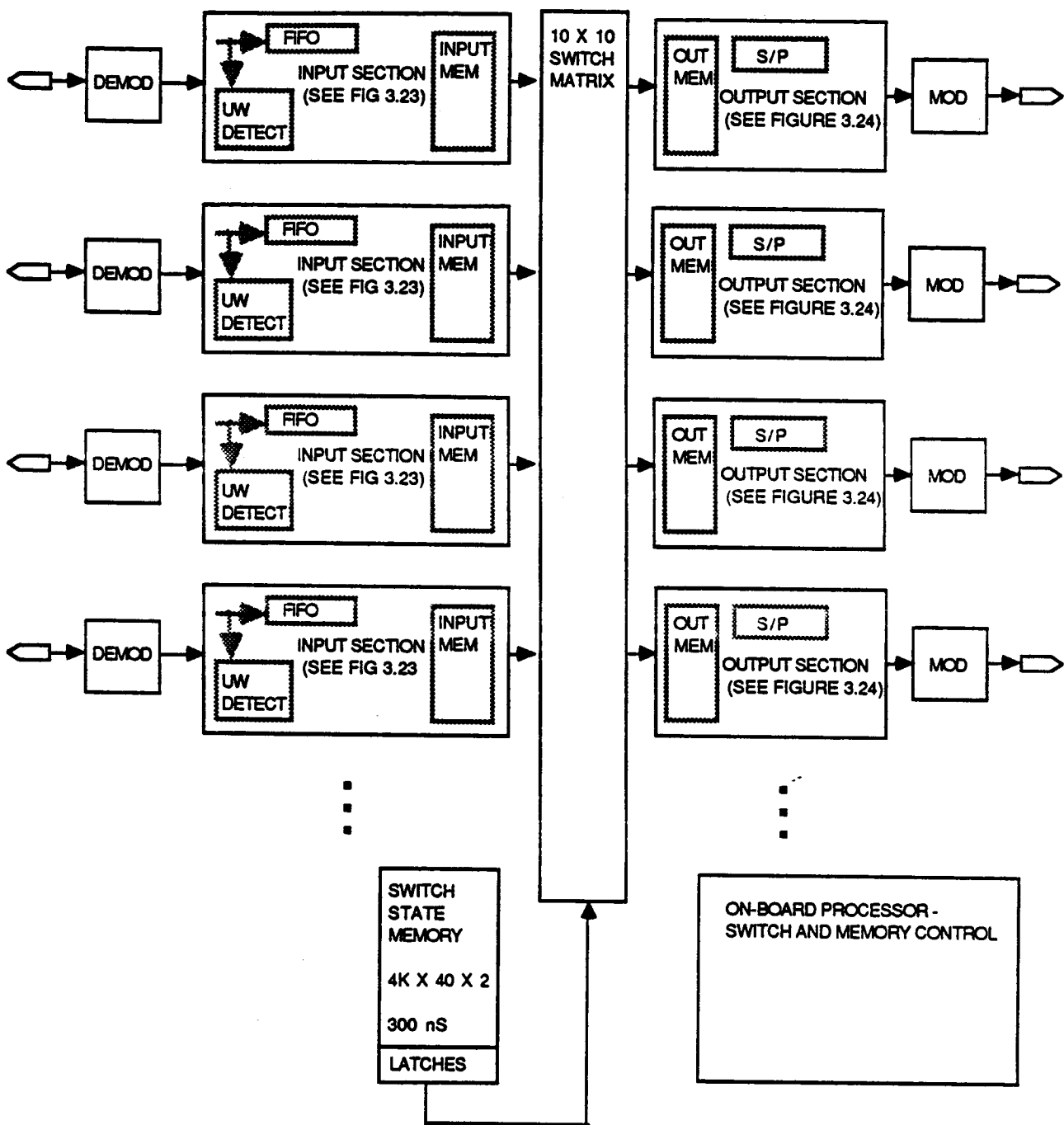
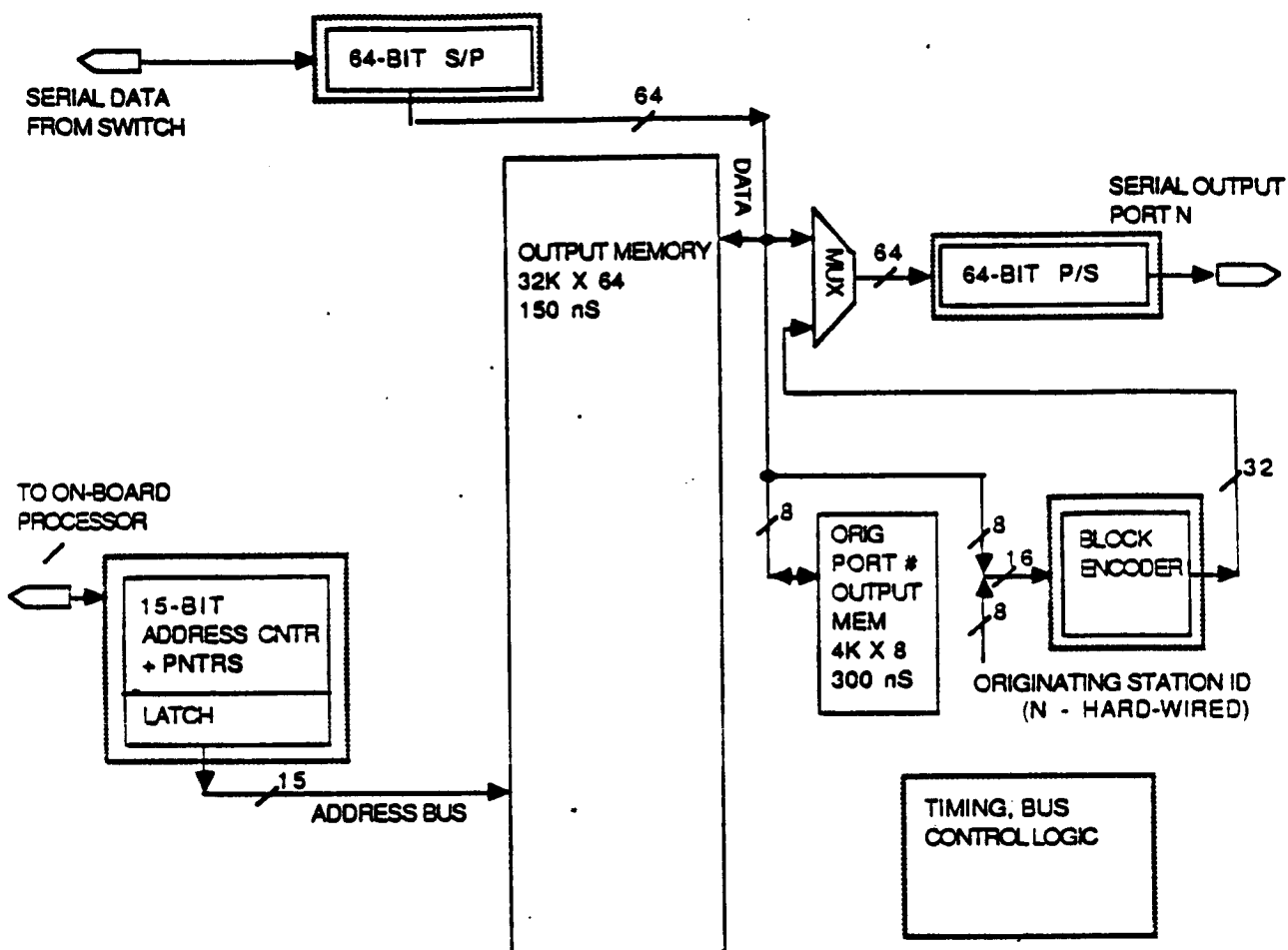


FIGURE 3.22 - SEPARATE MEMORY ARCHITECTURE HARDWARE BLOCK DIAGRAM



NOTE: CUSTOM CHIPS ARE ENCLOSED BY DOTTED LINES

FIGURE 3.24 - DETAILED HARDWARE BLOCK DIAGRAM OF OUTPUT SECTION

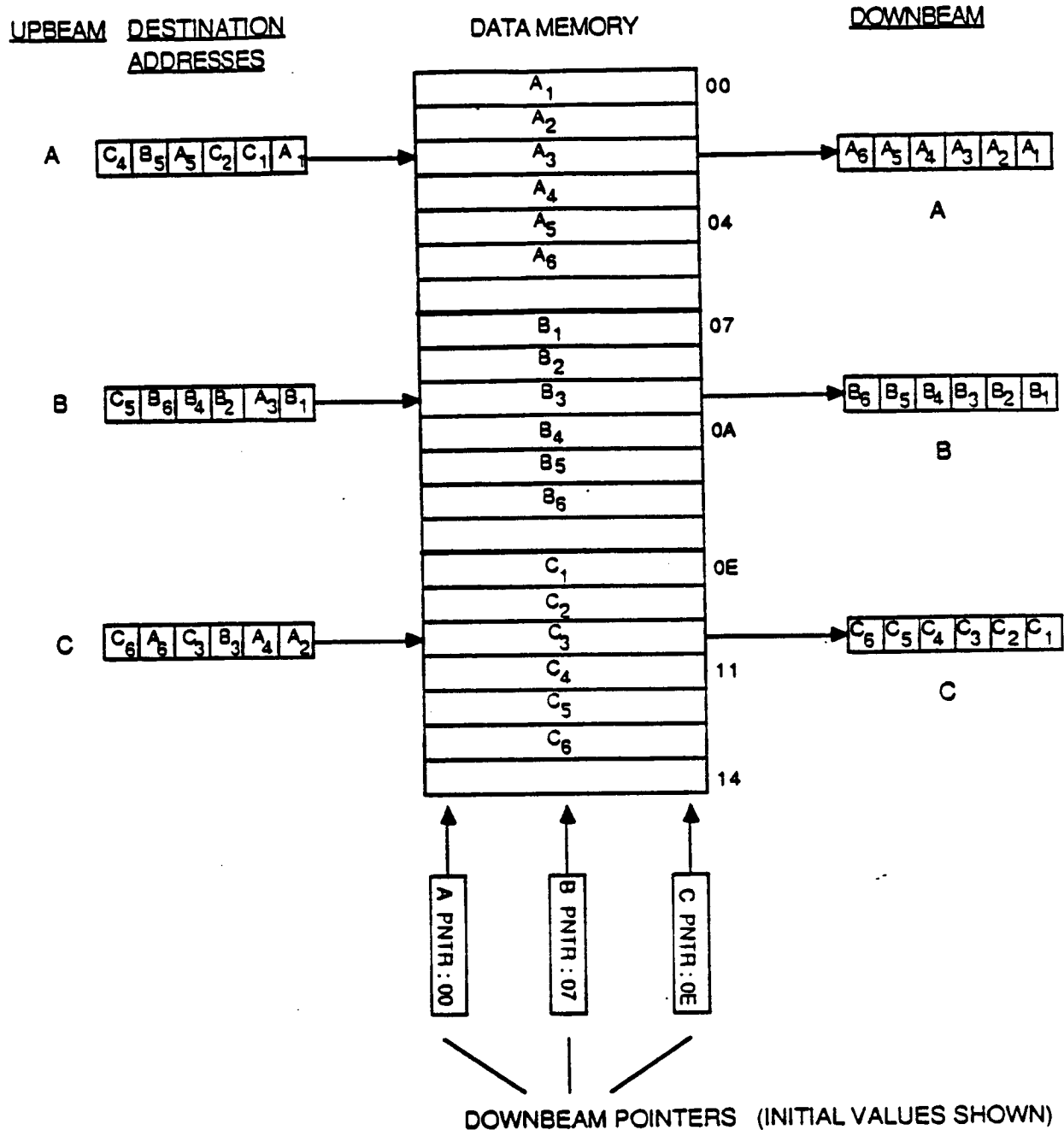


FIGURE 3.25 - SIGNAL FLOW FOR UNIFIED MEMORY ARCHITECTURE
DESTINATION-DIRECTED SWITCHING BETWEEN BEAMS

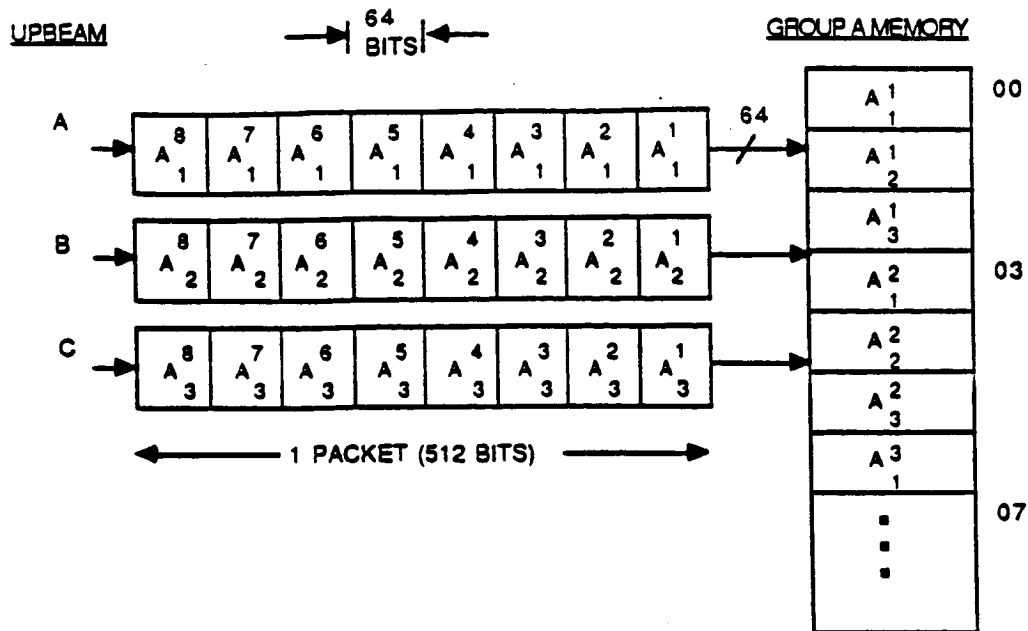


FIGURE 3.26 - SCRAMBLING PROBLEM WITH 64-BIT BUS

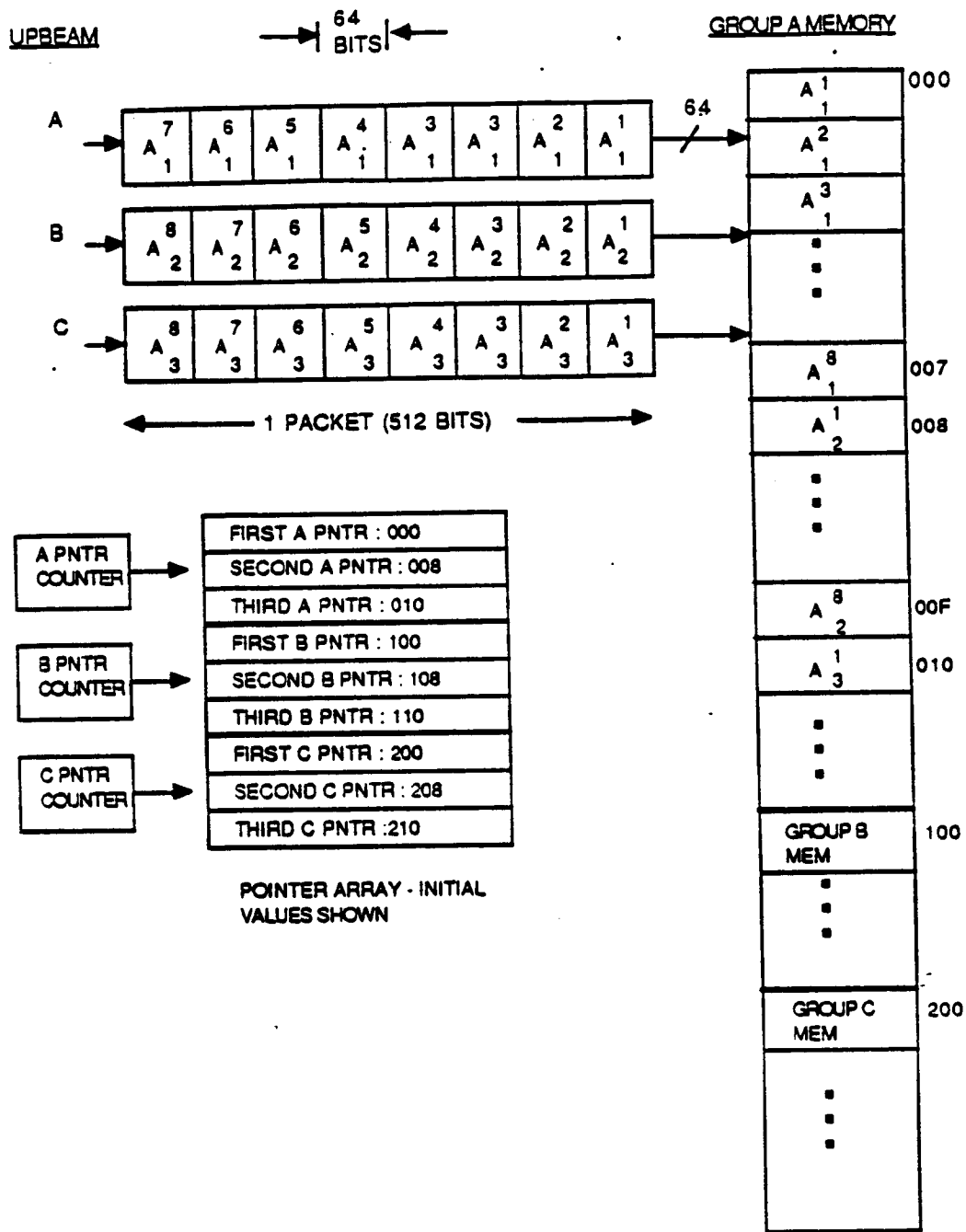


FIGURE 3.27 - DIAGRAM OF POINTER ARRAY TO SOLVE SCRAMBLING PROBLEM

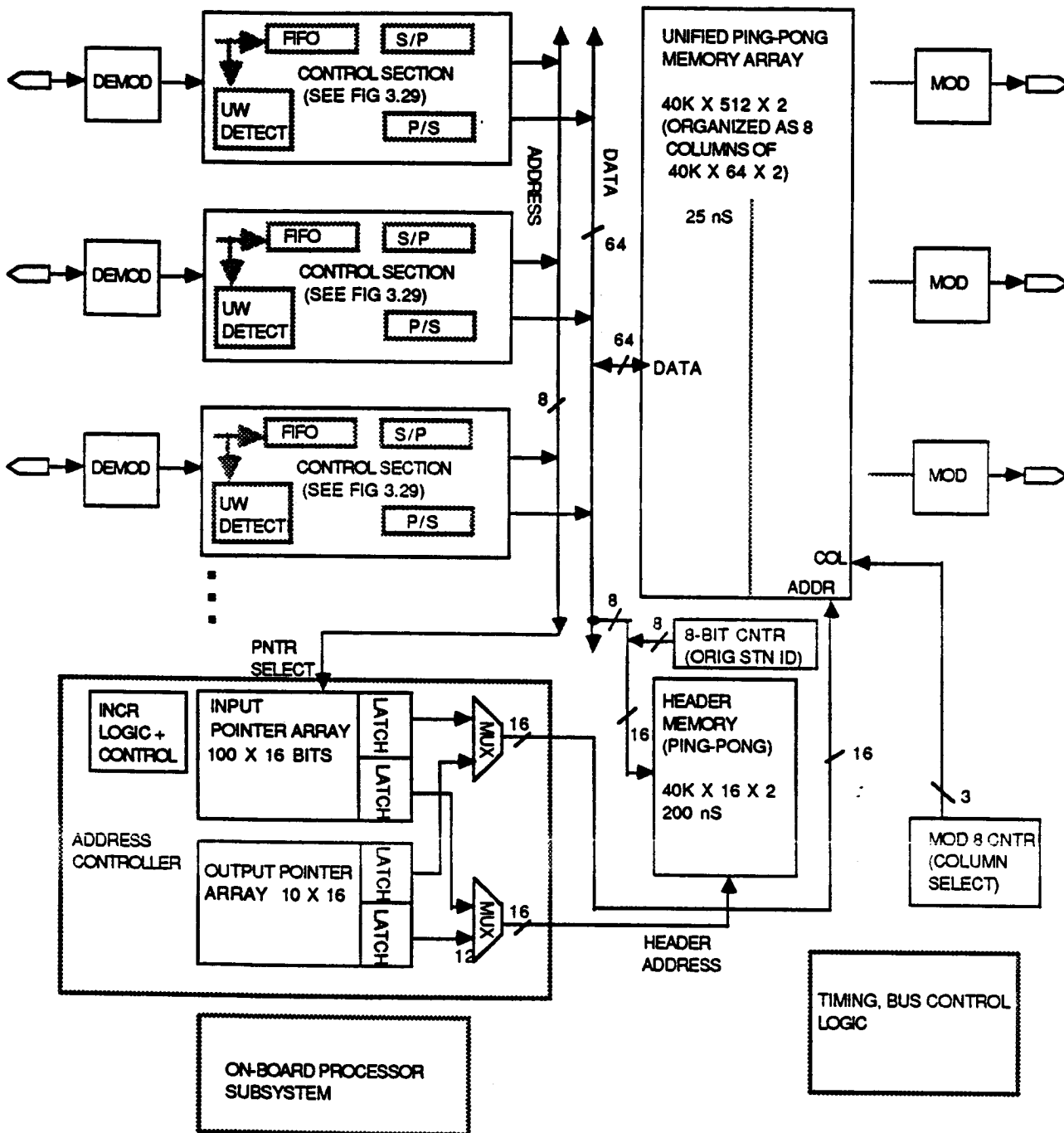
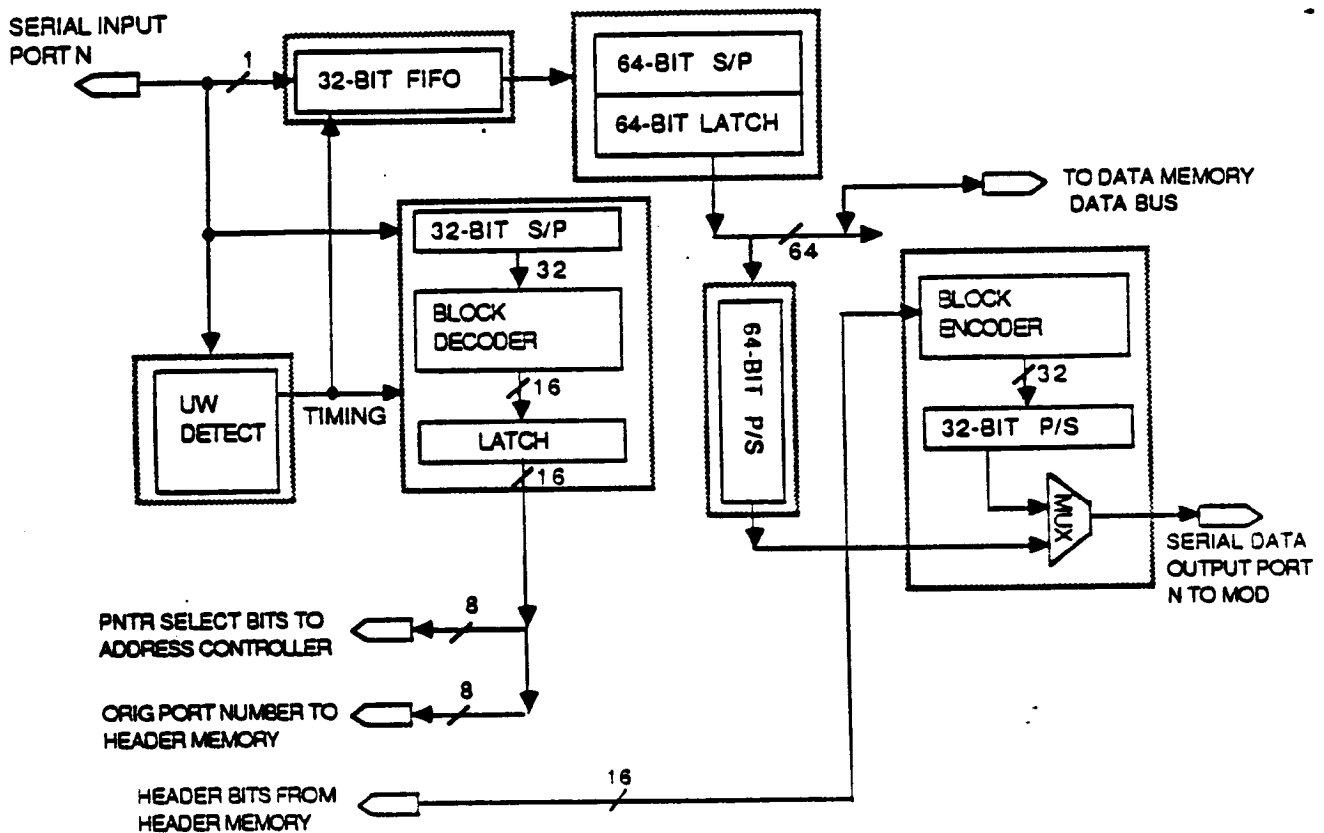


FIGURE 3.28 - UNIFIED MEMORY ARCHITECTURE HARDWARE BLOCK DIAGRAM



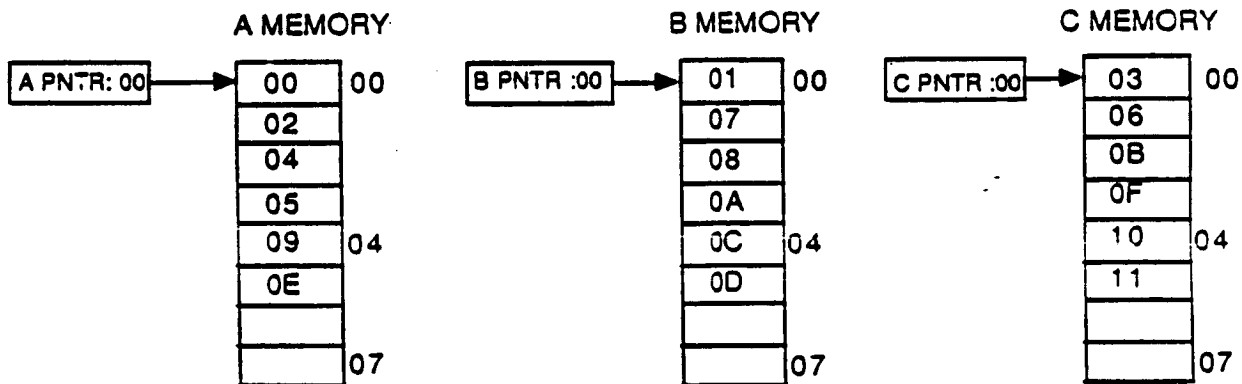
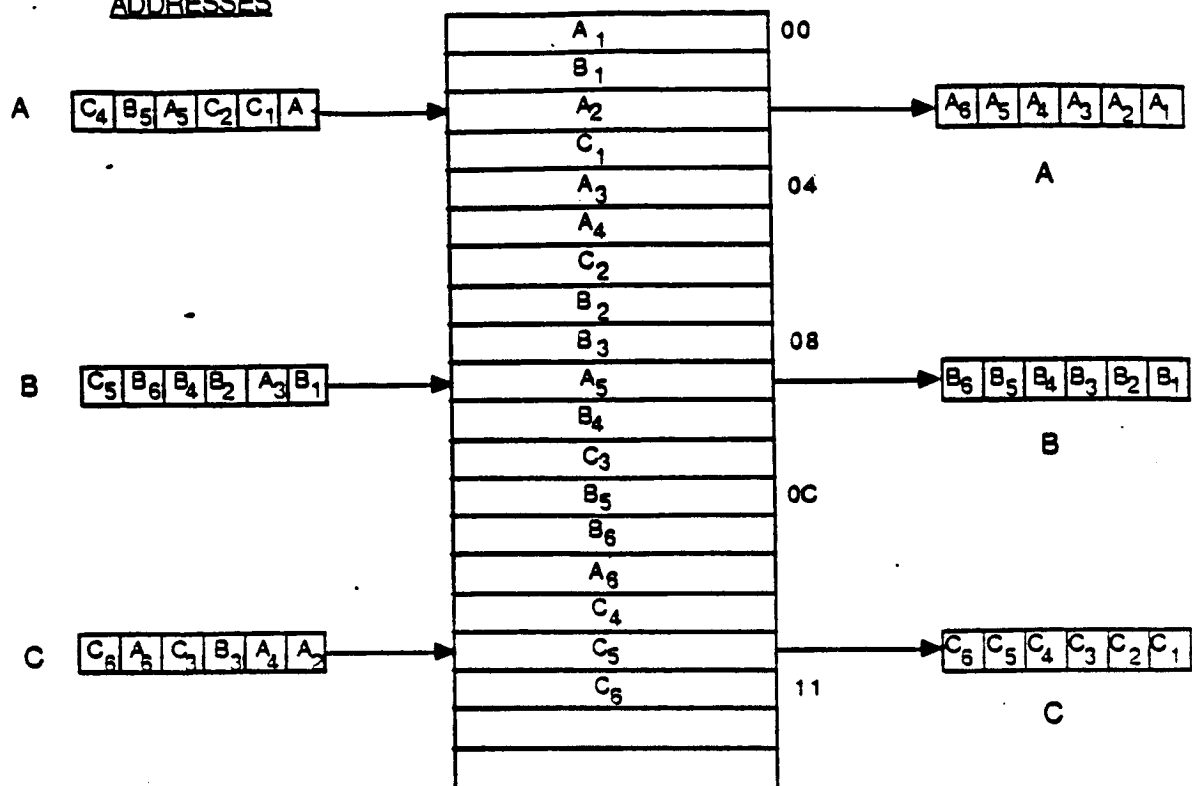
NOTE: CUSTOM CHIPS ARE ENCLOSED BY DOTTED LINES

FIGURE 3.29 - DETAILED HARDWARE BLOCK DIAGRAM OF CONTROL SECTION
UNIFIED MEMORY ARCHITECTURE

UPBEAM DESTINATION ADDRESSES

DATA MEMORY

DOWNBEAM



CONTROL MEMORIES AND POINTERS

FIGURE 3.30- ALTERNATIVE SIGNAL FLOW FOR UNIFIED MEMORY ARCHITECTURE

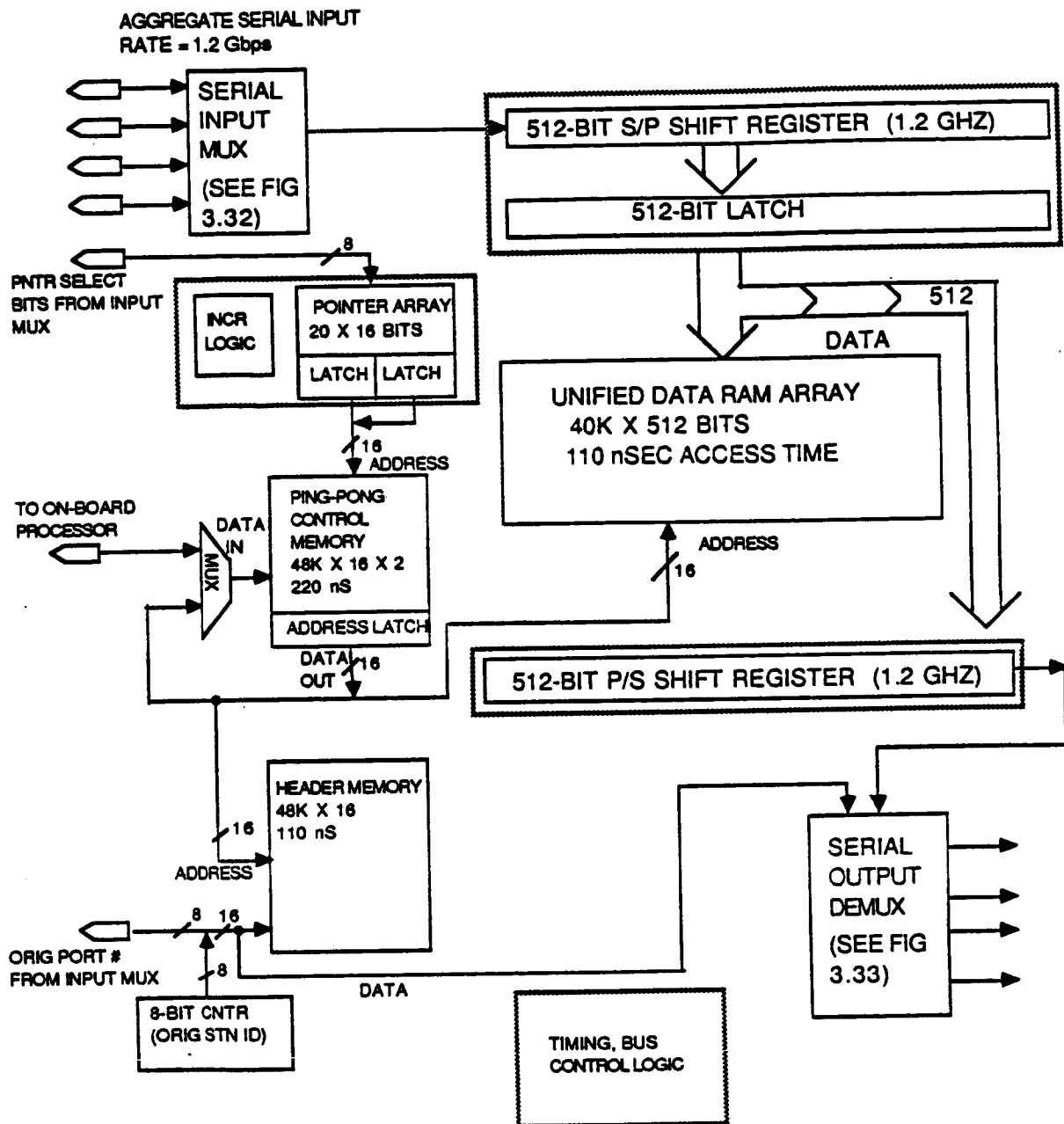


FIGURE 3.31 -ALTERNATIVE UNIFIED MEMORY HARDWARE BLOCK DIAGRAM

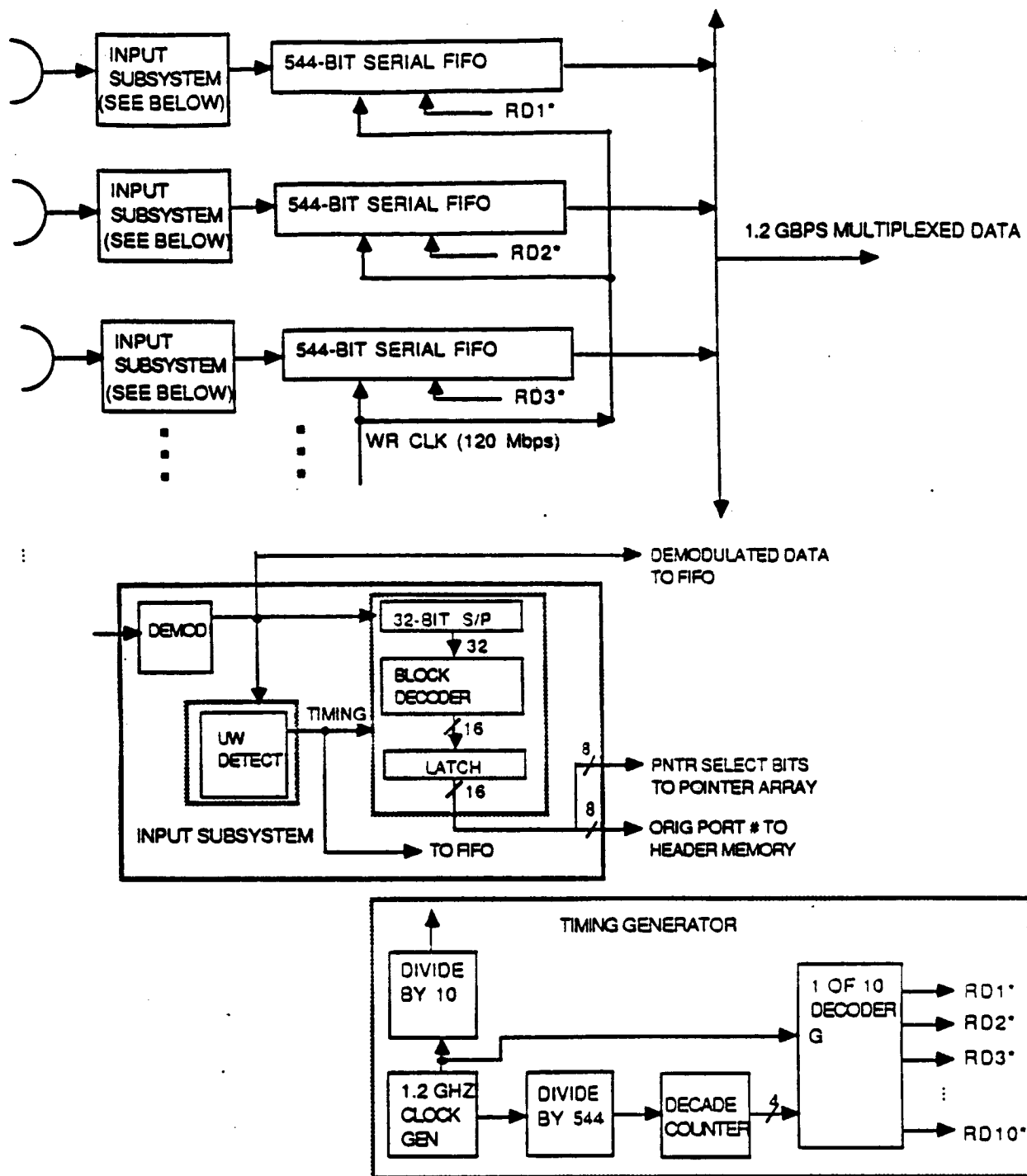


FIGURE 3.32 - BLOCK DIAGRAM OF SERIAL INPUT MUX

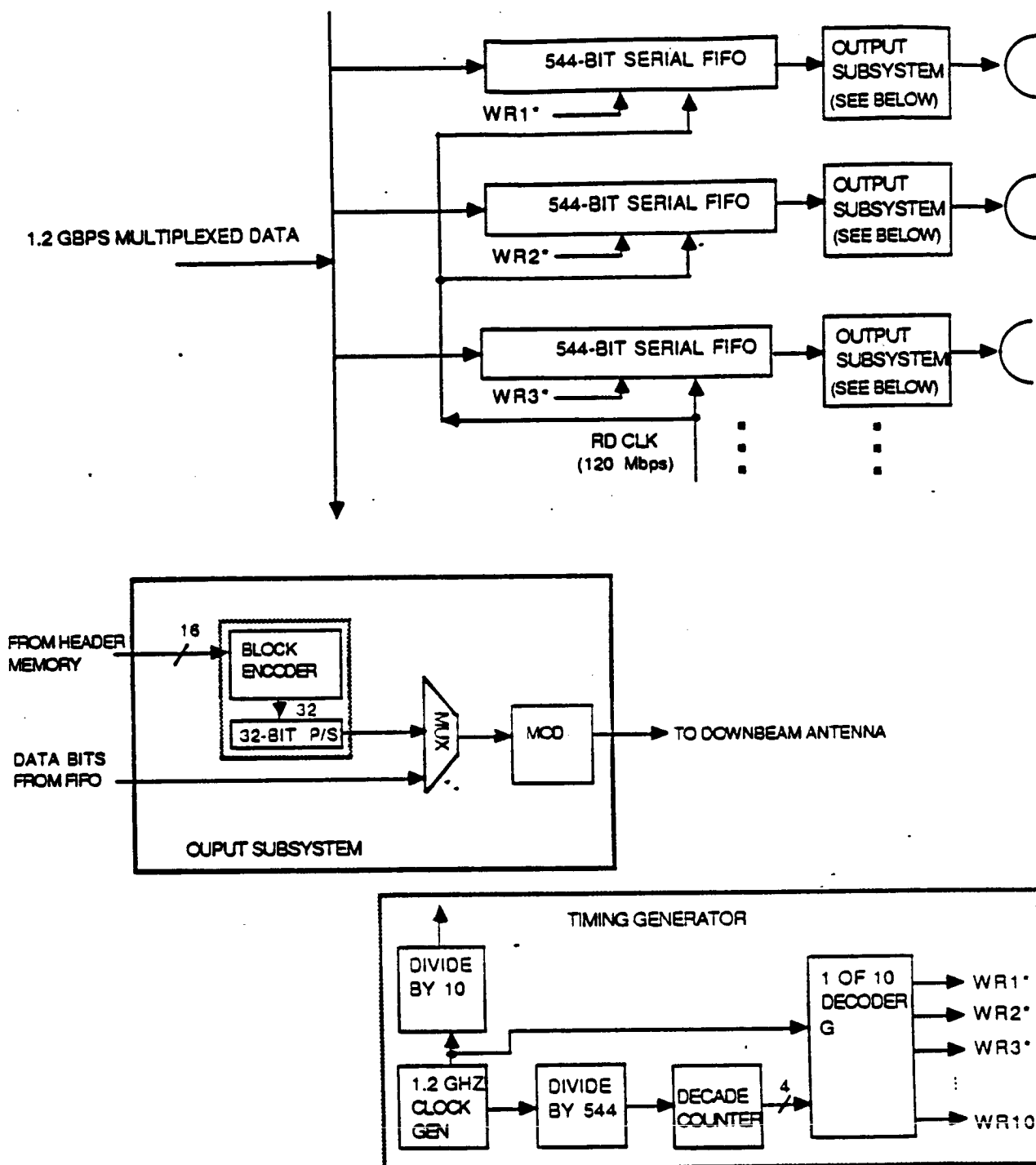


FIGURE 3.33 - BLOCK DIAGRAM OF SERIAL OUTPUT DEMUX

4.0 INTEGRATION OF OTHER SERVICES

The integration of services other than the trunk telecommunications and data services may be accomplished with only minor extension of the onboard architecture discussed in section 3. Two additional services to be examined are the Mobile and Intersatellite Link Services. These will be addressed in the following sections.

4.1 MOBILE SATELLITE SERVICE

Two methods for accommodating the transmission of the destination addressed packets have been described in the foregoing, viz., packet routing and sub-burst routing. Packet routing is the most suitable for thin route terminals using very small antennas such as would be desirable for mobile communications to sea, land and airborne platforms. In such cases, the packets would be carried on low bit rate continuous FDMA carriers that are not shared in the time domain and would be supported in a fixed beam covering a whole area such as CONUS. This would result in the most power efficient earth terminal, a property important for power limited mobile communications. In contrast the destination directed sub-burst method is suitable for earth terminals carrying multiple channels such as those needed for thin and medium capacity telephone trunks. These can operate in a TDMA transmission format served by hopping beams. Onboard the satellite, all channels, continuous and burst, would be routed at baseband by the same destination directed switching machine. Using this approach, the Mobile service can be directly interconnected to the public switched telephone network. The following sections examine how thin-route mobile service can be integrated into the destination directed on board processing architecture. Attention will be focussed on the Land Mobile Service, but the conclusions drawn are applicable to other mobile services, i.e. maritime and air mobile and other thin route services such as CPS business and DAMA telephony.

4.1.1. INTEGRATED FIXED SATELLITE AND LAND MOBILE SATELLITE SERVICES

The subject of a land-mobile satellite system has been studied in extensive detail [11- 14] in which numerous tradeoffs have been performed which lead to a possible system architecture. Drawing upon the results of these studies, a system that utilizes a multiple-access scheme similar to that which was developed for the Mobile satellite

Experiment (MSAT-X) is examined. Since the MSAT-X system does not incorporate on board processing, some modification to the original concept is needed.

The basic network elements of a fully integrated Fixed Satellite service (FSS) and Mobile Satellite Service (MSS) system are given in figure 4.1. The on-board packet processing satellite serves two basic types of stations operating in the FSS, those which interconnect to the public switched telephone network (PSTN) and those which are located on the customer's premises (CPS). The transmission link for this service is at K-band and utilizes hopping beams.

The onboard processor also serves the mobile satellite service at L-band or UHF. For mobile platform antenna design and transmission reasons, UHF band is preferred for mobile communications; however, permission to use UHF in CONUS has not been granted. In this text, for simplicity, mobile services are said to be at L-band. Fixed beams are positioned over the service area which is assumed to be CONUS. The on-board packet processor can serve mobile terminals (MTs) and base stations (BSs) at L-band. Base stations can also be located at FSS K-band stations where feeder links to the MSS occur. Thus, any MT can have direct access into the PSTN by on-board packet routing the call through an appropriate FSS gateway earth station operating at K-band. On rare occasions, a base station operating at L-band might be encountered when a MT transceiver is deployed at a base station. This requires MT to MT(serving as a BS) communications. The on-board processing architecture being studied permits single-hop MT to MT communication.

4.1.2 SYSTEM CHARACTERISTICS

The mobile satellite channels are accessed in frequency rather than time. Each channel is carried as a Single Channel Per Carrier (SCPC). Because of link budget considerations, the nominal carrier bit rate and channel bandwidth should be kept as low as practical. Narrow bandwidth is also essential to packing a sufficient number of SCPC carriers into the very limited L-band spectrum assigned to the service. To accomplish this, voice communications using low rate encoding is required. For the system considered here it is assumed that voice will use 2500 bit/s low rate source coding and this will be rate 1/2 FEC coded to yield a traffic channel rate of 5000 bit/s. The capacity needed to carry the destination address information must be added to get the total channel rate. The total channel rate is a function of the TDMA frame period and the channel bandwidth a function of the TDMA frame period and the modulation

technique. The total channel bit rate is 9000 bit/s for a 8ms frame period and 7000 bit/s for the 16ms frame period. For TDMA frame periods of 8 and 16ms, using BPSK modulation the channel bandwidths are 12 and 9 kHz and using QPSK modulation, the channel bandwidths are 6kHz and 4.5kHz respectively. Separate request channels are used by the MTs to gain access to the satellite and a separate status and signalling channel is received by all MTs that desire to receive incoming calls.

Typical uplink and downlink frequency plans are shown in figure 4.2. A "Channel Request" is made by a MT using a slotted Aloha random access method. The request channel frequency is also selected on a random basis by the MT. Since the frequency boundary between the request and information channels dynamically changes depending on the relative instantaneous loading between the two sets of channels, the MTs must be informed of the boundary location between the request channels and the transmit information channels. This information is conveyed over the status and timing channel to which all the MTs listen. This channel also provides the timing markers for slotted Aloha transmissions. If desired, the MTs can scan the active signalling channels to receive incoming calls.

4.2 CALL SET-UP PROCEDURES

Three basic types of call set-up procedures are needed in this system:

1. Call originating at MT and destined to BS or gateway in FSS,
2. Call originating from BS or gateway in FSS and destined to MT,
3. Call from MT and destined to MT which may be a MT transceiver operating at L-band and serving as a BS.

4.2.1 Calls Originating at MT to BS or Gateway

The call set-up procedure for calls originating at a MT and destined to either a BS or FSS gateway station is as follows:

- MT sends a request message (RQM) over a request channel using slotted Aloha.
- The on-board packet processor (OBPP) assigns a channel comprising a frequency pair (transmit/receive) from the pool of information channels to the requesting MT.
- The MT either receives a frequency pair of channels within a specified period of time or assumes that its request was not received by the OBPP because of packet collision.
- If the MT receives the satellite channels it proceeds as normal by sending a call set-up message (CSM) packet in an identical manner to that used for the FSS. These procedures are described in Section 3.1.

- If the MT does not receive the pair of channels, it continues to send request messages in a random fashion until it receives a pair of channels.

4.2.2 Calls Originating at BS or Gateway to MT

The call set-up procedure for a call originating at a BS or Gateway station in the FSS with a MT destination is as follows:

- BS or FSS places a call in the conventional manner using a CSM in one of its assigned satellite channels (time slots).
- The OBPP reads the header and determines that the destination is a MT as indicated by its destination address.
- The OBPP signals the called MT of an incoming call and assigns the frequency pair of channels over which the call will be carried. This information is conveyed over one of the signalling channels that is currently in use.
- The MT tunes to the assigned channel pair.
- The OBPP sends the CSM over the assigned channel pair.
- Normal packet flow, as described in Section 3.1, continues until the call is terminated.
- Upon call termination, the frequency pair is returned to the pool of unused frequencies and is available for use on another call.

4.2.3 Calls Originating at a MT Destined to a MT

The call set-up procedure for calls originating at a MT and destined to another MT is a combination of the above two procedures and is as follows:

- MT sends a request message (RQM) over the request channel using slotted Aloha.
- The OBPP assigns an information channel to the requesting channel.
- Once that the originating MT has successfully obtained a pair of information channels, it proceeds as normal by sending a CSM packet.
- The OBPP reads the header and determines that the destination is a MT as indicated by its destination address.
- The OBPP signals the called MT of an incoming call and assigns a pair of frequencies over which the call will be carried. This information is conveyed over one of the signalling channels that is currently active.
- The MT tunes to the assigned pair of information channels.
- The OBPP sends the CSM to the called MT over the allocated channel pair.
- Normal packet flow continues, according to the procedures described in Section 3.1, until the call is terminated.
- Upon call termination, the two channel pairs are placed back into

the pool of unassigned frequencies and are available for use on another call.

4.3 IMPACT ON THE ON-BOARD PACKET PROCESSOR

4.3.1 INTEGRATION OF FSS AND LMSS

A block diagram of the onboard packet processor that provides integrated FSS and MSS is given in Figure 4.3. The L-band fixed beams, the L-band receiver and HPA are RF components that need to be added to the original design concept. The demods and mods are all SCPC and operate at low bit rates in a frequency division multiple access (FDMA) mode. The outputs of the SCPC demods are aggregated in a time division multiplexer which translates the frequency multiplexed satellite channels into time multiplexed satellite channels. Because the MSS channels operate at lower bit rates than the FSS channels it is necessary to add dummy bits within the traffic portion of each packet when going from MSS to FSS channels and remove dummy bits when going from FSS to MSS channels. Once this is done, the MT (MSS) information channels are indistinguishable from those of the FSS and can be treated by the OBPP without special consideration. The demods, which are allocated to the request channels and mods which are allocated to the status and signalling channels, must be treated separately since they are not handling the normal packets.

At the output of the OBPP, the TDM information channels are demultiplexed and the time slot channels are translated into frequency slot channels. This is accomplished by arranging the time slots in the OBPP in a way that the demultiplexed channels will occur at the input to the modulator having the proper output frequency and at the low FEC coded bit rate of the MT channels. This is carried out by the OBPP in the same way that it handles all other packets, i.e. it routes packets into their proper time slots. Since the OBPP operates only on the packet headers, MSS information packets are indistinguishable from the FSS packets and are handled identically. The packets associated with request, status or signalling are handled separately.

4.3.2 MSS IMPLEMENTATION

Figure 4.4 is a block diagram of the additional implementation needed to incorporate the MSS. The aggregate information rate presented to the MSS processor to handle the request, status and signalling packets for assignment of the MSS carriers is very low, on the order of 10 kHz. The

speed of the associated processor memory is essentially determined by this aggregate rate. The exact speed depends on the maximum number of request channels that are to be accommodated. The power requirements and complexity of this processor are expected to be small compared to the OBPP. The multiplier and demultiplexer needs to provide a dynamic boundary to accommodate changing the ratio between the information channels and the request channels and the status and signalling channels. The dynamic boundary in the multiplexer is used to segregate request channels destined to the MSS processor from the MSS information channels that are destined to the OBPP. In the demultiplexer, the dynamic boundary combines the status and signalling channels provided by the MSS processor with the MSS information channels provided by the OBPP.

4.3.3 DIFFERENCE IN TRAFFIC BIT RATES OF MSS/FSS LINKS

The system must provide a means to cross connect MSS and FSS links and to accommodate the difference in traffic bit rates. A means for accomplishing this is now discussed.

MSS will incorporate low bit rate voice coding to carry voice messages. The MSS channels should operate at a transmission rate that is an integer submultiple of 32 kbit/s so that each packet carries an even number of bits. This must be done so that the MSS packets can be aligned with the FSS packets in the onboard baseband processor. In general, this results in rates given by the relation $2n/T_F$ where T_F is the TDMA frame period and $n = 1, 2, 3, \dots$. This choice is based on carrying 2 bits per symbol using QPSK and does not prohibit the use of BPSK on the LMSS links. The resulting rates are integer multiples of 250 and 125 Hz for frame periods of 8 and 16 ms respectively. This excludes rates such as 2400, 4800 and 9600 bit/s in favor of rates such as 2500, 5000 and 9750 bit/s.

MSS transmission would be in terms of a single channel per packet with a frame duration equal to 8 or 16 ms comprising a 32 bit, rate 1/2 coded packet header and a traffic portion containing $R_c T_F$ bits where R_c is the coded channel bit rate. Thus, for a voice coder operating at 2500 bit/s, 40 or 80 coded traffic bits per packet would occur for the 8 or 16 ms frames respectively. To this would be appended the 32 bit destination address header yielding a total length of 72 or 112 bits respectively which require transmission bit rates of 9000 or 7000 bit/s respectively. Based on a 30% guard band between SCPC MSS carriers, transmission channel spacings of 12 kHz or 9 kHz would result respectively using BPSK

modulation or 6kHz or 4.5kHz using QPSK.

The MSS carriers would be demultiplexed and demodulated onboard to baseband without decoding of the traffic. A digitally implemented onboard multichannel demultiplexer/demodulator processor such as that studied under NASA LeRC contract NAS3- 24885 could be used for this function. The packet headers would be processed in the same way as for FSS. The traffic portion would be multiplexed onto a 32 kbit/s downlink carried in the TDMA packet format. Since the transmission rate on the FSS channels is much higher than on the MSS channels, less bits are used on the MSS channels and the unused bits in the FSS packet would be dummies. It is up to the processor in the earth station to demultiplex the MSS channel bits from the FSS packets and either transcode them to a standard telephone system code such 32 kbit/s ADPCM or to convert them to analog voice or to transport the low bit rate code to its destination where it is decoded.

Transmission in the reverse direction, i.e. FSS to MSS, is accomplished by reversing the steps. The low bit rate MSS signal padded with dummy bits is carried to the satellite on 32 kbit/s FSS uplink packets where they are demodulated, demultiplexed, rate conversion buffered and routed to the MSS downlink modem operating at the appropriate downlink frequency.

4.3 INTERSATELLITE LINK OPERATION

Important factors regarding the implementation of the intersatellite link are now considered. From the networking point of view, it is important to direct attention to the needs of the onboard intersatellite link interface. The most important property of the intersatellite link influencing the interface is variation in the path length between the satellites. This problem is the same whether the link is a short or a long one. If the distance between satellites are held to a tolerance of $\pm\theta$ degrees, then the variation in distance can be as great as 9.9 θ ms max. peak-to-peak. Thus, if the satellites are held to a tolerance of ± 0.1 degrees, the path length can vary by 0.99ms max. peak-to-peak, but if the tolerance increases to 1 degree the path length change increases to 9.9ms max-peak to-peak. It is also possible to fly two satellites in formation to decrease the max. peak-to-peak intersatellite path length variation, but this increases position keeping fuel consumption in the trade.

To be properly synchronized the digital signals on each satellite will require buffering of the number of bits occupying the amount of time equal

to the max. peak-to-peak variation in each direction of transmission or twice the amount in one direction. If TDMA systems are used on both of the satellites, additional precautions are needed to maintain the discipline of the TDMA frame alignment. The problem is similar to that encountered at an earth station where the alignment between the TDMA frames and the terrestrial digital multiplex frame needs to be maintained. Methods for accommodating the variation are discussed in Chapter 8 by S. J. Campanella of a text edited by K. Feher entitled Digital Satellite Communications published by Prentice Hall, 1984. The intersatellite links will have to have similar Doppler/Alignment buffers.

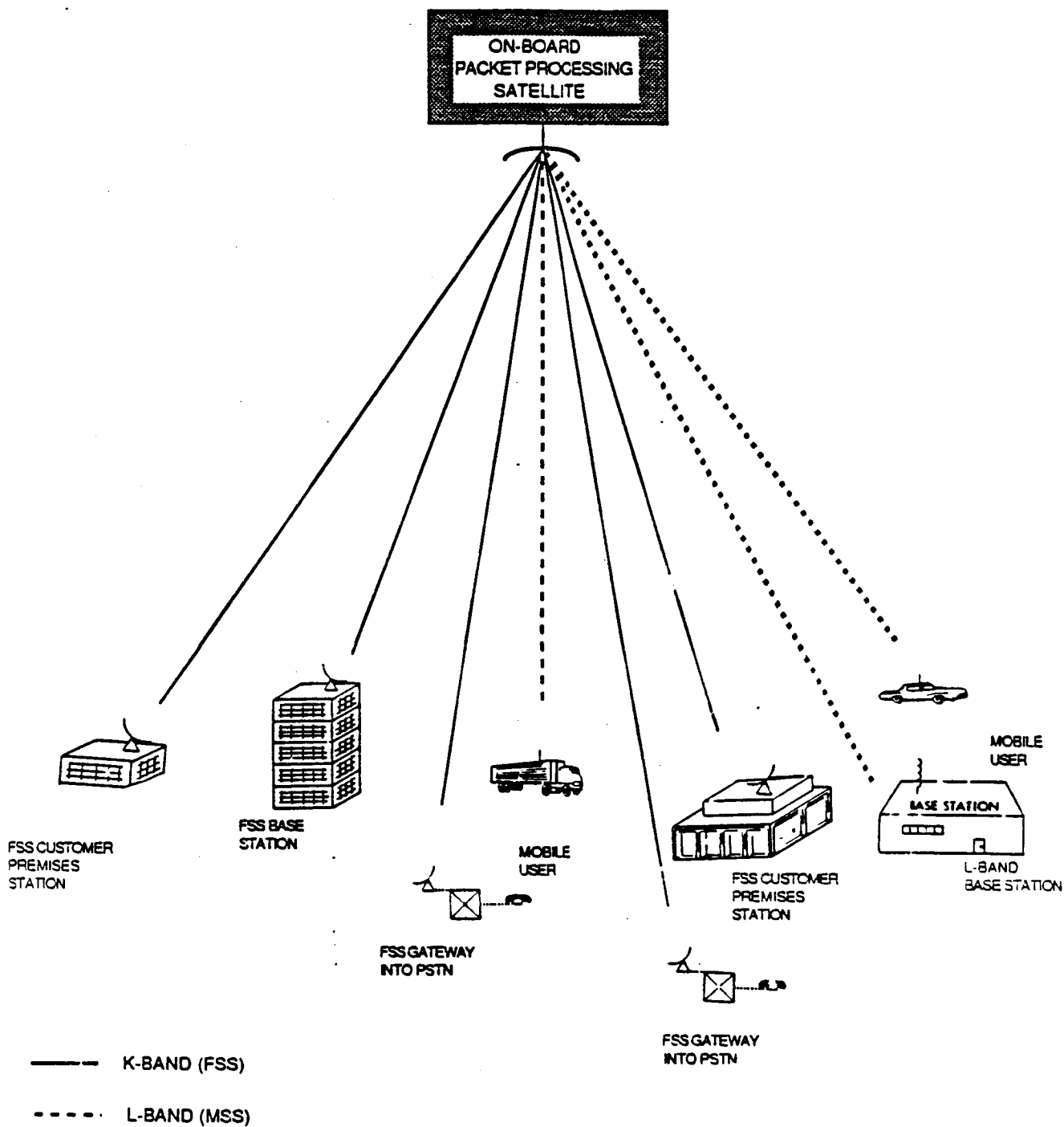


FIGURE 4.1
NETWORK ELEMENTS OF AN INTEGRATED
FSS AND MSS SATELLITE SYSTEM

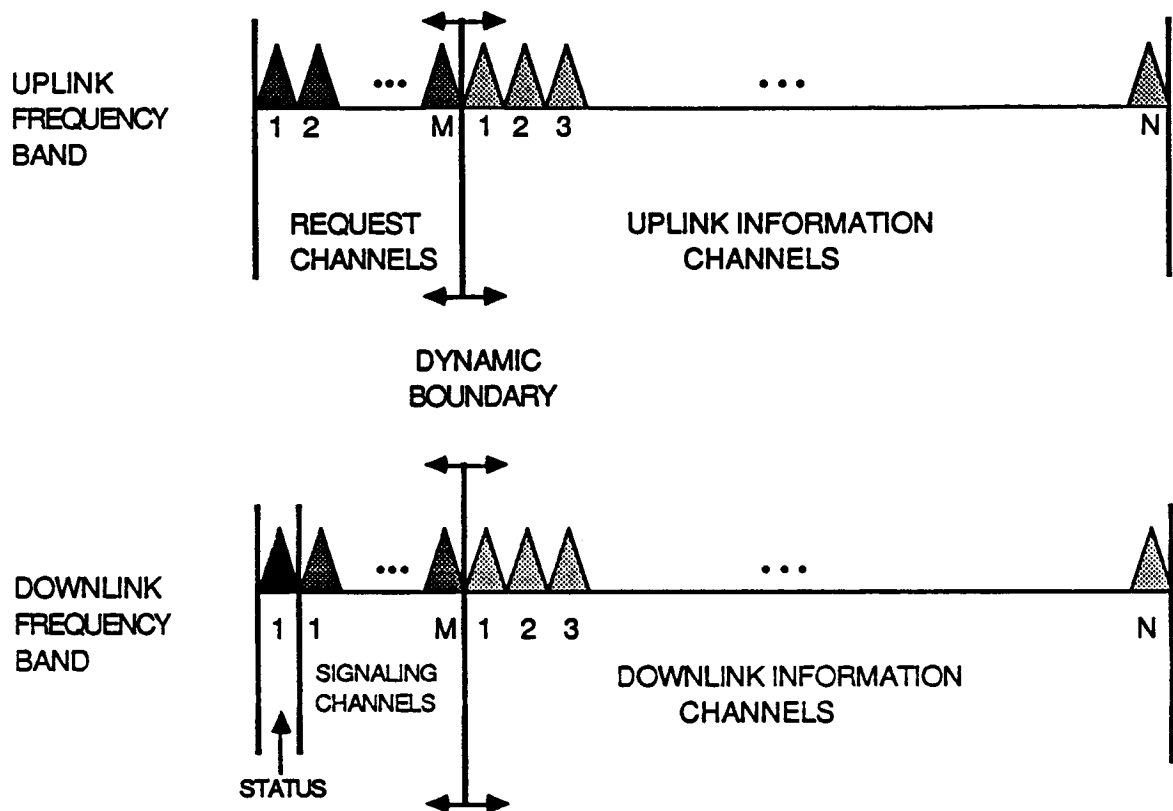


FIGURE 4.2
MSS FREQUENCY PLANS

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OF POOR QUALITY

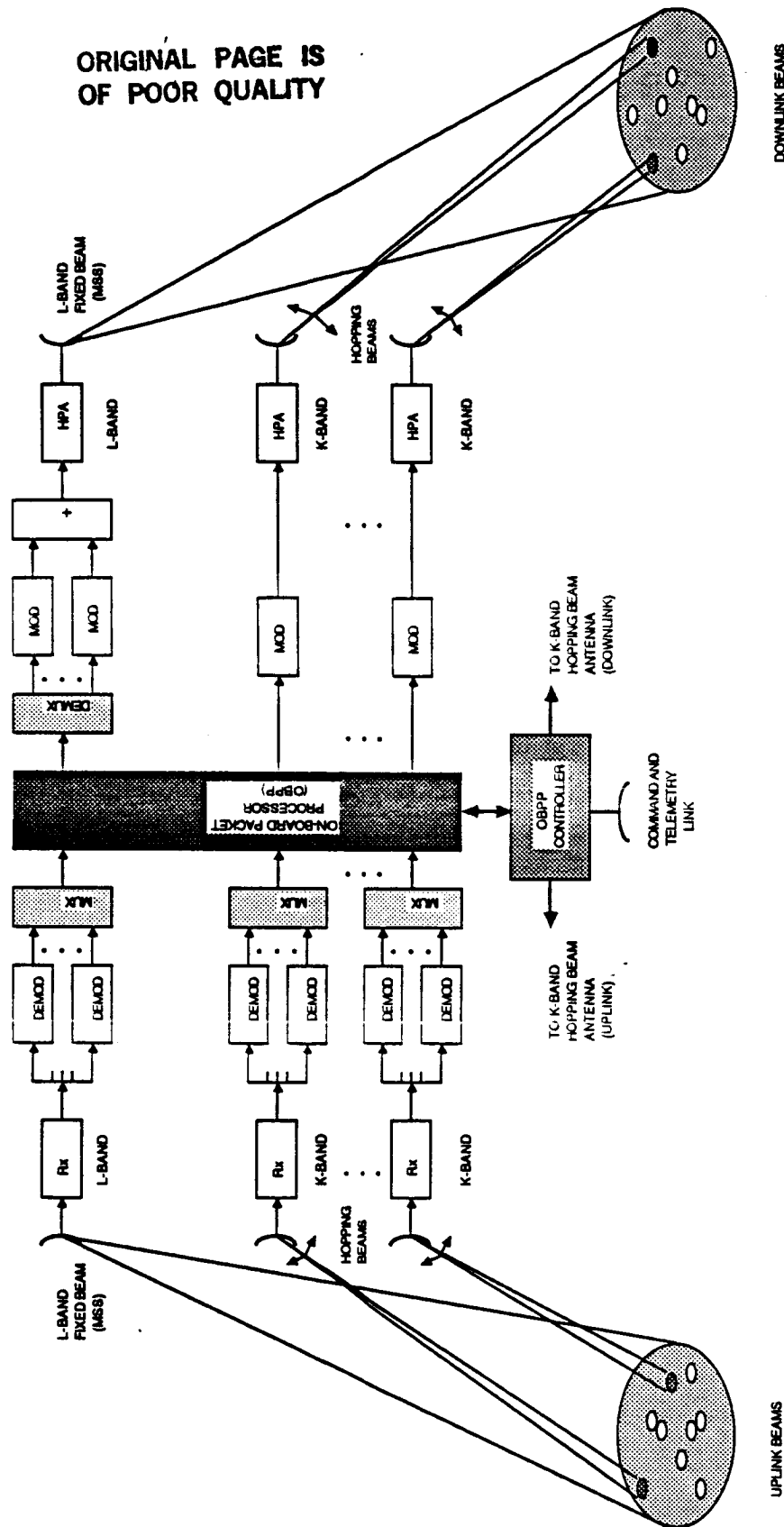


FIGURE 4.3
ON-BOARD PACKET PROCESSOR
FOR INTEGRATED FS & MS SERVICES

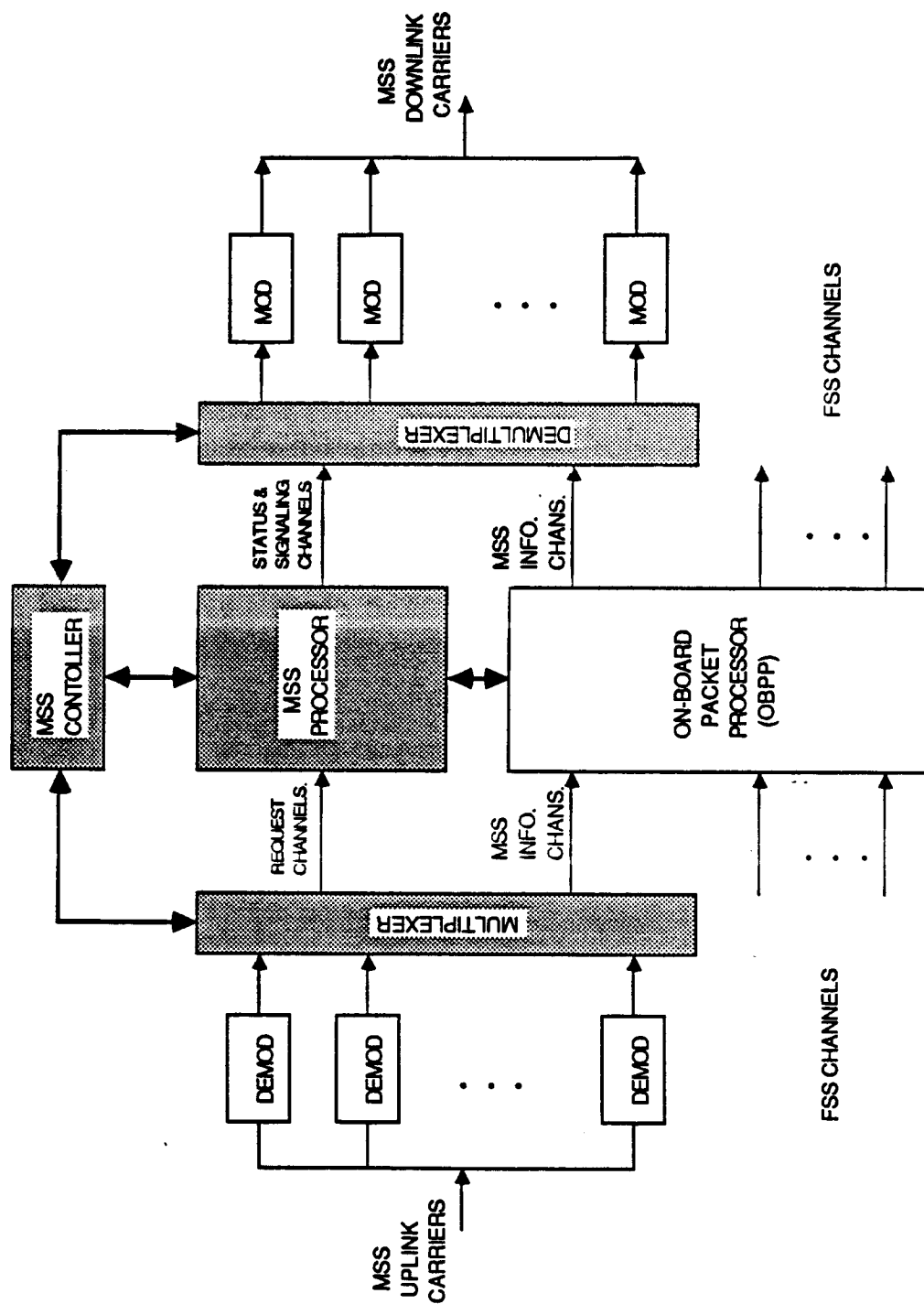


FIGURE 4.4
MSS PROCESSOR

5.0 TECHNOLOGY FORECAST FOR STATIC RAM AND CUSTOM DEVELOPMENT

This section describes the future trends in digital IC technology, and identifies the appropriate component technologies to use for the alternative unified memory architecture in the early 1990's. Based on the discussion to follow, the parts list of Table 3.8 has been revised to reflect 1990-1992 technology as shown in Table 5.1. The power dissipation is 3 to 4 times less than any of the 1987 architectures presented and the total chip count is reduced even more dramatically, mainly due to improvements in memory density. The architecture seems to have considerable merit in the future, once high-speed GaAs logic devices become more practical.

Section 5.1 will predict future trends in static RAM technology and section 5.2 will discuss the outlook for semi-custom logic device technology.

**TABLE 5.1 - SUBSYSTEM DEVICE COUNT AND POWER DISSIPATION -
ALTERNATIVE UNIFIED MEMORY ARCHITECTURE
(BASED ON 1990-1992 TECHNOLOGY)**

A. UNIFIED MEMORY SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
512 BIT S/P	CUSTOM, 64-BIT GaAs ²	8	10
512 BIT P/S	CUSTOM, 64-BIT GaAs ²	8	10
8 BIT COUNTER	STANDARD CMOS	1	0.1
POINTER ARRAY	CUSTOM CMOS ²	1	0.2
TIMING, BUS CNTRL	CUSTOM CMOS ²	1	0.5
DATA MEMORY	32K X 8 CMOS SRAM	80	25
CONTROL MEMORY	64K X 4 CMOS SRAM	8	2
HEADER INPUT MEM	64K X 4 CMOS SRAM	4	1
SUBTOTAL:		111 CHIPS	49 WATTS

B. INPUT MUX SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
BLOCK DECODER	CUSTOM ¹	10	10
UW DETECTOR	CUSTOM ¹	10	10
TIMING GENERATOR	CUSTOM GaAs	1	1
544 BIT FIFO	CUSTOM GaAs	10	20
<hr/> SUBTOTAL:		31 CHIPS	41 WATTS

C. OUTPUT DEMUX SUBSECTION (FOR 10 BEAMS)

<u>FUNCTION</u>	<u>DEVICE TYPE</u>	<u># OF DEVICES</u>	<u>TOTAL POWER DISSIP.</u>
BLOCK ENCODER	CUSTOM ¹	10	10
TIMING GENERATOR	CUSTOM GaAs ²	1	1
544 BIT FIFO	CUSTOM GaAs	10	20
<hr/> SUBTOTAL:		21 CHIPS	31 WATTS
TOTAL:		163 CHIPS	121 WATTS

NOTES:

1. Power dissipation figures approximate. Highly dependent on device technology chosen. CMOS may not meet speed requirements. GaAs is preferred for increased speed and reliability.
2. Could utilize gate array or standard cell technologies.

5.1 TECHNOLOGY FORECAST FOR STATIC RAMS

SRAM densities have increased by a factor of 4 every 3 years for the last 2 decades. Minimum address access times have decreased by a

factor of 10 for every 3-year generation. A recent study projects MOS memories will achieve density and speed improvements of 100 and 5 times higher, respectively, than at present within 15 years [9].

The same study also states that the biggest challenge in semiconductor memories is guaranteeing reliability as geometries shrink. Of particular importance in space applications is a memory's tolerance to high doses of radiation. A 1983 study by McDonnell Douglas ranked different types of memory technologies for space applications¹⁰ (see Table 5.2).

The table lists 1983-1987 technology projections and ranks the various memory technologies in order of suitability to space applications. The table is overly optimistic towards GaAs technology as commercially available GaAs RAMs are currently only at the 1K level and exhibit power dissipations of 1-2 watts. CMOS/SOS is at the 16K level but access times are actually in the 120 ns range. Nevertheless, the table is useful in comparing relative performance of each technology. The total dose and HEPR (high energy particle radiation) radiation sensitivity figures are reasonably accurate. As can be seen, GaAs and CMOS/SOS are the technologies most immune to all types of radiation. Standard CMOS is almost as good. ECL is one of the best technologies in terms of total dose exposure but is more susceptible to HEPR effects. I²L, TTL, and NMOS can be ruled out due to their higher radiation sensitivities (in addition to higher power dissipations).

1 Mbit static CMOS RAMs with access times under 45 ns have been reported at the 1987 International Solid State Circuits Conference (ISSCC). 256K static CMOS RAMs with 120 ns access times are currently available. However, the greater CMOS densities have been achieved by going from a 6 transistor RAM cell to a 4-T cell. 4-T cell structures have a characteristically reduced radiation tolerance. (Figures in Table 5.2 refer to 6-T cell structures).

Currently the highest density radiation hardened CMOS/SOS SRAMs are at the 16K level, 2 generations behind their standard CMOS counterparts. Access times and power dissipations are 120 ns and 200 mw respectively. 64K radiation hardened CMOS/SOS SRAMs should be available from RCA and Harris within the next 1-2 years. It can be assumed that the following generation 256K chips will not be available before 1991 or later.

GaAs technology has a predicted radiation tolerance even greater than

TECHNOLOGY	TOTAL DOSE (RAD SI)	HIGH ENERGY PARTICLE RADIATION SENSITIVITY			ACCESS TIME	SIZE	POWER, mW (OPER/STBY)
		PROTONS #	COSMIC RAYS #	LATCHUP			
GaAs	^{7 8} 10 ⁻¹⁰	1	1	NO	10 nS	4K	75/20
CMOSSOS	⁶ 10	1	1	NO	60 nS	16K	200/2
CMOS	^{5 6} 10 ⁻¹⁰	2	2	PREVENTABLE	40 nS	64K	100/10
2 I L	^{5 6} 10 ⁻¹⁰	4	4	PREVENTABLE	40-240 nS	4K	500/5
TTL	^{6 7} 10 ⁻¹⁰	5	5	PREVENTABLE	60 nS	16K	1000/1000
ECL	^{6 7} 10 ⁻¹⁰	3	3	PREVENTABLE	40 nS	16K	2000/2000
NMOS	³ 10	2	2	NO	40 nS	64K	625/100

NOTES:

*HEPR SENSITIVITY DATA FOR GaAs BASED ON ANALOGY TO CMOS/SOS SINCE BOTH USE

INSULATING SUBSTRATES.

SCORED FROM 1 (LEAST SENSITIVE) TO 5 (MOST SENSITIVE).

TABLE 5.2 - SRAM TECHNOLOGY RANKINGS ACCORDING TO MCDONNELL DOUGLAS STUDY

that of CMOS/SOS. Gigabit logic currently offers a 1K, 1 ns GaAs SRAM. Accurate radiation tolerance performance figures will not be available on the device until next year. Several 4K devices have been reported with access times in the 4 ns range in addition to a 16K, 4 ns SRAM [7]. GaAs SRAMs at the 4K level should be available by the end of 1988. However they would have to reach at least the 64K level before becoming feasible for the architectures described in this report. In addition, power dissipation for the current D-MESFET GaAs RAMs is prohibitively high. HEMT or some other advanced GaAs transistor structure would have to be commercially available to achieve the higher densities, a prospect at least several years away. The technology may be worth waiting for as the much greater speeds would make any of the switching architectures quite feasible for even higher bit rates.

CMOS or CMOS/SOS RAM technology must still be assumed for the early 1990's. 256K CMOS memories were listed in the parts list in Table 5.1. GaAs RAMs could be assumed if the time frame were to be moved out to the late 1990's. The discussion in the next section comparing various logic chip technologies also applies to static RAMs.

5.2 TECHNOLOGY FORECAST FOR CUSTOM AND SEMI-CUSTOM LOGIC ARRAYS

A list of the custom chips required for the alternative unified memory architecture in the early 1990's is shown in Table 5.3. The chips are sorted into 3 distinct groups according to their maximum clock rates and approximate gate complexities (expressed in terms of the number of gates) are given. The gate complexities for the 1.2 GHz chips should be quite accurate as the chips have a very regular structure. The other chip densities are more difficult to estimate and only absolute maximum numbers are given. Because the three groups represent such a wide range of clock rates, the future prospects of each group are discussed separately.

**TABLE 5.3 - SUMMARY OF FUTURE CUSTOM CHIP REQUIREMENTS FOR
ALTERNATIVE UNIFIED MEMORY ARCHITECTURE**

<u>DEVICE</u>	<u>MAX. CLOCK RATE</u>	<u>GATE COMPLEXITY</u>
PNTR ARRAY/ADDR GEN	10 MHZ	< 10,000
MEMORY TIMING/BUS CNTRL	20 MHZ	< 10,000
BLOCK ERROR DECODER	120 MHZ	< 3,000
BLOCK ERROR ENCODER	120 MHZ	< 3,000
UW DETECTOR	120 MHZ	< 5,000
64 BIT S/P REG.	1.2 GHZ	1500
64 BIT P/S REG.	1.2 GHZ	1500
544 BIT FIFO	1.2 GHZ	10,000
MUX/DEMUX TIMING GEN.	1.2 GHZ	500

The pointer array and memory timing chips will almost certainly have complexities of under 10,000 gates and a clock rate of 20 MHz or less. Currently, CMOS gate arrays utilizing 2 micron geometries are available from a large number of vendors and will easily meet these requirements. In standard cell designs, current state of the art utilizes 1.25 to 1.5 micron double layer metal CMOS technology with a gate level of 50,000, sub-nanosecond gate delays, and maximum logic toggle rates approaching 100 MHz. CMOS is the clear choice for the chips in the 20 MHz frequency range because of its superior power dissipation characteristics and proven reliability and availability.

The 3 chips in the 120 MHz clock category could utilize one of 3 competing technologies: CMOS, ECL, or GaAs. Considerable insight can be gained by comparing their speed-power products [1] (see Figure 5.1). CMOS is at the lowest end of the power scale, with dissipations between 0.05 to 0.5 mw/gate. Current CMOS technology exhibits on the order of 1000 ps gate propagation delay but delays should go down as low as 250 ps as geometries shrink below 1 micron. Thus, complex 120 MHz CMOS logic arrays should be quite feasible within the next few years.

Silicon ECL technology is at the opposite end of the power scale with dissipations in the range of 0.8 to 8 mw/gate. Propagation delays are comparable to sub-micron CMOS. The main difference is that high density and very high speed ECL gate arrays are available today, using geometries larger than 1 micron. For example, the Motorola Mosaic-III process, the anticipated technology for the ACTS S/P and P/S registers (according to a 1984 report [2]), utilizes 1.5 micron ECL technology with gate delays as low as 150 ps and power dissipations as low as 1 mw/gate. The maximum toggle rate has been stated as 1.3 GHz [3]. The manufacturer is currently offering 10,000 equivalent gate arrays. 20,000 equivalent gate arrays with 50 ps gate delays should be available in two years with the introduction of the 1 micron Mosaic-IV process. Honeywell currently offers a 12,000 equivalent gate array built with 1.2 micron geometries with delays similar to the Motorola Mosaic-III array [4]. ECL is inherently a denser process than CMOS but the main problem with ECL is the need to dissipate large amounts of power as the number of transistors per chip increases. However ECL is the technology of choice if the 120 MHz devices were to be built today. CMOS or GaAs would be the choice for the early 1990's.

The third category of custom chips in Table 5.3 require 1.2 GHz clock rates. The table specifies much higher density parts than can be built today. To implement these dense chips at this speed, GaAs will almost certainly be required. It is clearly at the lowest end of the propagation delay scale and has the potential for power dissipation figures nearly as low as for CMOS. GaAs integration levels are several generations behind silicon since GaAs is a relatively new technology. However densities are increasing at a rate 3 times faster than for silicon. As silicon improves, GaAs can borrow much of the same processing technology for itself. It has been estimated that GaAs chip complexity will equal that of silicon sometime in the 1990's [5].

Performance of GaAs circuits is highly dependent on the particular device technology implementation [1,5-8]. The most mature technology today is based on the depletion mode MESFET or D-MESFET. This is represented by Honeywell's GaAs-I process in Figure 5.1. 2000 equivalent D-MESFET standard cell arrays are currently available from Gigabit Logic and Honeywell with gate delays on the order of 200 ps and power ratings of 1-2 mw/gate.

Gigabit Logic expects to lower the power to 100 uw/gate in 1988 by

introducing the enhancement mode or E-MESFET standard cell array. The Honeywell E-MESFET performance is shown as GaAs-II in Figure 5.1. E-MESFET technology is not necessarily faster but it uses much less power. Gigabit Logic predicts a density level of 10,000 gates by 1988 (See Figure 5.2)*. Fujitsu has reported on a 16-bit multiplier utilizing a combination of E and D type MESFETs to achieve a density of 3000 gates [7].

A third promising GaAs device technology is the high electron mobility transistor or HEMT. (See the GaAs-III curve in Figure 5.1). Although it requires more difficult processing technology, it promises even higher speeds with reduced power consumption. Other technologies are presently in the early research stages but promise even greater potential. Figure 5.3* shows Gigabit Logic's plans for introducing the various GaAs device technologies.

Based on the preceding information, it appears that the E-MESFET or combined E and D MESFET technologies of the early 1990's should be adequate for the 1.2 GHz custom chips required by the alternative unified memory architecture. The GaAs chips in Table 5.3 give integration levels and wattages assuming this technology.

The main technical barrier to the 1.2 GHz circuits in the architecture is the development of suitable packaging and interconnect technology. Distances of several inches can represent a significant fraction of a bit period at those clock rates.

* Figures 5.2 and 5.3 courtesy of Gigabit Logic Inc., Newbury Park CA

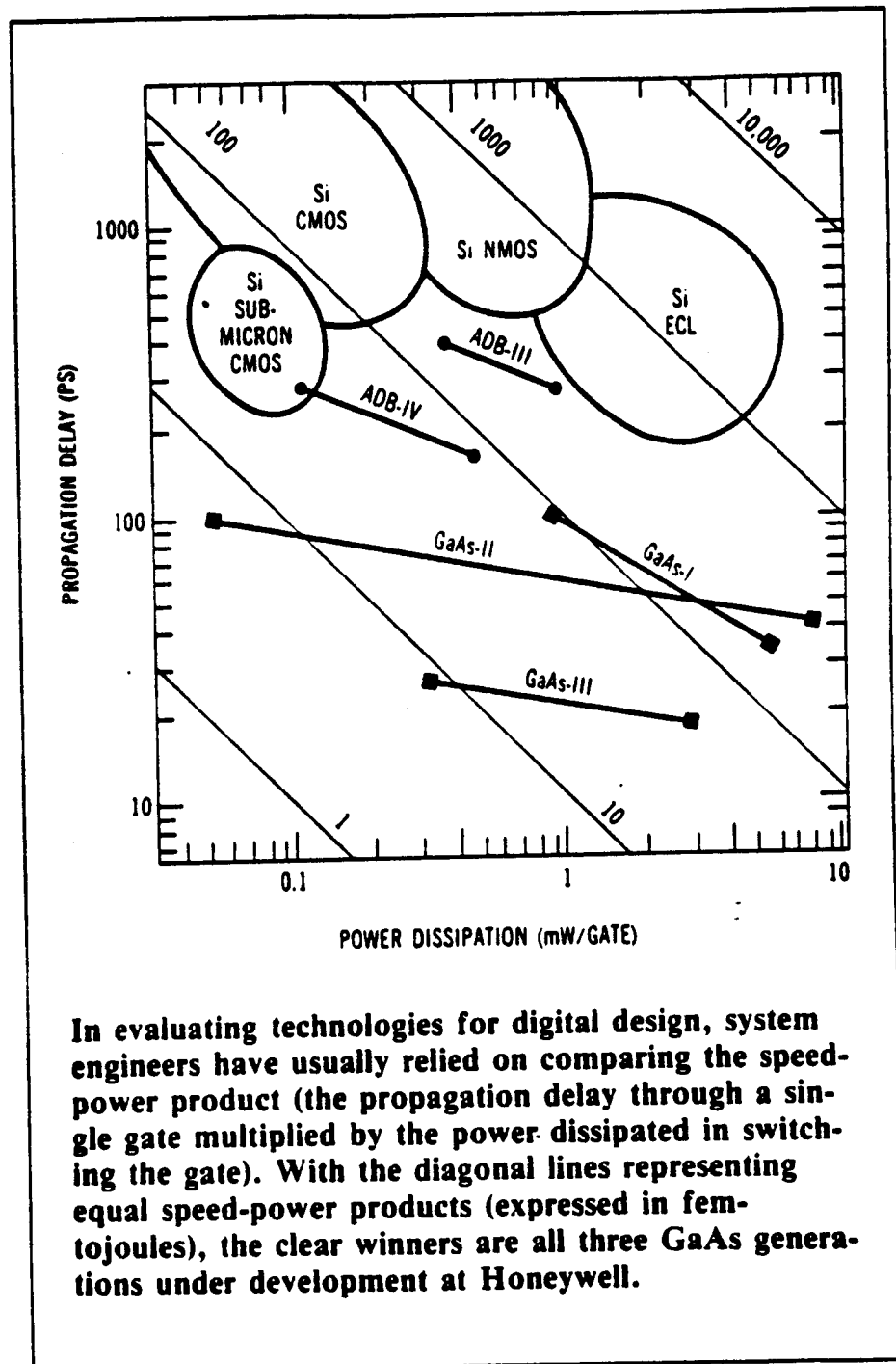


Figure 5.1 Speed-Power Products of Various Digital IC Technologies
 [Source: N. Mokhoff, Computer Design, p 77,
 Oct. 15, 1985]

FIGURE 5.2 FORECAST OF COMMERCIAL GAAS DIGITAL LOGIC IC
GATE COMPLEXITY VS. COMMERCIAL SILICON IC'S

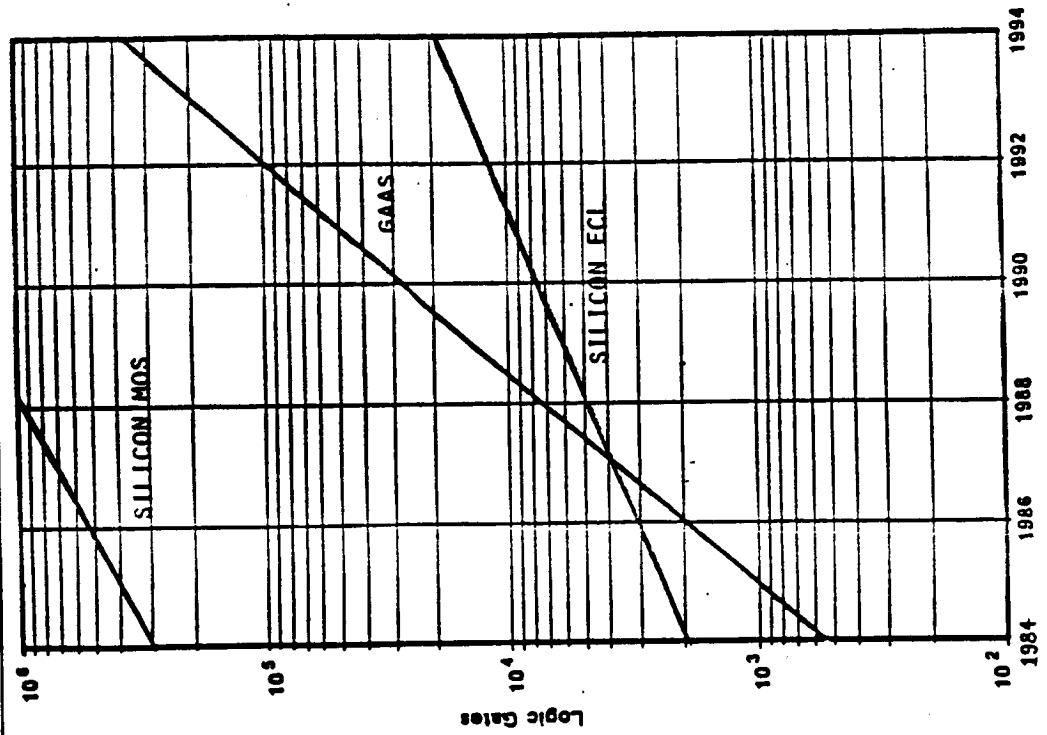
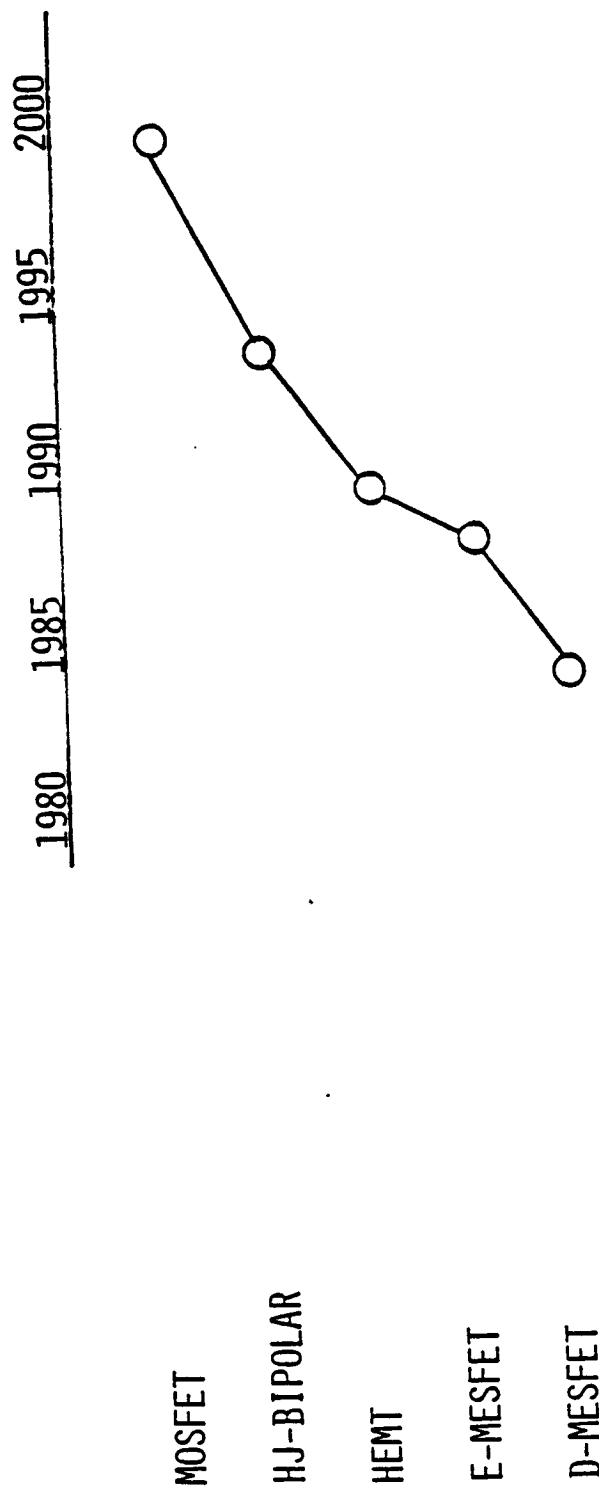


FIGURE 5.3

GaAs DEVICE TECHNOLOGY



- 0 D-MESFET IN PRODUCTION
- 0 E-MESFET REQUIRES PROCESS REFINEMENT TO TIGHTLY CONTROL V_T VARIATION.
SAME STRUCTURE AS D-MESFET (NORMALLY OFF, ONE POWER SUPPLY)
- 0 HEMT REQUIRES PRODUCTION MBE EQUIPMENT
- 0 HJ-BIPOLAR: BEGINNING R & D
- 0 MOSFET - R & D STAGE. SUITABLE GATE INSULATOR NEEDED. GaAs HAS NO NATIVE OXIDE

6.0 TECHNOLOGY DEVELOPMENT REQUIREMENTS

Future technology developments needed to realize a working destination directed on board packet system comprise:

- 1) Key Device Development,
- 2) Destination Directed Packet Architecture Development and
- 3) Test Bed Development.

Key device development is expected to be aided significantly by continuing pressures in the semiconductor industry to pursue the most competitive technologies needed for both military and commercial applications. Guided development in areas of particular importance to NASA applications can accelerate the process. Regarding the destination packet architecture development, this is uniquely related to the onboard processing structure defined in this document and must be done by NASA if the approach is to be realized in the future. The concepts involved are unique and are not being pursued widely by others. The Test Bed is recommended principally as a vehicle to implement the detailed protocols that would come from a destination packet architecture development. It would not only provide a means to demonstrate the technique but more importantly provide an opportunity to learn by the requirement to apply the technology and provide a means to perfect the processing algorithms. These three activities are summarized below.

6.1 KEY DEVICE DEVELOPMENT

The feasibility of a high-capacity destination directed packet switching architecture by the early 1990's assumes the availability of several key devices. Speed, gate densities, and power dissipation characteristics must be significantly improved over today's technology for many of these devices. Refer to Table 5.1 for a parts list of the alternative unified memory architecture. Logic devices and memory devices are treated separately below.

6.1.1 CUSTOM LOGIC DEVICES

A list of the custom logic devices required is given in Table 5.3. The devices can be broken down into three categories:

1. Standard CMOS logic arrays - <10,000 gate density, <20 MHz clock
Available using today's technology.
2. ECL, CMOS, or GaAs logic arrays - <5000 gate density, 120 MHz clock. Probably within today's ECL technology. Future GaAs or CMOS technology desirable for reduced power (100 uWatt per gate).
3. GaAs logic arrays 500-10,000 gate densities, 1200 MHz clock.
Requires future advanced GaAs technology. 100 uWatt per gate.

The most critical item listed in Table 5.3 is the 544 bit FIFO with a clock rate of 1200 MHz. It should be contained in a single chip with a maximum power dissipation under two watts. The technology listed in item 3 above must be available for this to be possible.

6.1.2 MEMORY DEVELOPMENT

Section 5.1 discusses future semiconductor RAM technology. Static RAMs with densities of at least 256K are required to keep system chip count at an acceptable level. RAM access times depend on the final architecture implementation, but probably should be about 100 ns. As discussed in Section 5.1, the limiting factor will be memory device reliability and radiation tolerance at the densities required. Current radiation hardened CMOS RAMs are about two generations behind the 256K level. GaAs devices are desirable but will not reach the 256K level for at least the next 5-10 years.

6.2 DESTINATION DIRECTED PACKET ON BOARD PROCESSING ARCHITECTURE DEVELOPMENT

Section 3.1 provides the system design for a destination directed packet on board processing architecture. Preliminary tradeoff analyses are provided which are used to develop key system parameters, such as packet length, frame size and efficiency. Additional detailed analysis is needed to firm up the system design in order to provide a fully optimized

system.

Issues which require further definition include: DAMA protocols including method of capacity allocation, burst time plan protocols, packet error control, packet flow control, acquisition and synchronization procedures, on board processor port mapping and control procedures.

6.3 DESTINATION DIRECTED PACKET NETWORK CONTROL TEST BED

The proposed architecture utilizes many new system concepts and requires a hardware implementation substantially different from existing satellite architectures. A proof-of-concept (POC) test bed is recommended to demonstrate the architecture feasibility, reveal potential problems, and assess performance.

6.3.1 CRITICAL FEATURES TO BE INVESTIGATED

The test bed will be used to examine the performance of the destination directed packet system implemented with the proposed unified memory architecture. The learning experience will permit further refinement of the system design. In addition, it is proposed to assess the system performance under various traffic conditions, determine memory control complexity, perform a reliability analysis, determine redundancy requirements, and explore methods of fault detection and onboard diagnostics.

6.3.2 PROPOSED POC TEST BED BREADBOARD

A POC Test Bed model should be scaled down sufficiently to facilitate construction with today's technology while still employing all the major architectural subsystems and features. Figure 6.1 shows a proposed block diagram. It would interconnect three 40 Mbit/s uplinks and downlinks operating in three hopping beams. Input and output multiplexers operate at rates of 120 Mbit/s in conjunction with a unified data RAM memory using the "in place" switching architecture. A memory control CPU accepts the addressing information, modifies the packet headers and controls the unified memory to accomplish the appropriate channel routing from upbeam to downbeam time locations.

A POC development program consisting of several phases over an 18 month period shown in Figure is suggested as the next appropriate step in the evolution of the destination directed onboard switching processor. The program would consist of the following phases:

- 1) ARCHITECTURE AND PROTOCOL DEVELOPMENT,
- 2) HARDWARE DESIGN,
- 3) TEST BED IMPLEMENTATION,
- 4) TEST AND EVALUATION

Phase 1 of the test bed program develops the architecture and protocols for defining the destination directed packet system. System requirements will be further refined to size the test bed in terms of its speed and memory size. Architecture tradeoffs will be performed to develop a system implementation that provides optimum performance with minimum onboard processor power and mass. Development of terrestrial interface protocols is needed to accommodate signalling and supervisory functions of the terrestrial network. The onboard processor routing protocols will be defined in detail permitting full definition of the control logic. The destination directed message structure presented in the current study will be evaluated in detail for the impact of error in transmission to develop a robust control logic.

Phase 2 develops the hardware using the results obtained from the architecture and protocol development work described above. This work will arrive at the design specifications and the design details for the test bed and its test and evaluation interface facility. During this phase of the program, memory and logic devices will be selected for constructing the test bed. The test bed design and its implementation will encompass all of the functions needed to demonstrate the message directed concepts developed during the first phase of this program. The throughput of the processor will be scaled down to 120 mbit/s (comprising three 40 mbit/s up link beams) to permit implementation with existing device technology. The test and evaluation interface facility is the means by which the operator accesses and controls the test bed and collects the test data .

Phase 3 of the test bed program implements and tests individual test

bed modules. Next these are assembled into the complete test bed system. Early in this phase, a selection will be made of the method of packaging and the type of circuit board technology to be used. Issues such as component and system packaging, heat dissipation, intercomponent delay, race effects and mechanical design and will be addressed.

Phase 4 of the test bed program comprises the test and evaluation phase. A detailed test plan will be written to describe the test bed verification and 'end-to-end' system tests. The verification test will confirm that the test bed meets the design specifications. The 'end-to-end ' system tests will assess the overall performance of the destination directed packet approach. These tests will include an assessment of throughput efficiency, immunity to blocking, immunity to channel error, adaptability to track changes in traffic patterns on a channel by channel basis and exercising burst time plan changes. In addition, the test bed will be used to refine the onboard routing protocols by testing performance with a variety of alternatives. The principal objective of the test bed is to explore the sensitivity of the destination directed switch concept to its environment and to optimize its operating protocols.

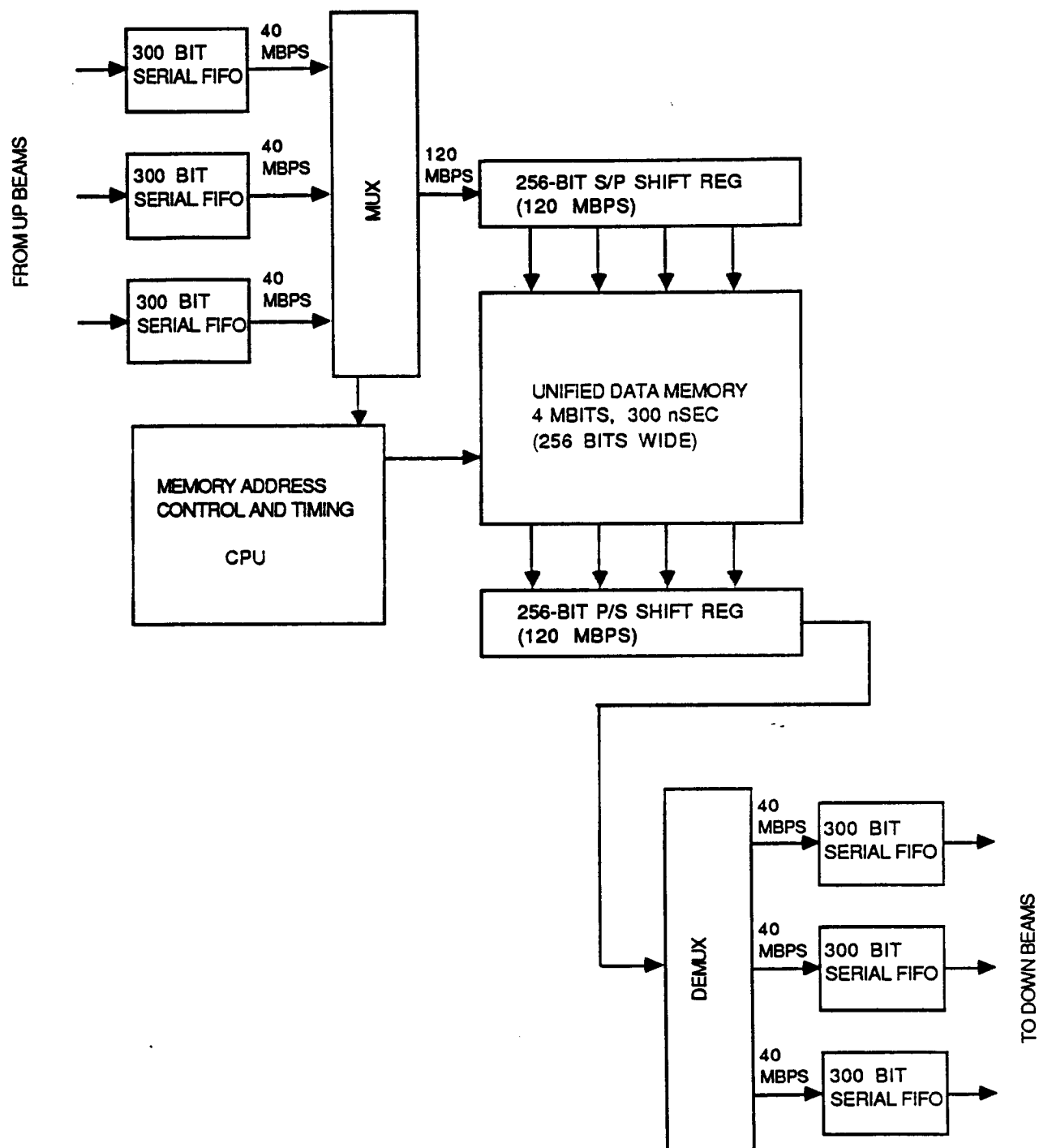
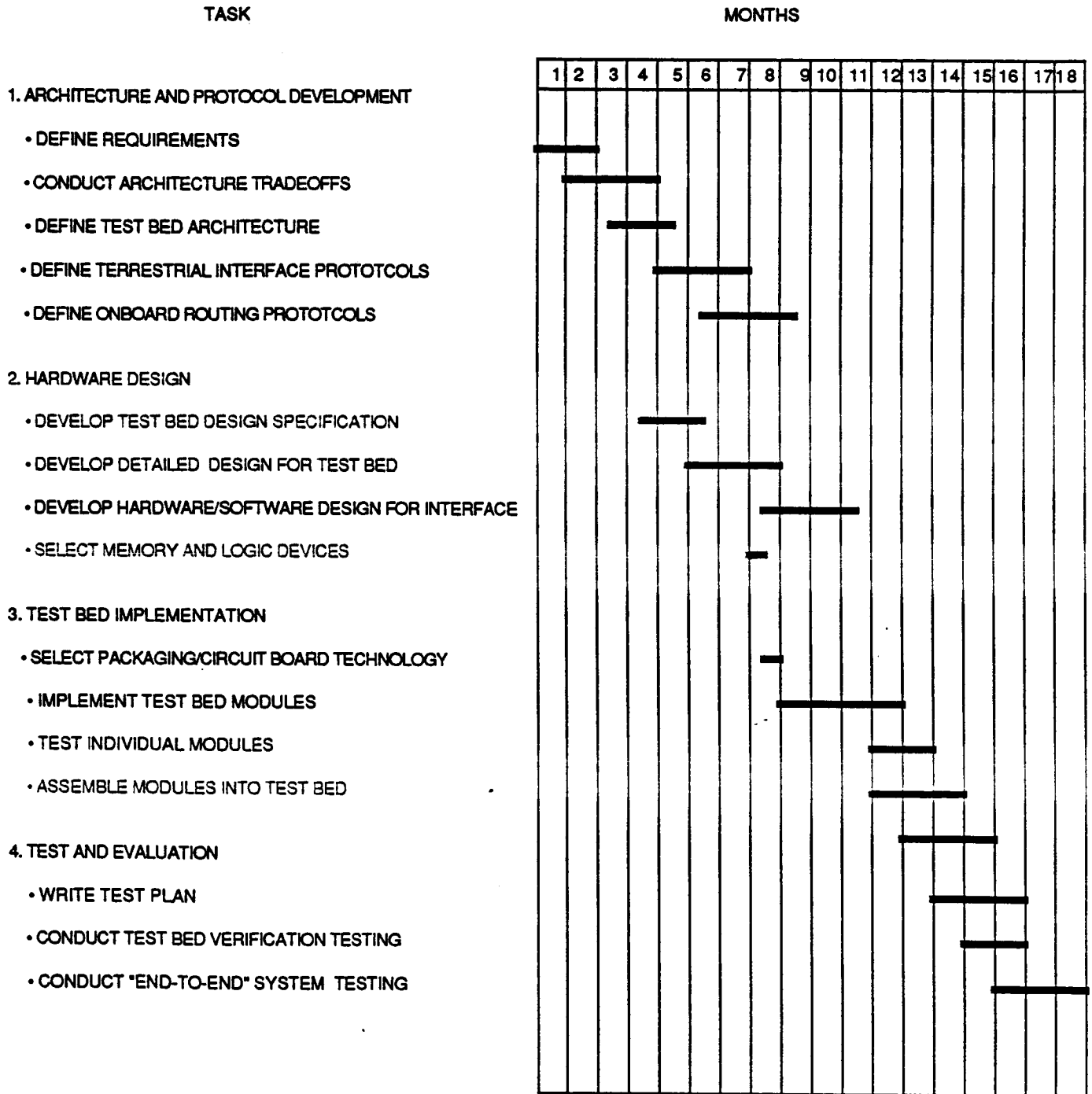


FIGURE 6.1 - DESTINATION DIRECTED PACKET SWITCHING TEST BED BLOCK DIAGRAM

FIGURE 6.2
TEST BED PROGRAM PLAN



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ONBOARD BASEBAND SWITCH CALL PROCESSING

The principal function of the onboard baseband switch is to route calls assigned to time slots on various carriers in various beam uplinks to other time slots assigned to carriers in various beam downlinks. TDMA digital transmission is used because it: a) provides the ease and flexibility to assign and reassign traffic simply by manipulating the duration and location of digital data bursts and b) it is the only way to provide the flexibility to accommodate beam hopping. This discussion is devoted to the functioning of the call processing in a baseband switch designed for serving such a TDMA implemented multibeam hopping system. A question to be addressed is the merit of including the capability to perform call processing as part of the onboard processing rather than performing it at a ground Network Control Center. The principal merit would lie in the reduction of the transmission load on the control link between the satellite and the earth. The conclusion is that there is not significant merit for performing call processing onboard with the circuit switched mode of operation. However, there may be significant merit for onboard destination directed switching for both voice and data.

ONBOARD CIRCUIT SWITCHING

Figure 1 illustrates the principal components of a baseband switch used to route a call from an upbeam burst to a downbeam burst in a beam hopping system. For the sake of simplicity, an implementation for only two beams is shown, the extension to a greater number of beams being apparent. This configuration corresponds to that being used on the ACTS. At the left side of the diagram are two Input Data Memories which are used to store the traffic bursts arriving from each of two hopping uplink beams. Each of Data Memory actually contains two memories operating in a ping-pong fashion where one memory is being filled with new data in the current TDMA frame while the contents of the other, which were collected in the previous frame, are being processed by the switch. The storing and playback functions alternate for each memory from TDMA frame to TDMA frame. In the ACTS the TDMA frame period is 1 ms and each telephone channel carries 64 kbit/s PCM, hence each channel comprises 64 information bits.

At a transmission rate of 110,592 kbit/s, the uncoded transmission rate used on the ACTS, each frame can accommodate 1728 telephone channels. It is assumed for the purpose of this discussion that each input memory serves the capacity of one such TDMA carrier and there is one carrier per beam. Hence, there are 1728 64 bit telephone channel slots in each of the input memories. The function of the baseband switch is to route individual channel slot contents to their proper destination slot in one of the down link beams. Figure 1 illustrates the routing for uplink slot V in beam 1 to downlink slot Y in beam 1 and uplink slot W in beam 2 to downlink Slot Z in beam 2. The switch is implemented as a time-space-time (TST) switch. Traffic arriving on each of the uplink beams is stored in the input memories in the time order of arrival as established by the burst time plan structure of TDMA stations.

Playback of the contents of the input data memories is controlled by the input control memories which operate in a sequential fashion to address the contents of the input data memories and cause them to be presented to the route switch. The route switch constitutes the space switch of the TST configuration. The function of the route switch is to direct the selected contents of the input memories to the appropriate output memories. The Route Switch Memory identifies which of the states of the route switch applies to the currently selected channels. For the 2x2 route switch assumed in this example, the total number of possible states are 16 as illustrated in Figure 2. In general, the total number of states of a MxN route switch is theoretically 2^{MN} and hence can become very large even for a small number of multiple beams. Care must be exercised to use only the states that are needed and to code these in an efficient way. The route switch presents the selected input data memory channel slot contents to the locations in the output memory designated by the contents of the output control memories. The entire process of transfer of the contents of all of the input data memories to the output data memories occurs in one TDMA frame period. The output memories operate in a ping-pong fashion like the input memories. Each ping-pong memory is filled on one TDMA frame period and played out on the next. The delay in passage through the entire switch is 2 ms. The order of storage in the output memories is controlled by the sequence of the route switch memory while the order of playback is controlled by the output control memories.

For each time slot occurring on the uplink beams, there will exist a current routing switch state selected to carry the traffic from a particular uplink beam to a particular downlink beam. For a 2x2 beam system the routing possibilities are:

INPUT 1 TO OUTPUT 1	2,6,9,10,14,15,16
INPUT 1 TO OUTPUT 2	4,6,7,11,12,13,15,16
INPUT 2 TO OUTPUT 2	3,7,8,10,12,13,14,16
INPUT 2 TO OUTPUT 1	5,8,9,11,13,15,16

The numbers given after each route possibility identify the 2x2 switch states that will provide the connection indicated. Switch state 1 is a no-connect state and is the initial state from which to begin. Some of the states may not be used. If only those corresponding to non broadcast or non convergence operation are included, only switch states 1,2,3,4,5,10 and 11, a total of seven, would be used. Similar arrangements will exist for other larger multiple beam systems. When a call is to be setup, an uplink slot must be picked for which the existing switch state is one that allows the wanted beam-to-beam connection to be made. To accomplish this, it is necessary that a record be kept of the route switch state currently in use for each uplink channel slot. This record may be kept in terms of lists, one for each type of routing, which identify the addresses of the addresses of channel slots currently using a switch state that can accommodate the routing type. For the 2x2 switch there are four such lists, viz., 1 to 1, 2 to 2, 1 to 2, and 2, to 1. In general there are N^2 of these lists for an NxN beam system.

CONNECTING A CALL THROUGH THE SWITCH

A procedure for connecting a call through the onboard baseband switch is now identified:

- 1) Identify the beam to beam routing needed to carry the call.
- 2) From the route-type lists, identify an uplink slot address and switch state type that can accommodate the connection.
- 3) Pick an available route switch address, say X.

- 4) Modify the route switch type to accommodate the new connection and update the route-type lists.
- 5) Determine an input control memory address. If the route switch address is X, then set the input control memory address to X-1.
- 6) Determine an output control memory address. If the route switch address is X, then set the output control memory address to X+1.
- 7) Determine from the Uplink Data Memory Map an available input data control memory address and corresponding uplink channel slot number.
- 8) Determine from the Downlink Traffic Map an available downlink channel slot address, say Y for beam 1 or Z for beam 2 and set the downlink control memory address to Y-1 or Z-1 as appropriate.

The above steps are performed each time a call is connected and a similar procedure must be used for a call disconnect.

The following messages must be sent to the onboard switch to implement the connection:

- 1) Contents of Input Control Memory 1 location X-1 comprising the address of the Uplink Data Memory 1 to hold the channel data for uplink time slot V.
- 2) Contents of Input Control Memory 2 location X-1 comprising the address of the Uplink Data Memory 2 to hold the channel data for uplink time slot W.
- 3) Contents of Route Switch Memory location X comprising a code identifying the Route Switch State S.

- 4) Contents of Output Control Memory 1 location Y-1 comprising the address Y of the downlink channel slot. Also programmable pointers used to control the sequence of reading the channels stored in the output data memory to permit flexibility to accommodate beam hopping are included.
- 5) Contents of Output Control Memory 2 location Z-1 comprising the address Z of the downlink channel slot. Also programmable pointers used to control the sequence of reading the channels stored in the output data memory to permit flexibility to accommodate beam hopping are included.

SWITCH CONTROL MESSAGES

A message format containing the essential parameters for establishing two connections simultaneously is

W/V/X/Y/Z/S/P

where P indicates a parity check. Typically W, V and X can be 16 bit numbers; Y and Z each have associated pointers and require 32 bits. S requires at least N^2 bits to identify all possible states of the routing switch and hence can also be a 16 bit number for up to a 4x4 beam system. For larger numbers of beams the number becomes extremely large. For example, a 10 x10 beam system would require 100 bits to identify all of its possible switch states. This implies that it is important to define a minimum set of switch states and to find ways to adjust the states by incremental changes rather than replacing the entire switch state code every time it is to be modified. For a 2x2 beam system the number of bits totals to 117 bits ($3 \times 16 + 2 \times 32 + 4 + 1$) for processing a call in both beams. When error protected by use of R 1/2 FEC, this number is doubled to 234. In a satellite handling 3500 circuits (a practical number for consideration in a system of modest capacity) with an average call holding time of 3 min, the average call initiation rate is 20 calls/s. This corresponds to one call every 50 millisecond. If the system sets up two calls for every connect message, the transmission rate for the messages is 2.34 kbit/s for a 2x2 system. This discussion has ignored hopping beam

pointing, which requires little additional information rate and will not change the result significantly.

Increasing the number of beams requires additional information to control the onboard switch. The increase in the number and/or size of control memories is in direct proportion to the increased capacity: however the increase in the number of routing switch states is exponential and the number of bits required to express all possible states increases as the square of the number of beams. This later fact can cause a more than linear increase in the capacity needed to administer control of the onboard switch. However this increase is not very significant for 10 beams or less. For 10 beams the number of bits needed for messages to the control memories is 560 and for the route switch memory 100, yielding a total of 661 including parity. This must be doubled for R 1/2 FEC to a total of 1322 bits per 10 calls or 132 per call. The number of bits per call for the 2x2 beam configuration was 117.

COMPARISON OF ONBOARD VERSUS GROUND CONTROL

The discussion thus far referred to control of the onboard switch from the ground and identification of the parameters that need to be sent to the satellite. These parameters have been identified as W,V,X,Y Z,S and P in the preceding discussion. Consider now what would happen if the route switch processing were performed onboard. Obviously, those parameters identifying the uplink and downlink slots, viz W,V,Y and Z and the parity P would still have to be sent from the ground since these are determined on the ground where the overall system network control is performed. This network control function involves the central collection and processing of all call requests and the generation of the resulting traffic burst time plans for all stations in the system and the generation of the instructions that go to the onboard switch including the determination and control of the states of the routing switch. The only function that might be transferred to the satellite, outside of transferring all the network control functions to the satellite, is selection of the states of the routing switch. The discussion of the preceding section shows that the control information S pertaining to the route switch does not constitute a large fraction of the uplink command link data rate even for a large number of beams. If the function of selecting the route switch states was implemented on board the satellite, the associated processing implementation would also have to be onboard thus increasing the onboard

power and weight. The small savings in the command link capacity would likely not be worth the additional expense of having the the route switch state selection processing performed onboard. As long as the network control function remains on the ground, the selection of the route switch states is best done there. However, if a means is implemented onboard to directly perform routing from destination directed addressing carried with the message, route switch state selection would appropriately be a part of the onboard call processing function.

FIGURE 1. ONBOARD CALL ROUTING FOR TWO BEAMS

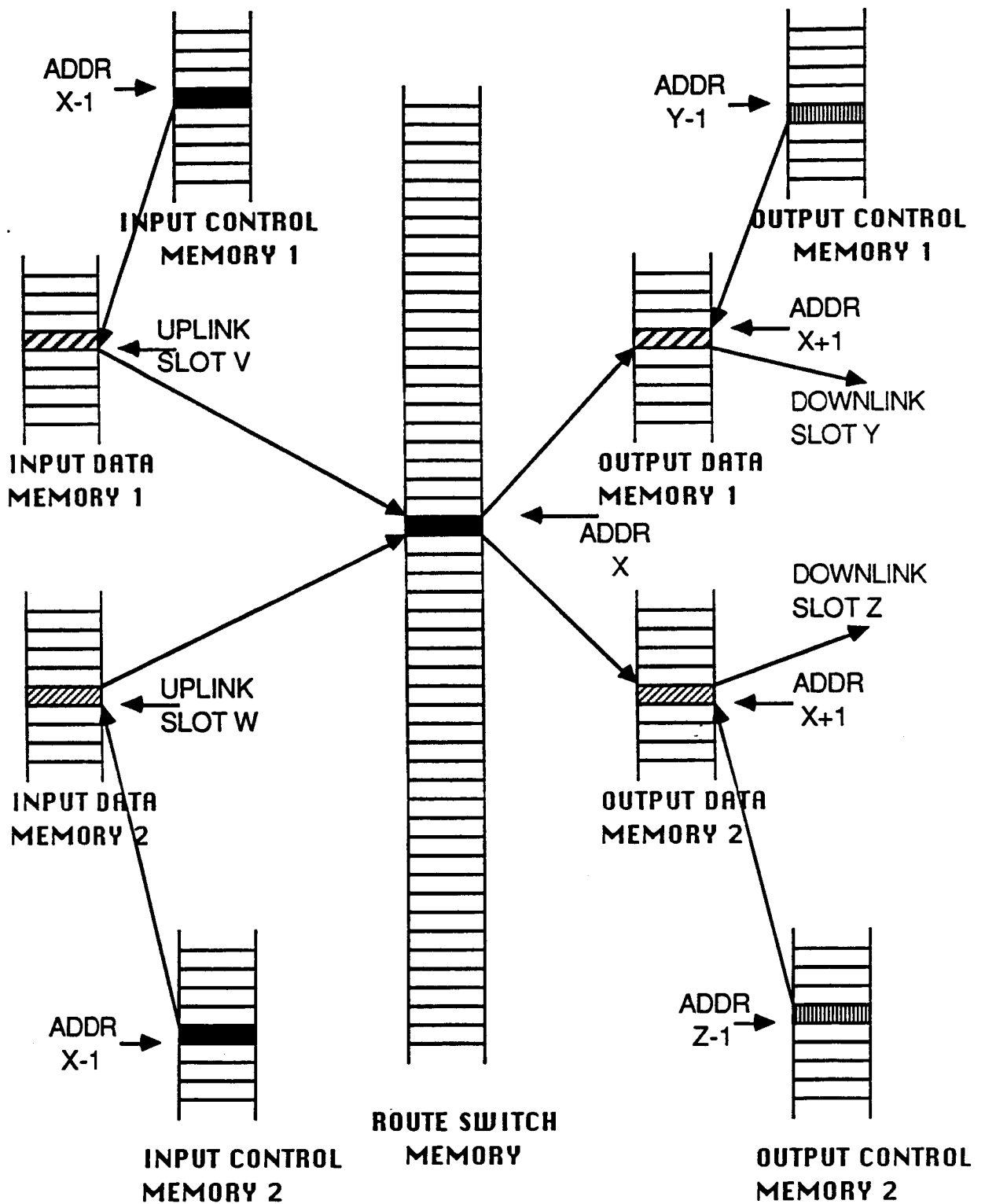
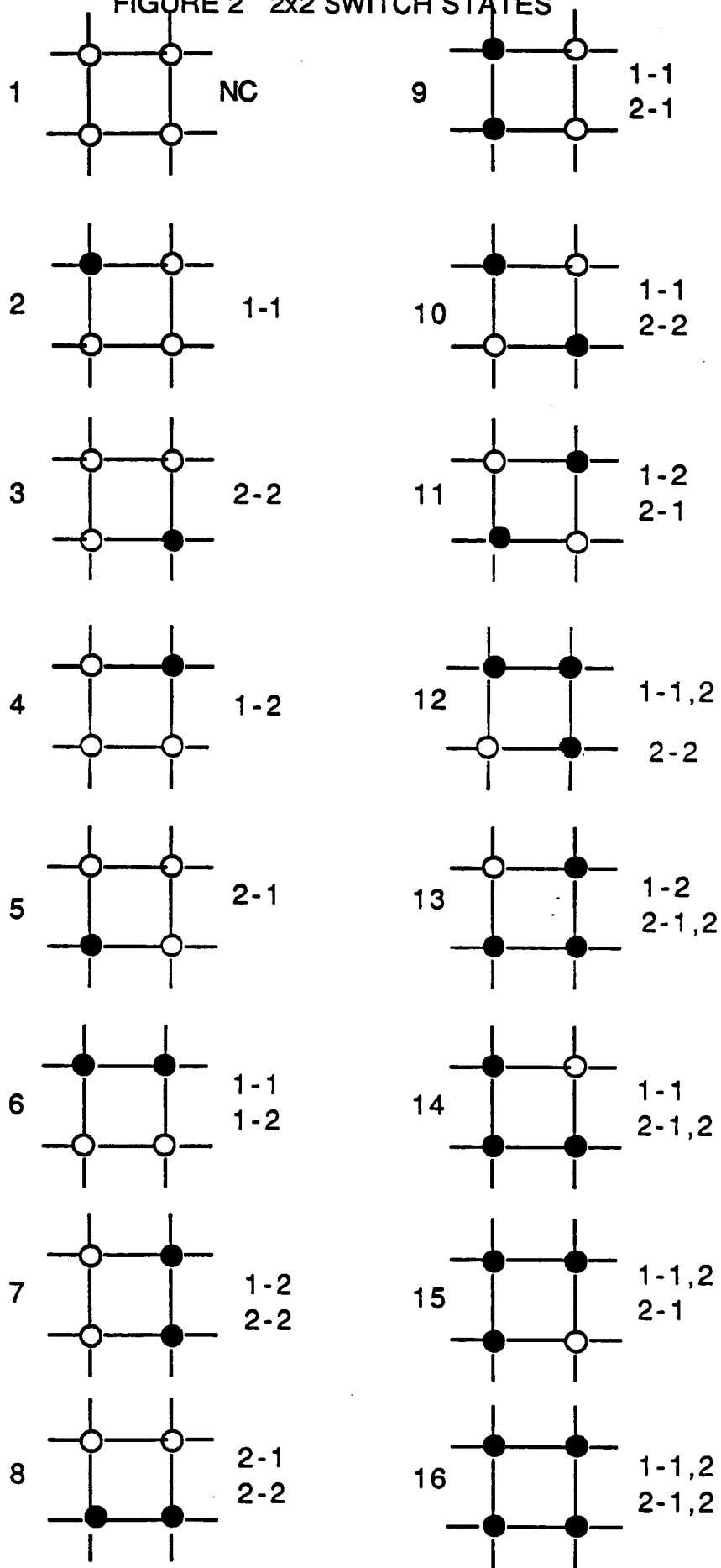


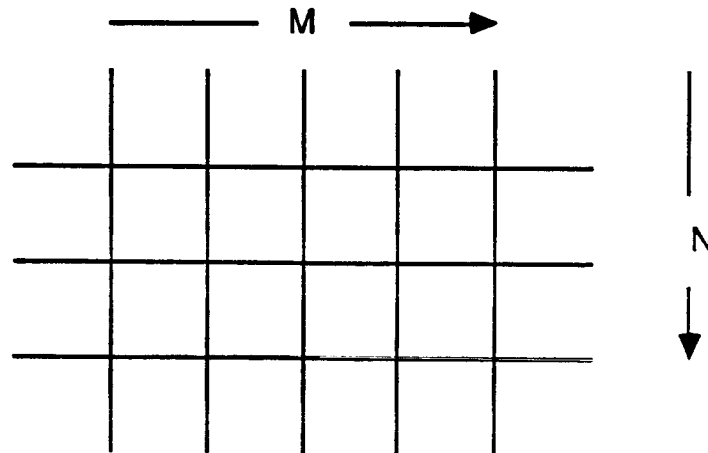
FIGURE 2 2x2 SWITCH STATES



APPENDIX 2

NUMBER OF POSSIBLE SWITCH STATES FOR MxN SWITCH

For a switch having M input lines and N output lines, there are MN possible single connections between the input and output lines. If only



M x N SWITCH

single point states of the switch are counted, then there are obviously MN such states. If only double point connection states are of interest, then the number of such states is simply the number of ways that two items can be selected without permutations from a collection of MN items and this is given by the well known binomial relation,

$$\binom{MN}{2} = \frac{(MN)!}{((MN-2)!(2!)}$$

If k-tuples of connections are made for each switch state then the number of states possible is the number of ways that k items can be selected at a time from a collection of MN items which is the binomial coefficient.

$$\binom{MN}{k} = \frac{(MN)!}{((MN-k)!(k!)}$$

The total number of states of all types is the summation on the index k over all possible values of k. Hence,

$$\text{TOTAL NUMBER OF STATES} = \sum_{k=1}^{k=MN} \binom{MN}{k} = 2^{MN}$$

This result shows that the number of switch states increases exponentially with the product MN. Thus for a 2x2 switch there are 16 possible switch states, for 3x3 there are 256, for 4x4 there are 65536, etc. If each is to be addressed it will take a code of MN bits.

Report Documentation Page

1. Report No. CR180817		2. Government Accession No.		3. Recipient's Catalog No.	
4. Title and Subtitle On-Board Processing Satellite Network Architecture and Control Study				5. Report Date June 1987	
				6. Performing Organization Code 650-20-26	
7. Author(s) S. Joseph Campanella B. Pontano H. Chalmers				8. Performing Organization Report No.	
				10. Work Unit No.	
9. Performing Organization Name and Address COMSAT 22300 Comsat Drive Clarksburg, MD 20871				11. Contract or Grant No. NAS3-24886	
				13. Type of Report and Period Covered	
12. Sponsoring Agency Name and Address NASA-LEWIS Research Center 21000 Brookpark Road Cleveland, OH 44135				14. Sponsoring Agency Code	
15. Supplementary Notes					
16. Abstract see attached					
17. Key Words (Suggested by Author(s))				18. Distribution Statement General Release	
19. Security Classif. (of this report) unclassified		20. Security Classif. (of this page)		21. No of pages	
				22. Price*	